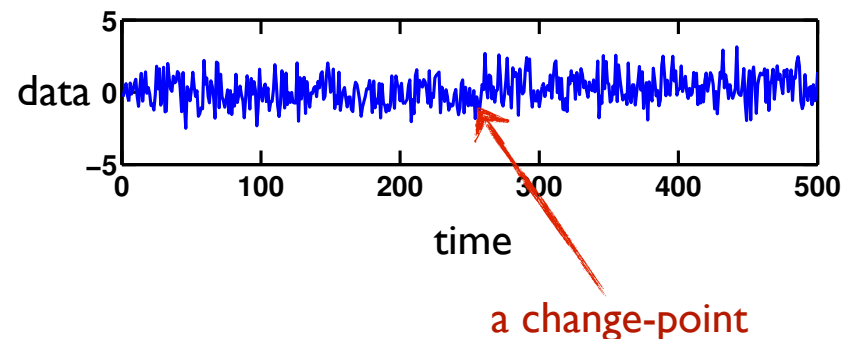


Change-point detection

“... to detect abrupt changes in the statistical behavior of an observed signal or time series.”

*–Quickest detection
by Poor and Hadjiliadis, 2008*

- ▶ change-point represents an **interesting event** or **anomaly**
seismic event, solar flare, human activity
- ▶ wish to detect change-point **online**



A brief history of change-point detection

Single-sensor

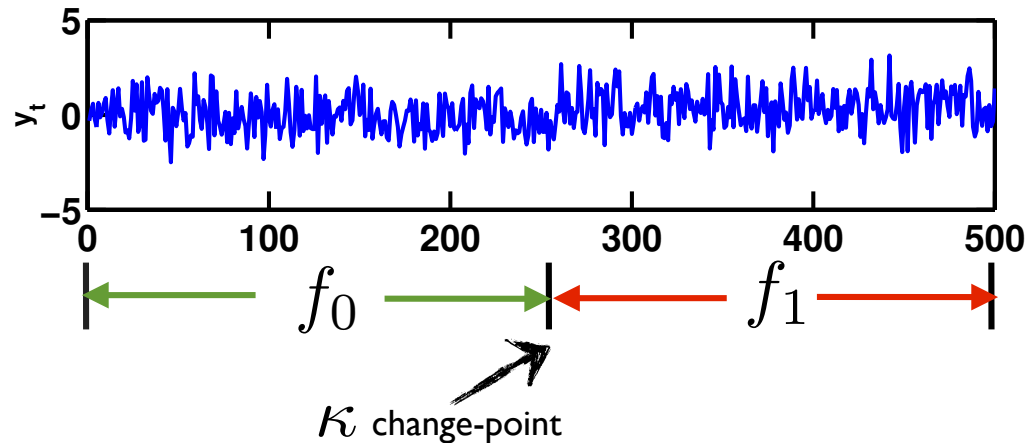
Multi-sensor



Single-sensor change-point detection

Classic “change-point” detection in statistics and quality-control

- ▶ a sequence of i.i.d. observations $y_1, y_2, \dots \in \mathbb{R}$



- ▶ sequential hypothesis testing

$$H_0 : y_t \sim f_0, \quad t = 1, 2, \dots$$

$$H_1 : y_t \sim f_0, \quad t = 1, \dots, \kappa,$$
$$y_t \sim f_1, \quad t = \kappa + 1, \dots$$

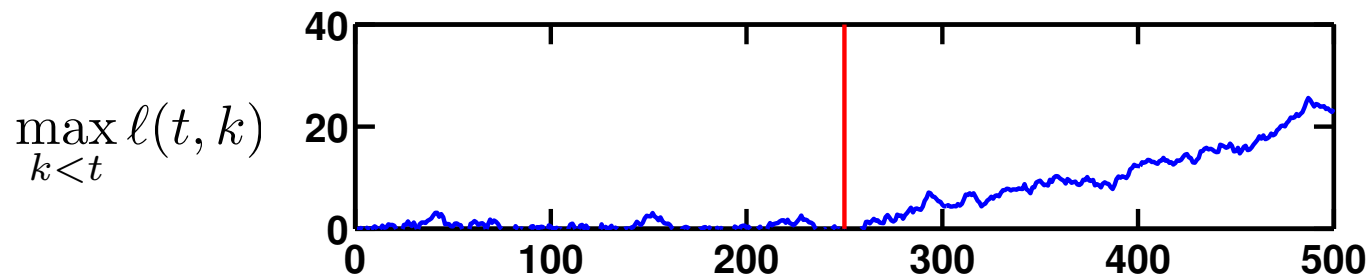
unknown change-point $\kappa > 0$

- ▶ **goal:** detect change-point as quickly as possible

Single-sensor likelihood procedure

- ▶ for a hypothesized $\kappa = k$:

$$\ell(t, k) = \log \frac{\prod_{i=1}^k f_0(y_i) \cdot \prod_{i=k+1}^t f_1(y_i)}{\prod_{i=1}^t f_0(y_i)} = \sum_{i=k+1}^t \log \frac{f_1(y_i)}{f_0(y_i)}$$



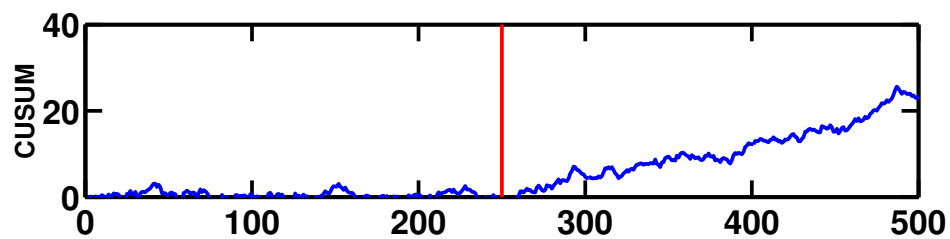
- ▶ stop the first time hitting a threshold b

$$T = \inf\{t : \max_{k < t} \ell(t, k) \geq b\}$$

Gaussian case

- ▶ $f_0 = \mathcal{N}(0, 1)$, $f_1 = \mathcal{N}(\mu, 1)$, $\mu > 0$

CUSUM procedure [P54]: $T = \inf\{t : \max_{k < t} \sum_{i=k+1}^t (\mu y_i - \frac{\mu^2}{2}) \geq b\}$



- ▶ when μ **unknown**, replace it with maximum likelihood estimator

GLR procedure [SV86]: $T = \inf\{t : \max_{k < t} \frac{(\sum_{i=k+1}^t y_i)^2}{t - k} \geq b\}$

