

Online Supplement to “Reducing the Conservativeness of Fully Sequential Indifference-Zone Procedures”

Huizhu Wang
Seong-Hee Kim

H. Milton Stewart School of Industrial and Systems Engineering
Georgia Institute of Technology
Atlanta, GA 30332-0205 U.S.A.

August 24, 2012

1 Validity Proofs of Procedures for Known Variances

Two lemmas are needed to prove the validity of a number of procedures presented in the paper.

Lemma 1 *Jennison et al. [1982]* Suppose that a continuation region $H(t)$ is $(-h(t), h(t))$ given by a non-negative function $h(t), t \geq 0$. Consider two processes: a continuous process $\{\mathcal{W}(t, \Delta), t \geq 0\}$ with $\Delta > 0$, and a discrete process obtained by observing $\mathcal{W}(t, \Delta)$ at a random, increasing sequence of times $\{t_i : i = 1, 2, \dots\}$ taking values in a given countable set. Let $T_C = \inf\{t : \mathcal{W}(t, \Delta) \notin H(t)\}$ and $T_D = \inf\{t_i : \mathcal{W}(t_i, \Delta) \notin H(t_i)\}$, and assume that $T_D < \infty$ almost surely. Note that $T_D \geq T_C$. The error probabilities are

$$\Pr\{\mathcal{E}_C\} \equiv \Pr\{\mathcal{W}(T_C, \Delta) \leq -h(T_C)\} = \Pr\{\mathcal{W}(T_C, \Delta) < 0\},$$

$$\Pr\{\mathcal{E}_D\} \equiv \Pr\{\mathcal{W}(T_D, \Delta) \leq -h(T_D)\} = \Pr\{\mathcal{W}(T_D, \Delta) < 0\}.$$

Consider an outcome $\{(b(t); t \geq 0), \{t_i\}\}$, where $b(t)$ is the path of a Brownian motion. Assume that the conditional distribution of $\{t_i\}$ given $\mathcal{W}(t, \Delta) = b(t), t \geq 0$, is the same as the conditional distribution of $\{t_i\}$ given $\mathcal{W}(t, \Delta) = -b(t), t \geq 0$. Under these conditions,

$$\Pr\{\mathcal{E}_D\} \leq \Pr\{\mathcal{E}_C\}.$$

Lemma 2 *Fabian [1974]* Consider a standard Brownian motion process with drift $\mathcal{W}(t, \Delta)$ with $\Delta > 0$ and $t \geq 0$. Let $h(t) = a - \gamma t$ for some $a > 0$ and $\gamma \geq 0$. Let $H(t)$ denote the interval $(-h(t), h(t))$ (so that $H(t) = \emptyset$ when $-h(t) \geq h(t)$), and let $T = \inf\{t : \mathcal{W}(t, \Delta) \notin H(t)\}$ be the first time $\mathcal{W}(t, \Delta)$ does not fall in the triangular continuation region defined by $(H(t); t \geq 0)$. Finally, let \mathcal{E} be the event $\{\mathcal{W}(T, \Delta) \leq -h(T) \text{ and } H(T) \neq \emptyset, \text{ or } \mathcal{W}(T, \Delta) \leq 0 \text{ and } H(T) = \emptyset\}$. If $\gamma = \Delta/(2e)$ for any positive integer e , then

$$\Pr\{\mathcal{E}\} = \sum_{v=1}^e (-1)^{v+1} \left(1 - \frac{1}{2}\mathcal{I}(v=e)\right) \exp\{-2a\gamma(2e-v)v\}.$$

The proof of statistical validity of Procedure (\mathcal{P}) is as follows.

Let an incorrect selection (ICS) denote the event that the best system (system 1) is eliminated. This event implies that $\sum_{j=1}^r (X_{1j} - X_{ij})$ exits through the lower boundary of the continuation region.

$$\Pr\{\text{ICS}\} = \Pr \left\{ \sum_{j=1}^{T_i^d} (X_{1j} - X_{ij}) \leq -R(T_i^d; \delta, \eta, \sigma_{1i}^2) \text{ for some } i \neq 1 \right\} \quad (\text{S.1})$$

$$\stackrel{\text{BI}}{\leq} \sum_{i=2}^k \Pr \left\{ \sum_{j=1}^{T_i^d} (X_{1j} - X_{ij}) \leq -R(T_i^d; \delta, \eta, \sigma_{1i}^2) \right\} \quad (\text{S.2})$$

$$= \sum_{i=2}^k \Pr \left\{ \sum_{j=1}^{T_i^d} \left(\frac{X_{1j} - X_{ij}}{\sigma_{1i}} \right) \leq -\max \left\{ 0, \left(\frac{\eta\sigma_{1i}}{\delta} - \frac{\delta}{2e\sigma_{1i}} T_i^d \right) \right\} \right\} \\ \stackrel{\text{DTC}}{\leq} \sum_{i=2}^k \Pr \left\{ \mathcal{W} \left(T_i^c, \frac{\mu_1 - \mu_i}{\sigma_{1i}} \right) \leq -\max \left\{ 0, \left(\frac{\eta\sigma_{1i}}{\delta} - \frac{\delta}{2e\sigma_{1i}} T_i^c \right) \right\} \right\} \quad (\text{S.3})$$

$$\stackrel{\text{SC}}{\leq} \sum_{i=2}^k \Pr \left\{ \mathcal{W} \left(T_i^c; \frac{\delta}{\sigma_{1i}} \right) \leq -\max \left\{ 0, \left(\frac{\eta\sigma_{1i}}{\delta} - \frac{\delta}{2e\sigma_{1i}} T_i^c \right) \right\} \right\} \quad (\text{S.4})$$

$$= \sum_{i=2}^k \left[\sum_{v=1}^e (-1)^{v+1} \left(1 - \frac{1}{2} \mathcal{I}(v=e) \right) \exp \left\{ -\frac{\eta(2e-v)v}{e} \right\} \right] \quad (\text{S.5}) \\ = \sum_{i=2}^k g(\eta) = \alpha,$$

where the first inequality (S.2) is due to the BI; the second inequality (S.3) employs Lemma 1, denoted as DTC; the third inequality (S.4) holds because the smallest mean difference between the best system and any inferior system i is δ under the SC assumption; and Equation (S.5) is due to Lemma 2. Since we choose η such that $g(\eta) = \frac{\alpha}{k-1}$, the last equality holds.

Now consider Procedures (\mathcal{E}), (\mathcal{BI}) and ($\mathcal{BI} + \mathcal{DTC}$). Procedure (\mathcal{E}) uses the right-hand side (RHS) of Equation (S.1) to determine η , and one can see that Procedure (\mathcal{E}) is an exact procedure in the sense that it guarantees the actual PCS to be exactly equal to the nominal level. Procedure (\mathcal{BI}) employs the RHS of Inequality (S.2), therefore Procedure (\mathcal{BI}) is conservative due to the use of the BI. Unfortunately, there is no closed-form solution η for Procedures (\mathcal{E}) and (\mathcal{BI}), so we empirically search for η . Procedure ($\mathcal{BI} + \mathcal{DTC}$) uses the RHS of Inequality (S.3) to solve η , which implies that Procedure ($\mathcal{BI} + \mathcal{DTC}$) needs the BI and DTC for its validity proof. Note that Lemma 2 is applicable to Procedure ($\mathcal{BI} + \mathcal{DTC}$), which results in the same η as in Procedure (\mathcal{P}). Procedure (\mathcal{P}) is the most conservative procedure, because it employs all three conservativeness sources, and therefore it can also be considered as Procedure ($\mathcal{BI} + \mathcal{DTC} + \mathcal{SC}$).

2 Impacts of the BI, DTC, and the SC Assumption for Correlated Systems

Percentages of average additional number of observations for correlated systems with $\rho = 0.6$ are given in Figures S1 and S2.

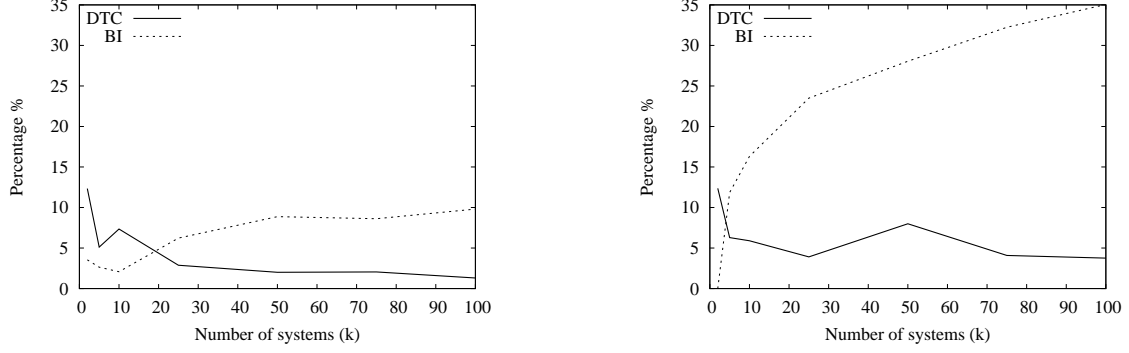


Figure S1: Percentages of average additional number of observations under the SC with INC (left) and DEC (right) variances when $\rho = 0.6$.

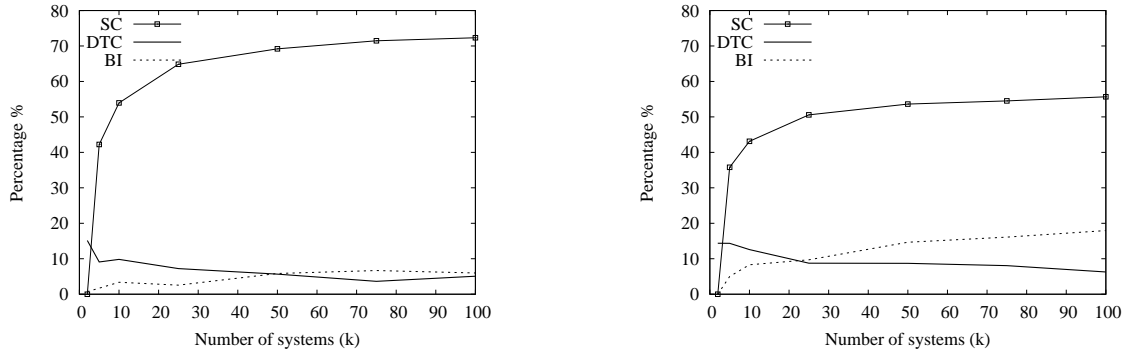


Figure S2: Percentages of average additional number of observations under the DC with INC (left) and DEC (right) variances when $\rho = 0.6$.

3 Derivation of Asymptotic Ratio \mathcal{S}

We employ a similar heuristic argument from Perng [1969] to approximate the number of observations for Procedures (\mathcal{P}) and ($\mathcal{BI} + \mathcal{DTC}$). The following happens for Procedures (\mathcal{P}) and ($\mathcal{BI} + \mathcal{DTC}$) as $\alpha \rightarrow 0$: (i) procedures stop making mistakes and system 1 is always found superior to other systems; and (ii) a larger number of observations is needed to make a decision, and hence sample mean $\bar{X}_i(r)$ behaves like the true mean μ_i for system i .

Let N_i^P and N_i^B be the number of observations that system i takes until a decision is reached in Procedures (\mathcal{P}) and ($\mathcal{BI} + \mathcal{DTC}$), respectively. For Procedure (\mathcal{P}), system i is eliminated when

$$\mu_1 - \mu_i \geq \frac{1}{r}R(r; \delta, \eta, \sigma_{1i}^2) = \frac{\eta\sigma_{1i}^2}{r\delta} - \frac{\delta}{2} \quad \text{and} \quad N_i^P \approx \frac{\eta\sigma_{1i}^2}{\delta(\mu_1 - \mu_i + \delta/2)}, \quad \text{for } i = 2, \dots, k.$$

System 1 keeps receiving additional observations until all inferior systems are eliminated and thus takes

$$N_1^P = \max(N_2^P, \dots, N_k^P).$$

Similarly, for Procedure ($\mathcal{BI} + \mathcal{DTC}$),

$$\mu_1 - \mu_i \geq \frac{1}{r}R(r; \delta_{1i}, \eta, \sigma_{1i}^2) = \frac{\eta\sigma_{1i}^2}{r\delta_{1i}} - \frac{\delta_{1i}}{2} \quad \text{and} \quad N_i^B \approx \frac{\eta\sigma_{1i}^2}{\delta_{1i}(\mu_1 - \mu_i + \delta_{1i}/2)}, \quad \text{for } i = 2, \dots, k.$$

Also let $N_1^B = \max(N_2^B, \dots, N_k^B)$.

Then, the asymptotic ratio of savings between the total number of observations for Procedures ($\mathcal{BI} + \mathcal{DTC}$) and (\mathcal{P}) is

$$\mathcal{S} \equiv 1 - \frac{\sum_{i=1}^k N_i^B}{\sum_{i=1}^k N_i^P} = 1 - \frac{\sum_{i=2}^k \frac{\eta\sigma_{1i}^2}{3(\mu_1 - \mu_i)^2/2} + \max_{i \in \{2, \dots, k\}} N_i^B}{\sum_{i=2}^k \frac{\eta\sigma_{1i}^2}{\delta(\mu_1 - \mu_i + \delta/2)} + \max_{i \in \{2, \dots, k\}} N_i^P}$$

The following table shows the asymptotic ratios \mathcal{S} and empirical ratios with $\alpha = 0.01$ after 500 macro replications when the mean configuration follows the DC and $\rho = 0$. The table demonstrates that our theoretical asymptotic ratios match well empirical ratios. The table shows that Procedure ($\mathcal{BI} + \mathcal{DTC}$) spends 23% to 41% fewer observations than Procedure (\mathcal{P}).

Variances	Ratio	$k = 5$	$k = 10$	$k = 25$	$k = 50$	$k = 75$	$k = 100$
INC	\mathcal{S}	0.277	0.345	0.391	0.406	0.412	0.415
	Empirical	0.273	0.334	0.375	0.393	0.396	0.406
Equal	\mathcal{S}	0.259	0.324	0.368	0.384	0.390	0.392
	Empirical	0.256	0.311	0.351	0.365	0.369	0.375
DEC	\mathcal{S}	0.247	0.310	0.354	0.370	0.375	0.384
	Empirical	0.233	0.276	0.319	0.323	0.327	0.378

4 Proof of Theorem 1

We need the following lemmas for the proof of Theorem 1.

Lemma 3 Define the standardized partial sum for system i as

$$C_i(t, r) \equiv \frac{\sum_{j=1}^{\lfloor rt \rfloor} X_{ij} - rt\mu_i}{\sigma_i \sqrt{r}}, \quad 0 \leq t \leq 1 \text{ and } r \in \mathbb{Z}^+, \quad (\text{S.6})$$

where $\lfloor \cdot \rfloor$ indicates truncation of any fractional part. The probability distribution of $C_i(t, r)$ over $D[0, 1]$, the space of functions that are right-continuous and have left-hand limits, converges to that of a standard Brownian motion process, $\mathcal{W}(t)$, as r increases; i.e., $C_i(\cdot, r) \Rightarrow \mathcal{W}(\cdot)$ as $r \rightarrow \infty$, where \Rightarrow denotes convergence in distribution. Further, we assume that for any $t \in [0, 1]$, the family of random variables $\{C_i^2(t, r) : r = 1, 2, \dots\}$ is uniformly integrable.

Lemma 3 is basically Functional Central Limit Theorem (Billingsley [1968]). It is straightforward that Lemma 3 holds under Assumption 1.

Lemma 4 If Assumptions 1, 2 and 3 hold, then there exists $N \in \mathbb{Z}^+$ such that $\delta \leq \hat{\delta}_{1i}(r) < (c_i + \kappa)\delta$ with probability 1 (w.p.1), for any $r > N$ and some $\kappa \in \mathbb{R}^+$.

Proof: Under Assumptions 1, 2 and 3, $|\bar{X}_1(r) - \bar{X}_i(r)| - A_{1i}(r) \rightarrow c_i\delta$ w.p.1 as $r \rightarrow \infty$ for $i \in \{2, \dots, k\}$. This follows by the strong law of large numbers and continuous mapping theorem (CMT, Billingsley [1968]). Set $\epsilon = \kappa\delta$ for some $\kappa \in \mathbb{R}^+$. Then there exists some $N \in \mathbb{Z}^+$, $(c_i - \kappa)\delta < |\bar{X}_1(r) - \bar{X}_i(r)| - A_{1i}(r) < (c_i + \kappa)\delta$ and therefore $\delta \leq \hat{\delta}_{1i}(r) < (c_i + \kappa)\delta$ for $r > N$ w.p.1. \square

Proof of Theorem 1:

Let

$$T_{1i} \equiv T_{1i}(\delta) = \min \left\{ r : r \in \{n_0, n_0 + 1, \dots\} \text{ and } \left| \sum_{j=1}^r (X_{1j} - X_{ij}) \right| \geq R(r; \hat{\delta}_{1i}(r), h^2, S_{1i}^2(n_0)) \right\}$$

and

$$N_{1i}(r) = \left\lfloor \frac{2eh^2 S_{1i}^2(n_0)}{\hat{\delta}_{1i}^2(r)} \right\rfloor.$$

First of all, we will show that $T_{1i} \rightarrow \infty$ as $\delta \rightarrow 0$ w.p.1, which is a fundamental requirement for the convergence of estimators. We first represent the output process $\{X_{1j} - X_{ij}\}$ as $\{Z_j + c_i \delta\}$, where $Z_j \stackrel{\text{i.i.d.}}{\sim} N(0, \sigma_{1i}^2)$, $i = 2, \dots, k$ and $j = 1, 2, \dots$. Consider a sample path going up for which $\limsup_{\delta \rightarrow 0} T_{1i} = T^* \leq \infty$. (When the path goes down, the proof is analogous.) There must exist $\delta^* > 0$ such that for all $\delta \leq \delta^*$,

$$\sum_{j=1}^{T^*} Z_j + T^* c_i \delta \geq \frac{h^2 S_{1i}^2(n_0)}{\hat{\delta}_{1i}(T^*)} - \frac{\hat{\delta}_{1i}(T^*)}{2e} T^*. \quad (\text{S.7})$$

By Lemma 4, there must exist some $\kappa \in \mathbb{R}^+$ and $n < T^*$ that ensure $\delta \leq \hat{\delta}_{1i}(r) < (c_i + \kappa)\delta$ for any $r > n$ w.p.1. This implies that $\delta \leq \hat{\delta}_{1i}(T^*) < (c_i + \kappa)\delta$ and we obtain

$$\sum_{j=1}^{T^*} Z_j + T^* c_i \delta \geq \frac{h^2 S_{1i}^2(n_0)}{(c_i + \kappa)\delta} - \frac{(c_i + \kappa)\delta}{2e} T^*. \quad (\text{S.8})$$

Equation (S.8) can be rewritten as follows:

$$\sum_{j=1}^{T^*} Z_j + T^* \delta \left(c_i + \frac{c_i + \kappa}{2e} \right) \geq \frac{h^2 S_{1i}^2(n_0)}{(c_i + \kappa)\delta}.$$

Note that when T^* is finite, $\sum_{j=1}^{T^*} Z_j$ is finite w.p.1, but $T^* \delta$ goes to zero while $\frac{h^2 S_{1i}^2(n_0)}{(c_i + \kappa)\delta}$ goes to infinity as $\delta \rightarrow 0$. Thus (S.7) occurs with probability zero and then $T_{1i} \rightarrow \infty$ w.p.1 as $\delta \rightarrow 0$.

This also ensures that as $\delta \rightarrow 0$,

$$\hat{\delta}_{1i}(T_{1i})/\delta_{1i} \rightarrow 1 \quad \text{w.p.1.} \quad (\text{S.9})$$

Due to (S.9) and CMT, it is also true that $N_{1i}(T_{1i}) \rightarrow \infty$ as $\delta \rightarrow 0$. Let ICS_i denote the event that the best system gets eliminated by an inferior system i , $i = 2, \dots, k$. Then

$$\begin{aligned} \Pr\{\text{ICS}_i\} &= \Pr \left\{ \sum_{j=1}^{T_{1i}} (X_{1j} - X_{ij}) \leq - \max \left\{ 0, \frac{h^2 S_{1i}^2(n_0)}{\hat{\delta}_{1i}(T_{1i})} - \frac{\hat{\delta}_{1i}(T_{1i})}{2e} T_{1i} \right\} \right\} \\ &= \Pr \left\{ \frac{\sum_{j=1}^{T_{1i}} (X_{1j} - X_{ij}) - \delta_{1i} T_{1i}}{\sigma_{1i} \sqrt{N_{1i}(T_{1i})} + 1} + \frac{\delta_{1i} T_{1i}}{\sigma_{1i} \sqrt{N_{1i}(T_{1i})} + 1} \leq \right. \\ &\quad \left. - \max \left\{ 0, \frac{h^2 S_{1i}^2(n_0)}{\hat{\delta}_{1i}(T_{1i}) \sigma_{1i} \sqrt{N_{1i}(T_{1i})} + 1} - \frac{\hat{\delta}_{1i}(T_{1i})}{2e \sigma_{1i} \sqrt{N_{1i}(T_{1i})} + 1} T_{1i} \right\} \right\} \quad (\text{S.10}) \end{aligned}$$

Let

$$C_{1i}(t, \delta) = \frac{\sum_{j=1}^{\lfloor (N_{1i}(T_{1i})+1)t \rfloor} (X_{1j} - X_{ij}) - (N_{1i}(T_{1i}) + 1)\delta_{1i}t}{\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}}$$

for $0 \leq t \leq 1$. Further, define

$$\begin{aligned} \widehat{T}_{1i} &= \min \left\{ t \in \left\{ \frac{n_0}{N_{1i}(T_{1i}) + 1}, \frac{n_0 + 1}{N_{1i}(T_{1i}) + 1}, \dots, 1 \right\} : \left| C_{1i}(t, \delta) + \frac{(N_{1i}(T_{1i}) + 1)\delta_{1i}t}{\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} \right| \right. \\ &\geq \left. \frac{h^2 S_{1i}^2(n_0)}{\widehat{\delta}_{1i}(T_{1i})\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} - \frac{\widehat{\delta}_{1i}(T_{1i})(N_{1i}(T_{1i}) + 1)}{2e\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} t \right\}. \end{aligned}$$

Clearly, $\widehat{T}_{1i} = T_{1i}/(N_{1i}(T_{1i}) + 1)$. Also define the stopping time of the corresponding continuous-time process as

$$\begin{aligned} \widetilde{T}_{1i} &= \min \left\{ t \geq \frac{n_0}{N_{1i}(T_{1i}) + 1} : \left| C_{1i}(t, \delta) + \frac{(N_{1i}(T_{1i}) + 1)\delta_{1i}t}{\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} \right| \right. \\ &\geq \left. \frac{h^2 S_{1i}^2(n_0)}{\widehat{\delta}_{1i}(T_{1i})\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} - \frac{\widehat{\delta}_{1i}(T_{1i})(N_{1i}(T_{1i}) + 1)}{2e\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} t \right\}. \end{aligned}$$

Notice that for fixed δ , $C_{1i}(\widehat{T}_{1i}, \delta)$ corresponds to the right-hand limit of a point of discontinuity of $C_{1i}(\cdot, \delta)$. We can show that $\widehat{T}_{1i} \rightarrow \widetilde{T}_{1i}$ w.p.1 as $\delta \rightarrow 0$, making use of the fact that $1/(N_{1i}(T_{1i}) + 1) \rightarrow 0$ w.p.1. Thus, in the limit, we can focus on $C_{1i}(\widetilde{T}_{1i}, \delta)$.

Now condition on $S_{1i}^2(n_0)$. Then Lemma 3, (S.9) and CMT imply that

$$C_{1i}(t, \delta) + \frac{(N_{1i}(T_{1i}) + 1)\delta_{1i}t}{\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} \Rightarrow \mathcal{W}(t, \Delta)$$

as $\delta \rightarrow 0$, where

$$\Delta = \lim_{\delta \rightarrow 0} \frac{(N_{1i}(T_{1i}) + 1)\delta_{1i}}{\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} = \frac{\sqrt{2eh^2 S_{1i}^2(n_0)}}{\sigma_{1i}}.$$

Still conditional on $S_{1i}^2(n_0)$, let

$$\mathcal{A}(\delta) = \frac{h^2 S_{1i}^2(n_0)}{\widehat{\delta}_{1i}(T_{1i})\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} \xrightarrow{\delta \rightarrow 0} \frac{\sqrt{2eh^2 S_{1i}^2(n_0)}}{2e\sigma_{1i}} \equiv \mathcal{A}$$

$$\mathcal{B}(\delta) = \frac{\widehat{\delta}_{1i}(T_{1i})(N_{1i}(T_{1i}) + 1)}{2e\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} \xrightarrow{\delta \rightarrow 0} \frac{\sqrt{2eh^2 S_{1i}^2(n_0)}}{2e\sigma_{1i}} \equiv \mathcal{B}.$$

Notice that the stopping time \widetilde{T}_{1i} is the first time t at which the event

$$\left\{ \left| C_{1i}(t, \delta) + \frac{(N_{1i}(T_{1i}) + 1)\delta_{1i}t}{\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} \right| - \mathcal{A}(\delta) + \mathcal{B}(\delta)t \geq 0 \right\}$$

occurs. Define the mapping $s_\delta : D[0, 1] \rightarrow \mathbb{R}$ such that $s_\delta(Y) = Y(T_{Y,\delta})$ where

$$T_{Y,\delta} = \inf \{t : |Y(t)| - \mathcal{A}(\delta) + \mathcal{B}(\delta)t \geq 0\}$$

for every $Y \in D[0, 1]$ and $\delta > 0$. Similarly, define $s(Y) = Y(T_Y)$ where

$$T_Y = \inf \{t : |Y(t)| - \mathcal{A} + \mathcal{B}t \geq 0\}$$

for every $Y \in D[0, 1]$ and $\delta > 0$. Notice that

$$\begin{aligned} s_\delta \left(C_{1i}(t, \delta) + \frac{(N_{1i}(T_{1i}) + 1)\delta_{1i}t}{\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} \right) &= C_{1i}(\tilde{T}_{1i}, \delta) + \frac{(N_{1i}(T_{1i}) + 1)\delta_{1i}\tilde{T}_{1i}}{\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} \\ s(\mathcal{W}(\cdot, \Delta)) &= \mathcal{W}(T_{\mathcal{W}(\cdot, \Delta)}, \Delta). \end{aligned}$$

We need to show that

$$s_\delta(\mathcal{G}_{1i}(\cdot, \delta)) \Rightarrow s(\mathcal{W}(\cdot, \Delta)) \quad (\text{S.11})$$

as $\delta \rightarrow 0$, where

$$\mathcal{G}_{1i}(t, \delta) \equiv C_{1i}(t, \delta) + \frac{(N_{1i}(T_{1i}) + 1)\delta_{1i}t}{\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} \quad (\text{S.12})$$

for $t \in [0, 1]$ and $\delta > 0$. This follows Proposition 2 from Kim et al. [2005] which is established on the extended CMT (Billingsley [1968]).

Unconditioning on S_{1i}^2 , (S.11) gives

$$\begin{aligned} &\limsup_{\delta \rightarrow 0} \Pr\{\text{ICS}_i\} \\ &= \mathbb{E} \left[\Pr \{ \mathcal{W}(t, \Delta) \text{ exits continuation region through the lower boundary} | S_{1i}^2(n_0) \} \right] \\ &= \mathbb{E} \left[\sum_{v=1}^e (-1)^{v+1} \left(1 - \frac{1}{2} \mathcal{I}(v=e) \right) \exp \left\{ -\frac{h^2 S_{1i}^2(n_0)}{e \sigma_{1i}^2} (2e-v)v \right\} \middle| S_{1i}^2(n_0) \right] \quad (\text{S.13}) \end{aligned}$$

$$= \mathbb{E} \left[\sum_{v=1}^e (-1)^{v+1} \left(1 - \frac{1}{2} \mathcal{I}(v=e) \right) \exp \left\{ -\frac{\eta(n_0-1) S_{1i}^2(n_0)}{e \sigma_{1i}^2} (2e-v)v \right\} \middle| S_{1i}^2(n_0) \right] \quad (\text{S.14})$$

$$\begin{aligned} &= \sum_{v=1}^e (-1)^{v+1} \left(1 - \frac{1}{2} \mathcal{I}(v=e) \right) \mathbb{E} \left[\exp \left\{ -\frac{\eta \chi_{n_0-1}^2}{e} (2e-v)v \right\} \right] \\ &= \sum_{v=1}^e (-1)^{v+1} \left(1 - \frac{1}{2} \mathcal{I}(v=e) \right) \left(1 + \frac{2\eta(2e-v)v}{e} \right)^{-(n_0-1)/2} \quad (\text{S.15}) \\ &= \frac{\alpha}{k-1}, \end{aligned}$$

where (S.14) holds due to Lemma 2, χ_f^2 is a chi-squared random variable with degrees of freedom f , and (S.15) is from the moment generating function of χ_f^2 . Finally the probability of incorrect selection is less than the nominal level as below.

$$\limsup_{\delta \rightarrow 0} \Pr\{\text{ICS}\} \leq \limsup_{\delta \rightarrow 0} \sum_{i=2}^k \Pr\{\text{ICS}_i\} \leq \alpha.$$

□

5 Proof of Theorem 2

For the proof of $\mathcal{WK}++$ we need the following lemma:

Lemma 5 *Billingsley [1968]*

If $Y_n \Rightarrow Y$ and $Z_n \xrightarrow{P} a$ where a is a constant vector, then $(Y_n, Z_n) \Rightarrow (Y, a)$.

Proof of Theorem 2: First set T_{1i} and $N_{1i}(r)$ in the same way as the proof of Theorem 1, except replacing $S_{1i}^2(n_0)$ with $S_{1i}^2(r)$. Sample variance $S_{1i}^2(n_0)$ in (S.7) and (S.8) is also replaced with $S_{1i}^2(T^*)$. Then using a similar argument we can show $T_{1i} \rightarrow \infty$ as $\delta \rightarrow 0$ w.p.1 to guarantee the convergence of estimators. This ensures that as $\delta \rightarrow 0$,

$$\hat{\delta}_{1i}(T_{1i})/\delta_{1i} \rightarrow 1 \quad \text{and} \quad S_{1i}^2(T_{1i}) \rightarrow \sigma_{1i}^2, \quad \text{w.p.1.} \quad (\text{S.16})$$

Also, $N_{1i}(r) \rightarrow \infty$ as $\delta \rightarrow 0$ w.p.1 due to (S.16) and CMT. The definition of $C_{1i}(t, \delta)$ is the same as in the proof of Theorem 1. Redefine \hat{T}_{1i} and \tilde{T}_{1i} as follows:

$$\begin{aligned} \hat{T}_{1i} &= \min \left\{ t \in \left\{ \frac{n_0}{N_{1i}(T_{1i}) + 1}, \frac{n_0 + 1}{N_{1i}(T_{1i}) + 1}, \dots, 1 \right\} : \left| C_{1i}(t, \delta) + \frac{(N_{1i}(T_{1i}) + 1)\delta_{1i}t}{\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} \right| \right. \\ &\quad \left. \geq \frac{h^2 S_{1i}^2(T_{1i})}{\hat{\delta}_{1i}(T_{1i})\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} - \frac{\hat{\delta}_{1i}(T_{1i})(N_{1i}(T_{1i}) + 1)}{2e\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} t \right\}. \\ \tilde{T}_{1i} &= \min \left\{ t \geq \frac{n_0}{N_{1i}(T_{1i}) + 1} : \left| C_{1i}(t, \delta) + \frac{(N_{1i}(T_{1i}) + 1)\delta_{1i}t}{\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} \right| \right. \\ &\quad \left. \geq \frac{h^2 S_{1i}^2(T_{1i})}{\hat{\delta}_{1i}(T_{1i})\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} - \frac{\hat{\delta}_{1i}(T_{1i})(N_{1i}(T_{1i}) + 1)}{2e\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} t \right\}. \end{aligned}$$

We can show that $\hat{T}_{1i} \rightarrow \tilde{T}_{1i}$ w.p.1 as $\delta \rightarrow 0$ making use of the fact that $1/(N_{1i}(T_{1i}) + 1) \rightarrow 0$ w.p.1. Thus, in the limit, we can focus on $C_{1i}(\tilde{T}_{1i}, \delta)$.

Since strong consistency implies convergence in probability, (S.16) and Lemma 5 can be applied to $\left(C_{1i}(T_{1i}, \delta), \left[\frac{\hat{\delta}_{1i}(T_{1i})/\delta_{1i}}{S_{1i}^2(T_{1i})} \right] \right)$. By the random-change-of-time theorem (Billingsley [1968]), the followings hold.

$$C_{1i}(t, \delta) + \frac{(N_{1i}(T_{1i}) + 1)\delta_{1i}t}{\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} \Rightarrow \mathcal{W}(t, \Delta)$$

as $\delta \rightarrow 0$, where

$$\Delta = \lim_{\delta \rightarrow 0} \frac{(N_{1i}(T_{1i}) + 1)\delta_{1i}}{\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} = \sqrt{2eh^2}.$$

$$\begin{aligned} \mathcal{A}(\delta) &= \frac{h^2 S_{1i}^2(T_{1i})}{\hat{\delta}_{1i}(T_{1i})\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} \xrightarrow{\delta \rightarrow 0} \sqrt{\frac{h^2}{2e}} \equiv \mathcal{A} \\ \mathcal{B}(\delta) &= \frac{\hat{\delta}_{1i}(T_{1i})(N_{1i}(T_{1i}) + 1)}{2e\sigma_{1i}\sqrt{N_{1i}(T_{1i}) + 1}} \xrightarrow{\delta \rightarrow 0} \sqrt{\frac{h^2}{2e}} \equiv \mathcal{B} \end{aligned}$$

The definitions of mappings s_δ , s , $T_{Y,\delta}$, and T_Y follow those in the proof of Theorem 1 . Then (S.11) holds again. Therefore,

$$\begin{aligned} \limsup_{\delta \rightarrow 0} \Pr\{\text{ICS}_i\} &= \Pr\{\mathcal{W}(t, \Delta) \text{ exits continuation region through the lower boundary}\} \\ &= \sum_{v=1}^e (-1)^{v+1} \left(1 - \frac{1}{2} \mathcal{I}(v=e)\right) \exp\left\{-2 \frac{h^2}{2e} (2e-v)v\right\} \text{ (by Lemma 2)} \\ &= \sum_{v=1}^e (-1)^{v+1} \left(1 - \frac{1}{2} \mathcal{I}(v=e)\right) \exp\left\{-\frac{\eta}{e} (2e-v)v\right\} = \alpha/(k-1) \end{aligned} \quad (\text{S.17})$$

where the equality follows from the way we choose η . Finally,

$$\limsup_{\delta \rightarrow 0} \Pr\{\text{ICS}\} \leq \limsup_{\delta \rightarrow 0} \sum_{i=2}^k \Pr\{\text{ICS}_i\} \leq \alpha.$$

□

6 Estimated PCS for \mathcal{WK} and $\mathcal{WK}++$

Figure S3 shows estimated PCS for \mathcal{WK} and $\mathcal{WK}++$ when $\rho = 0$ and $\rho = 0.6$.

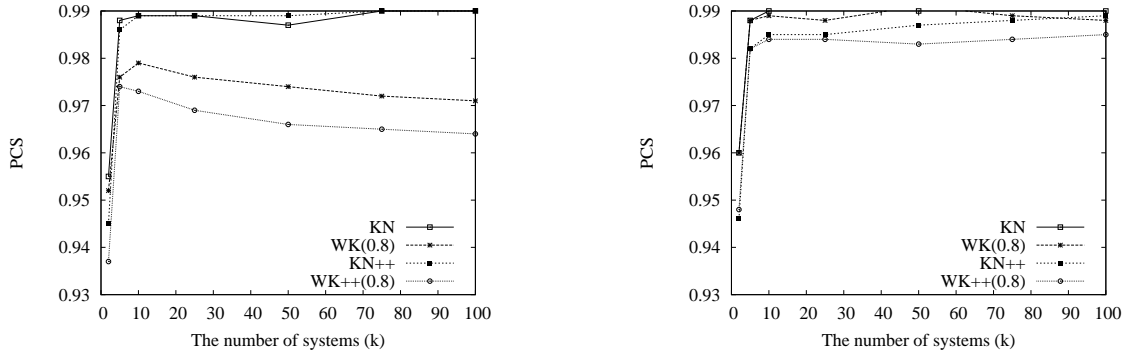


Figure S3: Estimated PCS under the DC-INC with $\rho = 0$ (left) and $\rho = 0.6$ (right).

References

- P. Billingsley. *Convergence of Probability Measures*. John Wiley & Sons, Inc., first edition, 1968.
- V. Fabian. Note on anderson's sequential procedures with triangular boundary. *Annals of Statistics*, 2:170–176, 1974.
- C. Jennison, I. M. Johnstone, and B. W. Turnbull. Asymptotically optimal procedures for sequential adaptive selection of the best of several normal means. In S. S. Gupta and J. O. Berger, editors, *Statistical Decision Theory and Related Topics, iii*, volume 2, pages 55–86. Academic Press, 1982.
- S.-H. Kim, B. L. Nelson, and J. R. Wilson. Some almost-sure convergence properties useful in sequential analysis. *Sequential Analysis*, 24:411–419, 2005.
- S. K. Perng. A comparison of the asymptotic expected sample sizes of two sequential procedures for ranking problem. *Annals of Mathematical Statistics*, 40:2198–2202, 1969.