# On obtaining the convex hull of quadratic inequalities via aggregations

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## 1 Introduction

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1.1 QCQP: Need for convexification

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## Quadratically Constrained Quadratic Program

## QCQP

Quadratic objective, quadratic constraints:

$$\begin{array}{ll} \max & x^{\top} Q_0 x + b_0^{\top} x \\ \text{s.t.} & x^{\top} Q_i x + b_i^{\top} x \leq d_i \ \forall i \in [m] \end{array}$$

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## Quadratically Constrained Quadratic Program

## QCQP

May be equivalently written as:

 $\begin{array}{ll} \max & c^{\top} x \\ \text{s.t.} & x^{\top} Q_i x + b_i^{\top} x \leq d_i \ \forall i \in [m] \end{array}$ 

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## Quadratically Constrained Quadratic Program

QCQP May be equivalently written as:

$$\begin{array}{ll} \max & c^{\top} x \\ \text{s.t.} & x^{\top} Q_i x + b_i^{\top} x \leq d_i \ \forall i \in [m] \end{array}$$

1. So, we care about finding:

$$\operatorname{conv}\left\{x \mid x^{\top} Q_i x + b_i^{\top} x \leq d_i \; \forall i \in [m]\right\}$$

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## Quadratically Constrained Quadratic Program

### QCQP May be equivalently written as:

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1. So, we care about finding:

$$\operatorname{conv}\left\{x \mid x^{\top} Q_i x + b_i^{\top} x \leq d_i \; \forall i \in [m]\right\}$$

2. This is challenging to compute! So we can consider convexification of relaxations (similar to integer programming)

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1.2 Two row relaxation

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## Two row relaxation

We can select two rows and try and find the convex hull of their interesection:

$$C2 = \left\{ x \in \mathbb{R}^n \mid x^\top Q_i x + b_i^\top x \le d_i \; \forall i \in [2] \right\}$$

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(For some technical reasons), let us consider the "open version" of the above set:

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$$\mathcal{O}2 = \left\{ x \in \mathbb{R}^n \mid x^\top Q_i x + b_i^\top x < d_i \; \forall i \in [2] \right\}$$

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## Two row relaxation

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$$\mathcal{O}2 = \left\{ x \in \mathbb{R}^n \mid x^\top Q_i x + b_i^\top x < d_i \; \forall i \in [2] \right\}$$

It turns out convex hull of O2 is well understood!

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## Lets first talk about aggregation

• Given  $\lambda \in \mathbb{R}^m_+$  and

$$\mathcal{S} := \left\{ x \mid x^\top Q_i x + b_i^\top x \blacklozenge d_i \ \forall i \in [m] 
ight\},$$
where  $\blacklozenge \in \{\leq, <\}.$ 

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## Lets first talk about aggregation

• Given  $\lambda \in \mathbb{R}_{+}^{m}$  and  $S := \left\{ x \mid x^{\top} Q_{i}x + b_{i}^{\top}x \blacklozenge d_{i} \forall i \in [m] \right\},$ where  $\blacklozenge \in \{\leq, <\}.$ Then:  $S^{\lambda} := \left\{ x \mid x^{\top} \left( \sum_{i=1}^{m} \lambda_{i} Q_{i} \right) x + \left( \sum_{i=1}^{m} \lambda_{i} b_{i} \right)^{\top} x \blacklozenge \left( \sum_{i=1}^{m} \lambda_{i} d_{i} \right) \forall i \in [m] \right\}$ is a relaxation of S.

Basically, we are multiplying *i<sup>th</sup>* constraint by λ<sub>i</sub> and then add them together.

Convex hull of O2

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 $\mathcal{O}2 = \left\{ x \in \mathbb{R}^n \mid x^\top Q_i x + b_i^\top x < d_i \; \forall i \in [2] \right\}$ 

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## Convex hull of O2

$$\mathcal{O}2 = \left\{ x \in \mathbb{R}^n \mid x^\top Q_i x + b_i^\top x < d_i \; \forall i \in [2] \right\}$$

## Theorem ([Yildiran (2009)])

Given a set O2, such that conv  $(O2) \neq \mathbb{R}^n$ , there exists  $\lambda^1, \lambda^2 \in \mathbb{R}^2_+$  such that:

$$\operatorname{conv}(\mathcal{O}2) = (\mathcal{O}2)^{\lambda^1} \cap (\mathcal{O}2)^{\lambda^2}$$
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## Convex hull of $\mathcal{O}2$

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- The paper [Yildiran (2009)] gives algorithm to compute  $\lambda_1$  and  $\lambda_2$ .
- The quadratic constraints (O2)<sup>λ<sup>i</sup></sup> i ∈ {1,2} has very nice properties:

►  $\sum_{j=1}^{2} \lambda_{j}^{i} Q_{j}$  has at most one negative eigenvalue for both  $i \in \{1, 2\}!$ 

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## Convex hull of $\mathcal{O}2$

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  - ►  $\sum_{j=1}^{2} \lambda_{j}^{i} Q_{j}$  has at most one negative eigenvalue for both  $i \in \{1, 2\}!$

► Basically, the sets  $(\mathcal{O}2)^{\lambda_i}$   $i \in \{1, 2\}$  are either ellipsoid (may be degenarate) or hyperboloid which is union of two convex sets

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hyperboloid which is union of two convex sets.

## Convex hull of $\mathcal{O}2$

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• The paper [Yildiran (2009)] gives algorithm to compute  $\lambda_1$  and  $\lambda_2$ .

The quadratic constraints (O2)<sup>λ<sup>i</sup></sup> i ∈ {1,2} has very nice properties:

- ►  $\sum_{j=1}^{2} \lambda_j^i Q_j$  has at most one negative eigenvalue for both  $i \in \{1, 2\}$ !
- ► Basically, the sets  $(\mathcal{O}2)^{\lambda_i}$   $i \in \{1, 2\}$  are either ellipsoid (may be degenarate) or

hyperboloid which is union of two convex sets.

Henceforth, we call quadratic constraints with the "quadratic part" having at most one negative eigenvalue as a good constraint.

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## Example

$$S := \left\{ x, y \mid \begin{array}{cc} -xy & < & -1 \\ x^2 + y^2 & < & 9 \end{array} \right\}$$



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## Example - contd 1

conv(S) := 
$$\left\{ x, y \mid \begin{array}{cc} (x - y)^2 & < & 7 \\ x^2 + y^2 & < & 9 \end{array} \right\}$$



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## Example - contd 2

$$S := \left\{ x, y \mid \begin{array}{cc} -xy < & -1 \\ x^2 + y^2 & < & 9 \end{array} \right\}$$

conv(S) := 
$$\left\{ x, y \mid \begin{array}{cc} (x-y)^2 < 7 \\ x^2 + y^2 < 9 \end{array} \right\}$$

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• Understanding the blue quadratic:  $\lambda^1 = (2, 1)$ +  $x^2 + y^2 < -1 \times 2$ +  $x^2 + y^2 < 9 \times 1$ 

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## Example - contd 2

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► Understanding the blue quadratic:  $\lambda^1 = (2, 1)$   $-xy < -1 \times 2$   $+ x^2 + y^2 < 9 \times 1$  $x^2 - 2xy + y^2 < 7 \equiv (x - y)^2 < 7$ 

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## Example - contd 2

$$S := \left\{ x, y \mid \begin{array}{c} -xy < -1 \\ x^2 + y^2 < 9 \end{array} \right\}$$

conv(S) := 
$$\begin{cases} x, y \mid (x - y)^2 < 7 \\ x^2 + y^2 < 9 \end{cases}$$

Understanding the blue quadratic: 
$$\lambda^1 = (2, 1)$$
  

$$-xy < -1 \times 2$$

$$+ x^2 + y^2 < 9 \times 1$$

$$x^2 - 2xy + y^2 < 7 \equiv (x - y)^2 < 7$$

▶  $\lambda^2 = (0, 1)$ , so the second aggregated constraints is  $x^2 + y^2 < 9$ .

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## Literature survey (incomplete!)

### Related results:

- [Yildiran (2009)]
- [Burer and Kılınc-Karzan (2017)] (second order cone intersection with a nonconvex quadratic)
- [Modaresi and Vielma (2017)] (closed version of results)

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## Literature survey (incomplete!)

### Related results:

- [Yildiran (2009)]
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Other related papers:

▶ ...

- [Tawarmalani, Richard, Chung (2010)] (Covering bilinear knapsack)
- [Santana and Dey (2020)] (polytope and one quadratic constraint)
- [Ye and Zhang (2003)], [Burer and Anstreicher (2013)], [Beinstock (2014)] [Burer (2015)], [Burer and Yang (2015)], [Anstreicher (2017)] (extended trust-region problem)
- [Burer and Ye (2019)], [Wang and Kılınc-Karzan (2020, 2021)], [Argue, Kılınc-Karzan, and Wang (2020)] (general conditions for the SDP relaxation being tight)
- [Bienstock, Chen, and Muñoz (2020)], [Muñoz and Serrano (2020)] (Cut for QCQP using intersction approach)

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## Questions we consider...

### The main goal of this study is to understand the power of aggregation.

- What happens for m > 2, i.e. for the case of two rows.
- If we cannot obtain the convex hull via aggregation, then can be identify explicit examples.

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etc.

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## Results described in a high level

Under some technical sufficient conditions, intersection of aggregations (not necessarily finite) can lead to convex hull for three quadratic constraints.

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## Results described in a high level

- Under some technical sufficient conditions, intersection of aggregations (not necessarily finite) can lead to convex hull for three quadratic constraints.
- The above result represents the limit of aggregations.

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## Results described in a high level

- Under some technical sufficient conditions, intersection of aggregations (not necessarily finite) can lead to convex hull for three quadratic constraints.
- ▶ The above result represents the limit of aggregations. Basically, aggregations do not lead to convex hull even when the technical sufficient condition does not hold for m = 3 or when m > 3.

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## Three rows: main result

Theorem Let  $n \ge 3$  and

$$\mathcal{O}3 = \left\{ x \in \mathbb{R}^n \mid \begin{bmatrix} x & 1 \end{bmatrix} \begin{bmatrix} A_i & b_i \\ b_i^\top & c_i \end{bmatrix} \begin{bmatrix} x \\ 1 \end{bmatrix} < 0, \ i \in [3] \right\}.$$

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### Assume

• (Positive definite linear combination, (PDLC)) There exists  $\theta \in \mathbb{R}^3$  such that

$$\sum_{i=1}^{3} \theta_i \begin{bmatrix} A_i & b_i \\ b_i^{\top} & c_i \end{bmatrix} \succ 0.$$

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• (Non-trivial convex hull)  $\operatorname{conv}(\mathcal{O}3) \neq \mathbb{R}^n$ .

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Let

 $\Omega:=\left\{\lambda\in\mathbb{R}^3_+\,|\,(\mathcal{O}3)^\lambda\supseteq\text{conv}(\mathcal{O}3)\text{ and }\mathcal{O}3\text{ is good}\right\},$ 

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• (Non-trivial convex hull)  $\operatorname{conv}(\mathcal{O}3) \neq \mathbb{R}^n$ .

Let

 $\Omega := \left\{ \lambda \in \mathbb{R}^3_+ \, | \, (\mathcal{O}3)^\lambda \supseteq \mathsf{conv}(\mathcal{O}3) \text{ and } \mathcal{O}3 \text{ is good} \right\},$ 

where 
$$(\mathcal{O}3)^{\lambda} = \left\{ x \in \mathbb{R}^n \mid \begin{bmatrix} x & 1 \end{bmatrix} \begin{pmatrix} \sum_{i=1}^3 \lambda_i \begin{bmatrix} A_i & b_i \\ b_i^{\top} & c_i \end{bmatrix} \end{pmatrix} \begin{bmatrix} x \\ 1 \end{bmatrix} < 0 \right\}.$$
  
Then

$$\operatorname{conv}(\mathcal{O}3) = \bigcap_{\lambda \in \Omega} (\mathcal{O}3)^{\lambda}.$$

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$$S := \left\{ (x, y, z) \middle| \begin{array}{rrrr} x^2 + y^2 & < & 2 \\ -x^2 - y^2 & < & -1 \\ -x^2 + y^2 + z^2 + 6x & < & 0 \end{array} \right\}$$

▶ PDLC condition holds,  $conv(S) \neq \mathbb{R}^3$ 

$$\operatorname{conv}(S) := \left\{ (x, y, z) \middle| \begin{array}{c} x^2 + y^2 < 2 \\ -2x^2 + z^2 + 6x < -1 & \star \\ -x^2 + y^2 + z^2 + 6x < 0 \end{array} \right\}$$

\*: sum of second and third constraint describing S

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## Example -contd 1



Figure: Plots of sets S (left) and conv(S) (right).

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## Comparsion of results

Two	quadratic	Three	quadratic
constraints		constraints	
[Yildira	n (2009)]	This tal	k

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When do	da a a	:+	conv(S	$S) \neq \mathbb{R}^n$	Under I	PDLC con-
	does	"			dition, o	$\operatorname{conv}(S) \neq$
1010 ?					$\mathbb{R}^n$	

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## Comparsion of results

	Two quadratic	Three quadratic
	constraints	constraints
	[Yildiran (2009)]	This talk
When does it hold?	$\operatorname{conv}(S)  eq \mathbb{R}^n$	Under PDLC con-
		dition, conv(S) $\neq$
		$\mathbb{R}^{n}$
	2	$\infty$ (Conjecture!)
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scribe convex		
hull?		

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## Comparsion of results

	Two quadratic constraints	Three quadratic constraints	
	[Yildiran (2009)]	This talk	
When does it hold?	$\operatorname{conv}(S)  eq \mathbb{R}^n$	Under PDLC condition, $conv(S) \neq \mathbb{R}^n$	
How many aggre- gated inequalities needed to de- scribe convex hull?	2	$\infty$ (Conjecture!)	
Structure of ag- gregated inequal- ities	Polynomial-time algorithm exists to find them	Even checking if $\lambda \in \Omega$ is not clear.	

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## The closed case

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Theorem Let  $n \ge 3$  and let

$$C3 = \left\{ x \in \mathbb{R}^n \mid \begin{bmatrix} x & 1 \end{bmatrix} \begin{bmatrix} A_i & b_i \\ b_i^\top & c_i \end{bmatrix} \begin{bmatrix} x \\ 1 \end{bmatrix} \le 0, \ i \in [3] \right\}.$$

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## The closed case

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### Assume

• (Positive definite linear combination, or PDLC) There exists  $\theta \in \mathbb{R}^3$  such that

$$\sum_{i=1}^{3} \theta_i \begin{bmatrix} A_i & b_i \\ b_i^{\top} & c_i \end{bmatrix} \succ 0.$$

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• (Non-trivial convex hull)  $\operatorname{conv}(C3) \neq \mathbb{R}^n$ .

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• (Non-trivial convex hull)  $\operatorname{conv}(C3) \neq \mathbb{R}^n$ .

• (No low-dimensional components)  $C3 \subseteq int(C3)$ .

Let

$$\Omega' := \left\{ \lambda \in \mathbb{R}^3_+ \, | \, (\mathcal{C}3)^\lambda \supseteq \operatorname{conv}(\mathcal{C}3) \text{ and } (\mathcal{C}3)^\lambda \text{ is good} \right\},$$
  
where  $(\mathcal{C}3)^\lambda = \left\{ x \in \mathbb{R}^n \, | \, [x \quad 1] \left( \sum_{i=1}^3 \lambda_i \begin{bmatrix} A_i & b_i \\ b_i^\top & c_i \end{bmatrix} \right) \begin{bmatrix} x \\ 1 \end{bmatrix} \le 0 \right\}$ 

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## The closed case

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• (Non-trivial convex hull)  $\operatorname{conv}(C3) \neq \mathbb{R}^n$ .

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where  $(\mathcal{C}3)^{\lambda} = \left\{ x \in \mathbb{R}^n \mid [x \quad 1] \left( \sum_{i=1}^3 \lambda_i \begin{bmatrix} A_i & b_i \\ b_i^{\top} & c_i \end{bmatrix} \right) \begin{bmatrix} x \\ 1 \end{bmatrix} \le 0 \right\}$  Then  
$$\overline{\operatorname{conv}(\mathcal{C}3)} = \bigcap_{\lambda \in \Omega'} (\mathcal{C}3)^{\lambda}.$$

## 2.2 Counter examples

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$$S := egin{cases} (x,y,z) & x^2 < 1 \ y^2 < 1 \ -xy + z^2 < 0 \end{cases}$$

m = 3 but not satisfying PDLC condition

▶ PDLC condition does not hold,  $conv(S) \neq \mathbb{R}^3$ 



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$$S := \begin{cases} (x, y, z) & x^2 < 1 \\ y^2 < 1 \\ -xy + z^2 < 0 \end{cases}$$

m = 3 but not satisfying PDLC condition

PDLC condition does not hold, conv(S) ≠ ℝ<sup>3</sup>



$$\blacktriangleright \hspace{0.1 cm} \mathsf{conv}(\mathcal{S}) \neq \cap_{\lambda \in \Omega} \mathcal{S}^{\lambda}$$

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$$m = 4$$
 (and satisfying PDLC)

$$S := \begin{cases} (x, y, z) & x^2 + y^2 + z^2 + 2.2(xy + yz + xz) < 1 \\ -2.1x^2 + y^2 + z^2 < 0 \\ x^2 - 2.1y^2 + z^2 < 0 \\ x^2 + y^2 - 2.1z^2 < 0 \end{cases}$$

▶ PDLC condition holds, conv(S)  $\neq \mathbb{R}^3$ 



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▶ PDLC condition holds, conv(S)  $\neq \mathbb{R}^3$ 



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 $\blacktriangleright \hspace{0.1 cm} \mathsf{conv}(S) \neq \cap_{\lambda \in \Omega} S^{\lambda}$ 

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## Do we need a finite number of aggregations?

$$S := \{x, y \mid x^2 \le 1, y^2 \le 1, (x-1)^2 + (y-1)^2 \ge 1\},\$$

PDLC does not hold

• Let 
$$\Omega^+ := \{\lambda \in \mathbb{R}^3_+ | S^\lambda \supseteq \operatorname{conv}(S)\}$$

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## Do we need a finite number of aggregations?

$$S := \{x, y \mid x^2 \leq 1, \ y^2 \leq 1, \ (x-1)^2 + (y-1)^2 \geq 1\},$$

PDLC does not hold

► conv(S) =  $\bigcap_{\lambda \in \Omega^+} S^{\lambda}$ .

▶  $\operatorname{conv}(S) \subsetneq \bigcap_{\lambda \in \tilde{\Omega}^+} S^{\lambda}$  for any  $\tilde{\Omega}^+ \subseteq \Omega^+$  which is finite.



Figure: Plots of sets S (left) and conv(S) (right).

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3 Proof outlines

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3.1 A new S-lemma

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## A new S-Lemma for 3 quadratic constraints

### Lemma

Let  $n \geq 3$  and let  $g_1, g_2, g_3 : \mathbb{R}^n \to \mathbb{R}$  be homogeneous quadratic functions:

$$g_i(x) = x^\top Q_i x.$$

Assuming there is a linear combination of  $Q_1, Q_2, Q_3$  that is positive definite, the following equivalence holds

$$\{x \in \mathbb{R}^n : g_i(x) < 0, i \in [3]\} = \emptyset \iff \exists \lambda \in \mathbb{R}^3_+ \setminus \{0\}, \sum_{i=1}^3 \lambda_i Q_i \succeq 0.$$

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## Main ingredients for proving new S-lemma

SDP strong duality (under staler condition)

## Theorem ([Barvinok (2001)])

If  $A \subseteq \mathbb{S}^n$  is an affine subspace such that the intersection  $\mathbb{S}^n_+ \cap A$  is non-empty, bounded and dim $(A) \ge \binom{n+1}{2} - \binom{r+2}{2}$  then there is a matrix  $X \in \mathbb{S}^n_+ \cap A$  such that rank $(X) \le r$ .

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## 3.2 Rest of proof

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## Lets try to prove $\operatorname{conv}(S) = \cap_{\lambda \in \Omega} S^{\lambda}$

 $\operatorname{conv}(S) \subseteq \cap_{\lambda \in \Omega} S^{\lambda}$  <— Straight forward

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## Lets try to prove $\operatorname{conv}(S) = \cap_{\lambda \in \Omega} S^{\lambda}$

 $\operatorname{conv}(S) \subseteq \cap_{\lambda \in \Omega} S^{\lambda} \operatorname{conv}(S) \supseteq \cap_{\lambda \in \Omega} S^{\lambda}$ :

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Pick  $x^* \in \mathbb{R}^n$  such that  $x^* \notin \text{conv}(S)$ 

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 $\operatorname{conv}(S) \subseteq \cap_{\lambda \in \Omega} S^{\lambda} \operatorname{conv}(S) \supseteq \cap_{\lambda \in \Omega} S^{\lambda}$ :

- Pick  $x^* \in \mathbb{R}^n$  such that  $x^* \notin \operatorname{conv}(S)$
- Separation theorem), there exists α<sup>T</sup>x < β valid for conv(S) that separates x<sup>\*</sup>.

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- Homogenization) The above together with conv(S) ≠ ℝ<sup>n</sup> can be shown to imply: {x|α<sup>T</sup>x = βx<sub>n+1</sub>} (call it H) does not intersect homogenization of S:

$$H \cap \left\{ \begin{pmatrix} x, x_{n+1} \mid \begin{bmatrix} x & x_{n+1} \end{bmatrix} \begin{bmatrix} A_i & b_i \\ b_i^\top & c_i \end{bmatrix} \begin{bmatrix} x \\ x_{n+1} \end{bmatrix} < 0, \ i \in [3] \right\} = \emptyset.$$

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► (Apply S-lemma, assuming PDLC) We obtain  $\lambda \in \Omega$  such that

$$H \cap \left\{ \begin{pmatrix} x, x_{n+1} \mid [x \quad x_{n+1}] \begin{pmatrix} \sum_{i=1}^{3} \lambda_i \begin{bmatrix} A_i & b_i \\ b_i^{\top} & c_i \end{bmatrix} \end{pmatrix} \begin{bmatrix} x \\ x_{n+1} \end{bmatrix} < 0, \right\} = \emptyset.$$

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It turns, the above is sufficient to show that  $x^* \neq S^{\lambda}$ .

Thank You

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