

MIDTERM II SOLUTIONS

Problem 1:

One way to prove this result is as follows: Consider the time points t_1, t_2, t_3 and t_4 with $t_1 < t_2 < t_3 < t_4$.

Then, the intervals (t_1, t_2) and (t_3, t_4) are non-overlapping, and we have:

$$\begin{aligned}
 & P[N(t_4) - N(t_3) = x \mid N(t_2) - N(t_1) = y] = \\
 &= \sum_{z=0}^{\infty} P[N(t_4) - N(t_3) = x \mid N(t_3) - N(t_2) = z \wedge N(t_2) - N(t_1) = y] \cdot \\
 & \quad \cdot P[N(t_3) - N(t_2) = z \mid N(t_2) - N(t_1) = y] = \\
 &= \sum_{z=0}^{\infty} \frac{P[N(t_4) - N(t_3) = x \wedge N(t_3) - N(t_2) = z \wedge N(t_2) - N(t_1) = y]}{P[N(t_3) - N(t_2) = z \wedge N(t_2) - N(t_1) = y]} \cdot \\
 & \quad \cdot \frac{P[N(t_3) - N(t_2) = z \wedge N(t_2) - N(t_1) = y]}{P[N(t_2) - N(t_1) = y]} = \text{(from memoryless property of the exp. dist.)} \\
 &= \sum_{z=0}^{\infty} \frac{P[N(t_4) - N(t_3) = x] \cdot P[N(t_3) - N(t_2) = z] \cdot P[N(t_2) - N(t_1) = y]}{P[N(t_2) - N(t_1) = y]} = \\
 &= P[N(t_4) - N(t_3) = x] \cdot \sum_{z=0}^{\infty} P[N(t_3) - N(t_2) = z] = \\
 &= P[N(t_4) - N(t_3) = x]
 \end{aligned}$$

Problem 2:

Let O_{ij} denote the number of people who got in the elevator at floor i and got off at floor j . Then,

$$\begin{aligned}
 P[O_{ij} = n] &= \sum_{k=0}^{\infty} P[O_{ij} = n \mid N_i = k] P[N_i = k] = \\
 &= \sum_{k=n}^{\infty} \binom{k}{n} p_{ij}^n (1-p_{ij})^{k-n} e^{-\lambda_i} \frac{\lambda_i^k}{k!} = \\
 &= \sum_{k=n}^{\infty} \frac{k!}{n! (k-n)!} p_{ij}^n (1-p_{ij})^{k-n} \frac{e^{-\lambda_i} \lambda_i^k}{k!} = \\
 &= \sum_{k=n}^{\infty} \left[\frac{(\lambda_i p_{ij})^n}{n!} e^{-\lambda_i p_{ij}} \right] \left[\frac{(\lambda_i (1-p_{ij}))^{k-n}}{(k-n)!} e^{-\lambda_i (1-p_{ij})} \right] = \\
 &= \frac{(\lambda_i p_{ij})^n}{n!} e^{-\lambda_i p_{ij}} \sum_{u=0}^{\infty} \frac{(\lambda_i (1-p_{ij}))^u}{u!} e^{-\lambda_i (1-p_{ij})} = (*) \\
 &= \frac{(\lambda_i p_{ij})^n}{n!} e^{-\lambda_i p_{ij}} \Rightarrow O_{ij} \sim \text{Poisson}(\lambda_i p_{ij})
 \end{aligned}$$

Furthermore, $O_j = \sum_{i \neq j} O_{ij}$ where the O_{ij} involved are Poisson distributed and mutually independent. In addition, the moment generating function of each O_{ij} is

$$M.G.F(O_{ij}) = E[\exp(O_{ij}t)] = e^{\lambda_i p_{ij}(e^t - 1)}$$

where the last part results from the fact that $O_{ij} \sim \text{Poisson}(\lambda_i p_{ij})$

Also,

$$\begin{aligned}
 M.G.F(O_j) &= E[\exp(O_j t)] = E\left[\exp\left(t \sum_{i \neq j} O_{ij}\right)\right] \stackrel{\text{from independence of } O_{ij}}{=} \\
 &= \prod_{i \neq j} E[\exp(O_{ij} t)] = \prod_{i \neq j} e^{\lambda_i p_{ij}(e^t - 1)}
 \end{aligned}$$

$$= e^{(\sum_{i,j} \lambda_i p_{ij}) (e^t - 1)} \Rightarrow O_j \sim \text{Poisson}(\sum_{i,j} \lambda_i p_{ij})$$

Furthermore, the above result implies that $E[O_j] = \sum_{i,j} \lambda_i p_{ij}$.

Finally, the computation of the pmf of O_j implies that this r.v. is independent from the number of passengers that enter the elevator at floor i and get off at some floor other than j (see the part highlighted by (*) in the corresponding computation above).

This result further implies that O_j and O_k are independent r.v.'s for $j \neq k$. But then

$$\begin{aligned} P(O_j = n \wedge O_k = m) &= P(O_j = n) \cdot P(O_k = m) = \\ &= \left[e^{-\sum_{i,j} \lambda_i p_{ij}} \frac{(\sum_{i,j} \lambda_i p_{ij})^n}{n!} \right] \left[e^{-\sum_{i,k} \lambda_i p_{ik}} \frac{(\sum_{i,k} \lambda_i p_{ik})^m}{m!} \right] \end{aligned}$$

In addition, a computation similar to that provided above for O_j , will establish that $O_j + O_k \sim \text{Poisson}(\sum_{i,j} \lambda_i p_{ij} + \sum_{i,k} \lambda_i p_{ik})$

Problem 3:

(i) With the initial positioning of the balls and the dynamics of their motion that are provided in the problem description, it is not hard to see that at any time point the relative positioning of the balls will be described by the following three states:

- (a) 111: The three balls occupy three consecutive positions.
 (b) 12: one ball is in the leftmost occupied position and the other two balls are one position to the right of it.
 21: two balls are in the leftmost occupied position and one ball is in the position to the right of them.

Furthermore, this state evolves according to the following one-step transition prob. matrix:

$$P = \begin{matrix} & \begin{matrix} 111 & 12 & 21 \end{matrix} \\ \begin{matrix} 111 \\ 12 \\ 21 \end{matrix} & \begin{bmatrix} 0.5 & 0.5 & 0 \\ 0 & 0 & 1 \\ 0.5 & 0.5 & 0 \end{bmatrix} \end{matrix}$$

(ii) The DTMC defined in step (i) is finite-state and irreducible; therefore it has an equilibrium distribution that is computed as follows:

$$\underline{\pi} = (\pi_{111} \ \pi_{12} \ \pi_{21}) = (\pi_{111} \ \pi_{12} \ \pi_{21}) \cdot P \quad ; \quad \sum_{x \in \{111, 12, 21\}} \pi_x = 1$$

The solution of the above system of equations will result in

$$\underline{\pi} = (1/3, 1/3, 1/3).$$

It can also be checked that the considered MC is aperiodic (notice, for instance, the self-loop at state 111) and therefore, the ~~considered~~^{computed} distribution also constitutes the limiting dist. for this MC.

(iii) After each visit at the states 111 and 12, the leftmost position of the ball configuration advances one position to the right. On the other hand, a visit to state 21 does not advance the leftmost position of the ball configuration. Thus the average speed of the balls' drift to the right is:

$$\frac{2}{3} \cdot 1 + \frac{1}{3} \cdot 0 = \frac{2}{3} \text{ slots per time period.}$$

(iv) This part of the problem description implies that the ball-advancing events follow a Poisson distribution with rate $\lambda = 1.0$. Using the same state space as in the previous parts, we can model the dynamics of the ball motion as a CTMC with infinitesimal generator matrix

$$Q = \begin{matrix} & \begin{matrix} 111 & 12 & 21 \end{matrix} \\ \begin{matrix} 111 \\ 12 \\ 21 \end{matrix} & \begin{bmatrix} -0.5 & 0.5 & 0 \\ 0 & -1 & 1 \\ 0.5 & 0.5 & -1 \end{bmatrix} \end{matrix}$$

The limiting distribution for this CTMC is obtained by

$$\underbrace{(P_{111} \ P_{12} \ P_{21})}_{\underline{P}} Q = \underline{0} ; \quad \underline{P} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = 1$$

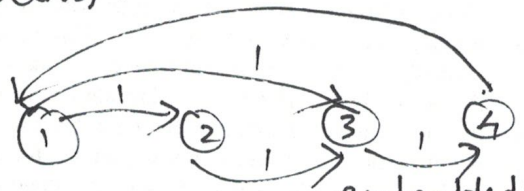
The solution of the above system is still $\underline{P} = (1/3, 1/3, 1/3)$

(Remark: This should be expected since all three states of this CTMC have a uniform departure rate $\lambda = 1$; then the above result is a demonstration of the corresponding result that we established for uniformized CTMCs).

Finally, the average ~~drift~~ speed for the ball drift can be computed equal to $2/3$ slots per time unit, in a way similar to that followed in part (iii).

Problem 4:

a) The state transition diagram (STD) for the CTMC is as follows:



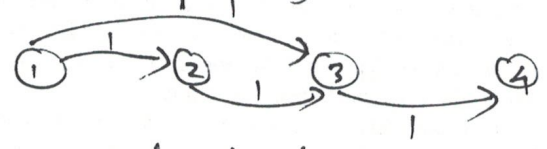
It is clear that this process is irreducible and positive recurrent (since it is also finite state). Therefore the CTMC has a limiting distribution obtained as follows:

$$(p_1, p_2, p_3, p_4) \begin{bmatrix} -2 & 1 & 1 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & -1 & 1 \\ 1 & 0 & 0 & -1 \end{bmatrix}; \quad \sum_{i=1}^4 p_i = 1 \rightarrow$$

$$\Rightarrow (p_1, p_2, p_3, p_4) = (1/6, 1/6, 1/3, 1/3)$$

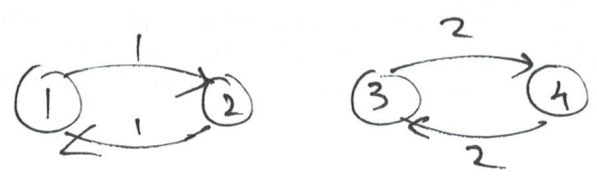
Hence $\lim_{t \rightarrow \infty} P(X_t = 2 | X_0 = 1) = p_2 = 1/6$.

b) The corresponding STD is



Hence state 4 is the unique absorbing state for this process and the long-run probability is equal to 1.

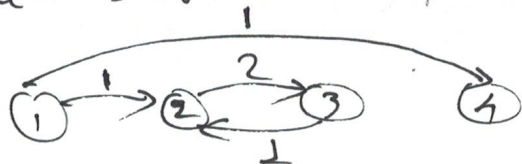
c) In this case, the STD is:



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Hence, if the process is started at state $X_0 = 1$, it is trapped in the subspace that is defined by states 1 and 2. The underlying DTMC is irreducible and therefore the considered continuous-time MC over these two states has a limiting distribution. Furthermore, from symmetry, it can be seen that the corresponding state probabilities are $1/2$. This is also the value for $\lim_{t \rightarrow \infty} P(X_t = 2 | X_0 = 1)$.

d) The STP is:



Starting from state 1, the considered process will be absorbed either in state 4 or the irreducible subspace defined by states 2 and 3. Furthermore, it is easy to see that the corresponding absorption probabilities are equal to $1/2$.

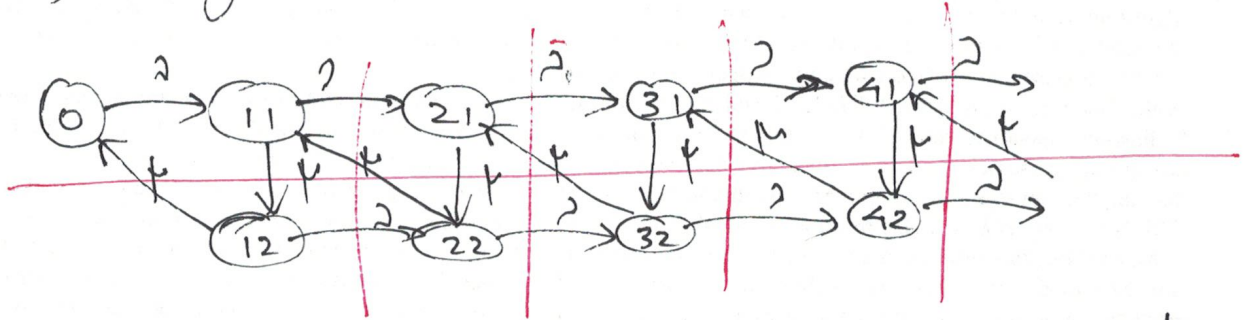
In the subspace of states 2 and 3, the process has the limiting distribution $(p_2 \ p_3) \begin{bmatrix} -2 & 2 \\ 1 & -1 \end{bmatrix} = 0$; $p_2 + p_3 = 1 \Rightarrow$
 $\Rightarrow (p_2 \ p_3) = (1/3, 2/3)$

Finally $\lim_{t \rightarrow \infty} P(X_t = 2 | X_0 = 1) = 1/2 \cdot 1/3 = 1/6$

Problem 5:

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- (i) The CTMC modeling the dynamics of the considered queueing station can be represented completely by the following STD:



The states (i, j) in the above STD with $i = 1, 2, \dots$ and $j \in \{1, 2\}$ should be understood as follows:

- i reports the # of customers in the station.
- j reports the stage of the customer in service.

- (ii) First, we show the necessity of the condition $2/\mu < 1/2$ for the existence of a limiting distribution for this CTMC. Consider the horizontal "cut" and the vertical "cuts" annotated by red lines in the above STD. If there exists a limiting distribution, then the flow between the two parts of the STD that are defined by each cut must be equal in both directions. Hence, from the horizontal cut we get:

$$\mu \sum_{i=1}^{\infty} \pi_{i1} = \mu \sum_{i=1}^{\infty} \pi_{i2} \Rightarrow \sum_{i=1}^{\infty} \pi_{i1} = \sum_{i=1}^{\infty} \pi_{i2} \quad (1)$$

Also, from the vertical cuts we have:

$$\forall i \geq 1, (\pi_{i1} + \pi_{i2}) \lambda = \pi_{(i+1)2} \mu \quad (2)$$

(9)

Summing the last set of equations over all i , we get:

$$\lambda \sum_{i=1}^{\infty} (\pi_{i1} + \pi_{i2}) = \mu \sum_{i=1}^{\infty} \pi_{(i+1)2} \quad (3)$$

From (1) and (3):

$$2\lambda \sum_{i=1}^{\infty} \pi_{i2} = \mu \sum_{i=1}^{\infty} \pi_{(i+1)2} = \mu \left[\sum_{i=1}^{\infty} \pi_{i2} - \pi_{12} \right] < \mu \sum_{i=1}^{\infty} \pi_{i2}$$

$$\Rightarrow 2\lambda < \mu \Rightarrow \lambda/\mu < 1/2$$

In the above derivation, we have used the fact that $0 < \sum_{i=1}^{\infty} \pi_{i2} < \infty$ if there exists a limiting distribution.

(Remark: Also, let me add that in the above discussion π denotes the limiting distribution for the CTMC, not the embedded PTMC.)

In order to show the sufficiency of the considered condition

$\lambda/\mu < 1/2$ for the existence of the limiting distribution, we shall show that under this condition, Equations (1) and (2) above define completely the sought distribution. More specifically, as shown above, Eqs (1) and (2) further imply that

$$\sum_{i=1}^{\infty} (2\lambda \pi_{i2} - \mu \pi_{(i+1)2}) = 0 \quad (4)$$

This equation can be satisfied by setting

$$\forall i \geq 1, \quad 2\lambda \pi_{i2} = \mu \pi_{(i+1)2} \Rightarrow \pi_{(i+1)2} = \frac{2\lambda}{\mu} \pi_{i2} \quad (5)$$

Equation (5) further implies that

$$\forall i \geq 1, \quad \pi_{i2} = \left(\frac{2\lambda}{\mu}\right)^{i-1} \pi_{12} \quad (6)$$

Hence, $\sum_{i=1}^{\infty} \pi_{i2} = \sum_{i=1}^{\infty} \left(\frac{2\lambda}{\mu}\right)^{i-1} \pi_{12} = \pi_{12} \sum_{i=1}^{\infty} \left(\frac{2\lambda}{\mu}\right)^{i-1} =$

$$= \pi_{12} \frac{1}{1 - \frac{2\lambda}{\mu}} = \pi_{12} \frac{\mu}{\mu - 2\lambda} \quad (7)$$

In the above computation we have used the working assumption $\lambda/\mu < 1/2 \Rightarrow \frac{2\lambda}{\mu} < 1$, and the results for the convergence of a geometric series.

Eqs (1) and (7) subsequently imply that:

$$1 = \pi_0 + \sum_{i=1}^{\infty} \pi_{i1} + \sum_{i=1}^{\infty} \pi_{i2} = \pi_0 + 2 \sum_{i=1}^{\infty} \pi_{i2} = \pi_0 + \frac{2\mu}{\mu - 2\lambda} \pi_{12} \quad (8)$$

Furthermore, from the flow-balance equation at state 0, we have:

$$\pi_0 \lambda = \pi_{12} \mu \Rightarrow \pi_{12} = \lambda/\mu \pi_0 \quad (9)$$

From (8) and (9):

$$\pi_0 \left(1 + \frac{2\lambda}{\mu - 2\lambda} \frac{\lambda}{\mu} \right) = 1 \Rightarrow \pi_0 = \frac{\mu - 2\lambda}{\mu - 2\lambda + 2\lambda} = 1 - \frac{2\lambda}{\mu} \quad (10)$$

Then, Eqs (6), (9) and (10) also imply that:

$$\forall i \geq 1, \quad \pi_{i2} = \left(\frac{2\lambda}{\mu}\right)^{i-1} \frac{\lambda}{\mu} \left(1 - \frac{2\lambda}{\mu} \right) \quad (11)$$

The computation of the π_{i1} , $i=1,2,\dots$ can be performed from the already obtained results using the flow balance equation for each state $i1$, $i=1,2,\dots$

Hence, for $i=1$, we have

$$(2+\mu)\pi_{11} = 2\pi_{10} + \mu\pi_{22} \Rightarrow \pi_{11} = \frac{2}{2+\mu}\pi_{10} + \frac{\mu}{2+\mu}\pi_{22}$$

For $i=2$,

$$(2+\mu)\pi_{21} = 2\pi_{11} + \mu\pi_{32} \Rightarrow \pi_{21} = \frac{2}{2+\mu}\pi_{11} + \frac{\mu}{2+\mu}\pi_{32}$$

~~etc.~~ More generally, for $i \geq 2$:

$$(2+\mu)\pi_{i1} = 2\pi_{(i-1)1} + \mu\pi_{(i+1)2} \Rightarrow \pi_{i1} = \frac{2}{2+\mu}\pi_{(i-1)1} + \frac{\mu}{2+\mu}\pi_{(i+1)2}$$

It is interesting to notice that each π_{i1} , $i=1,2,\dots$ is obtained as the weighted sum of two already computed probabilities, and therefore it does belong in the interval $(0,1)$.

Also, for verification purposes, notice that the summation of the above equations gives

$$(2+\mu)\sum_{i=1}^{\infty}\pi_{i1} = 2\pi_{10} + 2\sum_{i=1}^{\infty}\pi_{i1} + \mu\sum_{i=2}^{\infty}\pi_{i2} \Rightarrow$$

$$\begin{aligned} \Rightarrow \mu\sum_{i=2}^{\infty}\pi_{i1} &= 2\pi_{10} + \mu\sum_{i=2}^{\infty}\pi_{i2} \stackrel{(9)}{=} 2\frac{\mu}{2}\pi_{12} + \mu\sum_{i=2}^{\infty}\pi_{i2} = \\ &= \mu\sum_{i=1}^{\infty}\pi_{i2}, \text{ which is consistent with (1).} \end{aligned}$$

Finally, also notice that $2\lambda/\mu = 2(\lambda/\mu)$ is the average workload arriving at this station per time unit. And since the station has a single nonpreempting and nonidling server, it is reasonable to expect that the stability condition for this station is

$$2\lambda/\mu < 1 \quad (\Leftrightarrow) \quad \lambda/\mu < 1/2.$$

This insight also explains the result $\pi_0 = 1 - 2\lambda/\mu$, since state $\emptyset$ is the only state in which the server is idle.