

Set
Convexifications
for QCQP

Santanu Dey,
Burak Kocuk,
Asteroide Santana

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The convex hull of
a quadratic
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Rank-one sets and
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Appendix

Convexification of substructures in quadratically constrained quadratic program

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Mixed-integer Nonlinear Optimization: Theory and
Computation
Centre De Recherches Mathamatiques

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Outline

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1. The convex hull of quadratic constraints over polytopes

Asteroide Santana, Santanu S. Dey.

2. A study of rank-one sets with linear side constraints and application to the pooling problem

Santanu S. Dey, Burak Kocuk, Asteroide Santana.

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Section 1

Motivation

A QCQP for Structural engineering application

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$$\begin{aligned} \min \quad & \sum_{k=1}^m z_k \\ \text{s.t.} \quad & |x^\top Q_k y + a_k^\top x + b_k^\top y + c_k| = z_k, \quad k \in \{1, \dots, m\} \\ & x \in [0, 1]^{n_1}, y \in [0, 1]^{n_2}, \end{aligned} \tag{1}$$

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Updating FEM model for bridges

$$\begin{aligned} \min \quad & \sum_{k=1}^m z_k \\ \text{s.t.} \quad & |\mathbf{x}^\top Q_k \mathbf{y} + a_k^\top \mathbf{x} + b_k^\top \mathbf{y} + c_k| = z_k, \quad k \in \{1, \dots, m\} \\ & \mathbf{x} \in [0, 1]^{n_1}, \mathbf{y} \in [0, 1]^{n_2}, \end{aligned} \tag{1}$$

QCQP (Bilinear Program):

$$\begin{aligned} \min \quad & \sum_{k=1}^m z'_k + z''_k \\ \text{s.t.} \quad & \mathbf{x}^\top Q_k \mathbf{y} + a_k^\top \mathbf{x} + b_k^\top \mathbf{y} + c_k = z'_k - z''_k, \quad k \in \{1, \dots, m\} \\ & \mathbf{x} \in [0, 1]^{n_1}, \mathbf{y} \in [0, 1]^{n_2}. \\ & 0 \leq z'_k, z''_k \leq u, \quad k \in \{1, \dots, m\}. \end{aligned} \tag{2}$$

Need to obtain good dual bounds

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We tried various approaches.

1. McCormick relaxation + Semidefinite programming relaxation
2. Commercial solvers (for hours)

Need to obtain good dual bounds

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We tried various approaches.

1. McCormick relaxation + Semidefinite programming relaxation
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Motivation from Integer programming: Convexification of substructures like knapsack set, flow cover sets, mixing sets, etc.

A very successful approach in integer linear programming is to generate cutting-planes implied by single constraint relaxations.

Convex hull of one-constraint relaxation

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Theorem (Santana, D., Wang)

Consider the set (S) defined as:

$$\left. \begin{array}{l} \sum_{i=1}^{n_1} \sum_{j=1}^{n_2} q_{ij} w_{ij} + \sum_{i=1}^{n_1} a_i x_i + \sum_{j=1}^{n_2} b_j y_j + c = 0, \\ w_{ij} = x_i y_j, \quad i \in [n_1], j \in [n_2], \\ (x, y, w) \in [0, 1]^{n_1+n_2+n_1 n_2} \end{array} \right\} (S)$$

Then, $\text{conv}(S)$ is SOC-representable (SOCr).

Convex hull of one-constraint relaxation

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Theorem (Santana, D., Wang)

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$$\left. \begin{array}{l} \sum_{i=1}^{n_1} \sum_{j=1}^{n_2} q_{ij} w_{ij} + \sum_{i=1}^{n_1} a_i x_i + \sum_{j=1}^{n_2} b_j y_j + c = 0, \\ w_{ij} = x_i y_j, \quad i \in [n_1], j \in [n_2], \\ (x, y, w) \in [0, 1]^{n_1+n_2+n_1 n_2} \end{array} \right\} (S)$$

Then, $\text{conv}(S)$ is SOC-representable (SOCr).

We give a constructive proof.

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Convex hull of one-constraint relaxation

Theorem (Santana, D., Wang)

Consider the set (S) defined as:

$$\left. \begin{array}{l} \sum_{i=1}^{n_1} \sum_{j=1}^{n_2} q_{ij} w_{ij} + \sum_{i=1}^{n_1} a_i x_i + \sum_{j=1}^{n_2} b_j y_j + c = 0, \\ w_{ij} = x_i y_j, \quad i \in [n_1], j \in [n_2], \\ (x, y, w) \in [0, 1]^{n_1+n_2+n_1 n_2} \end{array} \right\} (S)$$

Then, $\text{conv}(S)$ is SOC-representable (SOCr).

- ▶ M. Tawarmalani, N.V. Sahinidis [2001]
- ▶ M. Tawarmalani, J.-P. P. Richard, K. Chung [2010]
- ▶ K. M. Anstreicher, S. Burer [2010]
- ▶ T. T. Nguyen, J.-P. P. Richard, M. Tawarmalani [2012]
- ▶ A. Gupte Thesis [2012]
- ▶ B. Kocuk, SSD, and X. A. Sun [2018]
- ▶ And many others... (especially on convex envelopes of bilinear functions)

This substructure convexification worked well

1. We used a new branching rule.
2. Used a polyhedral outer approximation of the SOCr convex hull.

Table: Comparison with BARON

Inst	newBB, row-wise SOCP			BARON		
	Dual	Primal	% Gap	Dual	Primal	% Gap
1	2.5074	3.4785	27.91	0.3312	3.4789	90.47
2	2.8644	3.4998	18.15	0.5245	3.4993	85.01
3	3.1308	3.6810	14.94	0.4760	3.6831	87.07
4	3.1115	3.7522	17.07	0.7863	3.7530	79.04
5	3.7896	4.1328	8.30	0.3840	4.1354	90.71
6	4.6399	5.6609	18.03	2.2657	5.6605	59.97

Running-time: 10 hours.

$$\% \text{gap} = \frac{\text{Primal} - \text{Dual}}{\text{Primal}}$$

Questions

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- ▶ What about more general quadratic constraints?
- ▶ What about more general linear constraints?

Section 2

The convex hull of a quadratic constraint over a polytope

Our result

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Theorem (Santana, D.)

Let

$$S := \{x \in \mathbb{R}^n \mid x^\top Qx + c^\top x = d, x \in P\},$$

where P is a polytope. Then, $\text{conv}(S)$ is SOCr. Moreover, we provide a constructive proof to generate $\text{conv}(S)$.

Proof of Thm (sketch)

Underlying Proof Structure

If S is a compact set, then

$$\text{conv}(S) = \text{conv}(\text{extr}(S)).$$

Proof of Thm (sketch)

Underlying Proof Structure

If S is a compact set, then

$$\text{conv}(S) = \text{conv}(\text{extr}(S)).$$

As a consequence:

1. If $\text{extr}(S) \subseteq \bigcup_{k=1}^m T_k \subseteq S$, then

$$\boxed{\text{conv}(S) = \text{conv}\left(\bigcup_{k=1}^m \text{conv}(T_k)\right)}$$

2. Finally, if $\text{conv}(T_k)$ is SOCr, then $\text{conv}(S)$ is SOCr.

Proof of Thm (sketch)

Structure Lemma on Quadratic functions

Lemma

Consider the set defined by a quadratic equation. Then exactly one of the following occurs:

Proof of Thm (sketch)

Structure Lemma on Quadratic functions

Lemma

Consider the set defined by a quadratic equation. Then exactly one of the following occurs:

1. *It is the boundary of a SOCP representable convex set,*

Proof of Thm (sketch)

Structure Lemma on Quadratic functions

Lemma

Consider the set defined by a quadratic equation. Then exactly one of the following occurs:

1. *It is the boundary of a SOCP representable convex set,*
2. *It is the union of boundary of two disjoint SOCP representable convex set; or*

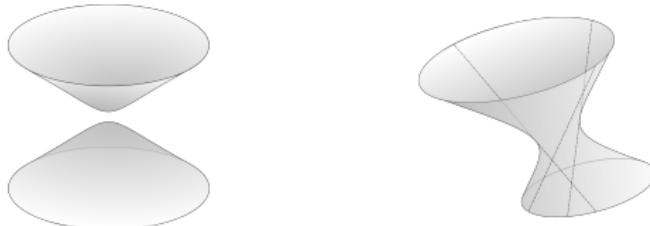
Proof of Thm (sketch)

Structure Lemma on Quadratic functions

Lemma

Consider the set defined by a quadratic equation. Then exactly one of the following occurs:

1. It is the *boundary of a SOCP representable convex set*,
2. It is the *union of boundary of two disjoint SOCP representable convex set*; or
3. It has the property that, *through every point, there exists a straight line that is entirely contained in the surface*.



https://www.math.arizona.edu/~models/Ruled_Surfaces/source/1.html

Ruled surface are beautiful!

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Proof of Thm (sketch)

Using the Structure Lemma

1. If in Case 1 or Case 2: (i.e., the boundary of SOCP representable convex set or union of boundary of two SOCP representable sets), then done!

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Proof of Thm (sketch)

Using the Structure Lemma

1. If in Case 1 or Case 2: (i.e., the boundary of SOCP representable convex set or union of boundary of two SOCP representable sets), then done!
2. Otherwise:
 - 2.1 Because of the lines (Case 3), no point in the relative interior of the polytope can be an extreme point;

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Using the Structure Lemma

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 - 2.1 Because of the lines (Case 3), **no point in the relative interior of the polytope can be an extreme point;**
 - 2.2 Intersect the quadratic with each facet of the polytope;

Proof of Thm (sketch)

Using the Structure Lemma

1. If in Case 1 or Case 2: (i.e., the boundary of SOCP representable convex set or union of boundary of two SOCP representable sets), then done!
2. Otherwise:
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 - 2.2 Intersect the quadratic with each facet of the polytope;
 - 2.3 Each intersection yields a new quadratic set of the same form, but in lower dimension;

Proof of Thm (sketch)

Using the Structure Lemma

1. If in Case 1 or Case 2: (i.e., the boundary of SOCP representable convex set or union of boundary of two SOCP representable sets), then done!
2. Otherwise:
 - 2.1 Because of the lines (Case 3), **no point in the relative interior of the polytope can be an extreme point**;
 - 2.2 Intersect the quadratic with each facet of the polytope;
 - 2.3 Each intersection yields a new quadratic set of the same form, but in lower dimension;
3. Repeat above argument for each facet.

Proof of Thm (sketch)

Proof of Structure Lemma: Reduction

Lemma

If F is an affine bijective map, then:

1. $\text{conv}(F(S)) = F(\text{conv}(S))$;
2. $\text{conv}(S)$ is SOC r iff $\text{conv}(F(S))$ is SOC r .

Then, we rewrite

$$S := \{x \in \mathbb{R}^n \mid x^\top Qx + c^\top x = d, x \in P\},$$

as

$$\begin{aligned} S = \Big\{ (u, v, w) \in \mathbb{R}^{n_{q+}} \times \mathbb{R}^{n_{q-}} \times \mathbb{R}^{n_l} \mid \\ \sum_{i=1}^{n_{q+}} u_i^2 - \sum_{j=1}^{n_{q-}} v_j^2 + \sum_{k=1}^{n_l} w_k = d, (u, v, w) \in P \Big\}, \end{aligned}$$

where we may assume $d \geq 0$.

Proof of Thm (sketch)

Proof of Observation 2: Classification

$$S = \left\{ (u, v, w) \in \mathbb{R}^{n_{q+}} \times \mathbb{R}^{n_{q-}} \times \mathbb{R}^{n_l} \mid \sum_{i=1}^{n_{q+}} u_i^2 - \sum_{j=1}^{n_{q-}} v_j^2 + \sum_{k=1}^{n_l} w_k = d, (u, v, w) \in P \right\}$$

Lemma

Case	Classification
1) $n_l \geq 2$	<i>straight line</i>
2) $n_{q+} \leq 1, n_l = 0$	<i>Case 1 or Case 2</i>
3) $n_{q+} + n_{q-} = 0, n_l \leq 1$	<i>Case 1 or Case 2</i>
4) $n_{q+}, n_{q-} \geq 1, n_l = 1$	<i>straight line</i>
5) $n_{q+} \geq 2, n_{q-} \geq 1, n_l = 0$	<i>straight line</i>

Discussion

Classify: conv.hull of QCQP substructure is SOCr?

Is SOCP representable:

1. One quadratic equality constraint \cap polytope
2. Two quadratic inequalities (Burer, Klinc-Karzan [2017],
Modaresi, Vielma [2017])

Discussion

Classify: conv.hull of QCQP substructure is SOCr?

Is SOCP representable:

1. One quadratic equality constraint \cap polytope
2. Two quadratic inequalities (Burer, Klinc-Karzan [2017],
Modaresi, Vielma [2017])

Is not SOCP representable:

1. Already in 10 variables, 5 quadratic equalities, 4 quadratic inequalities, 3 linear inequalities (Fawzi [2018])

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Section 3

Rank-one sets and applications to the pooling problem

3.1

Setting and Theoretical results

Rank-one sets with linear side constraints

Notation: $[m] = \{1, \dots, m\}$

Consider again the QCQP:

$$\begin{aligned} \min \quad & x^\top Q^0 x + (a^0)^\top x \\ \text{s.t.} \quad & x^\top Q^k x + (a^k)^\top x = b_k \quad \forall k \in [m] \\ & x \in [0, 1]^n. \end{aligned}$$

Rank-one sets with linear side constraints

Notation: $[m] = \{1, \dots, m\}$

Consider again the QCQP:

$$\begin{array}{ll}\min & x^\top Q^0 x + (a^0)^\top x \\ \text{s.t.} & x^\top Q^k x + (a^k)^\top x = b_k \quad \forall k \in [m] \\ & x \in [0, 1]^n.\end{array}$$

Which can be rewritten as:

$$\begin{array}{ll}\min & \langle Q^0, X \rangle + (a^0)^\top x \\ \text{s.t.} & \langle Q^k, X \rangle + (a^k)^\top x \leq b_k \quad \forall k \in [m] \\ & \text{rank} \left(\begin{bmatrix} 1 & x^\top \\ x & X \end{bmatrix} \right) = 1 \\ & x \in [0, 1]^n,\end{array}$$

where $\langle U, V \rangle := \sum_{i=1}^{n_1} \sum_{j=1}^{n_2} U_{ij} V_{ij}$.

Rank-one sets with linear side constraints

Notation: $[m] = \{1, \dots, m\}$

Consider again the QCQP:

$$\begin{array}{ll}\min & x^\top Q^0 x + (a^0)^\top x \\ \text{s.t.} & x^\top Q^k x + (a^k)^\top x = b_k \quad \forall k \in [m] \\ & x \in [0, 1]^n.\end{array}$$

Which can be rewritten as:

$$\begin{array}{ll}\min & \langle Q^0, X \rangle + (a^0)^\top x \\ \text{s.t.} & \langle Q^k, X \rangle + (a^k)^\top x \leq b_k \quad \forall k \in [m] \\ & \text{rank} \left(\begin{bmatrix} 1 & x^\top \\ x & X \end{bmatrix} \right) = 1 \\ & x \in [0, 1]^n,\end{array}$$

where $\langle U, V \rangle := \sum_{i=1}^{n_1} \sum_{j=1}^{n_2} U_{ij} V_{ij}$.

$$\mathcal{U} := \left\{ W \in \mathbb{R}_+^{n_1 \times n_2} \mid \langle A^k, W \rangle \leq b_k, \forall k \in [m], \text{rank}(W) \leq 1 \right\}$$

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Some choices of linear side constraints: a well-known result

$$\mathcal{U} := \left\{ W \in \mathbb{R}_+^{n_1 \times n_2} \mid \langle A^k, W \rangle \leq b_k, \forall k \in [m], \text{rank}(W) \leq 1 \right\}.$$

Known result

- ▶ All individual variable bounds:

$$\bar{\mathcal{U}} := \left\{ W \in \mathbb{R}_+^{n_1 \times n_2} \mid W_{ij} \leq 1, \forall i \in [n_1], j \in [n_2], \text{rank}(W) \leq 1 \right\}.$$

Then, $\text{conv}(\bar{\mathcal{U}})$ is the Boolean Quadric Polytope.

(Burer, Letchford [2009])

One of two arbitrary side constraints

- ▶ Single linear constraint with non-negative coefficients:

$$\mathcal{U}^1 := \left\{ W \in \mathbb{R}_+^{n_1 \times n_2} \mid \langle A^1, W \rangle \leq b_1, \text{rank}(W) \leq 1 \right\}.$$

Then, $\text{conv}(\mathcal{U}^1)$ is a polyhedron.

One of two arbitrary side constraints

- ▶ Single linear constraint with non-negative coefficients:

$$\mathcal{U}^1 := \left\{ W \in \mathbb{R}_+^{n_1 \times n_2} \mid \langle A^1, W \rangle \leq b_1, \text{rank}(W) \leq 1 \right\}.$$

Then, $\text{conv}(\mathcal{U}^1)$ is a polyhedron.

- ▶ Two linear constraint (assuming set is bounded):

$$\mathcal{U}^2 := \left\{ W \in \mathbb{R}_+^{n_1 \times n_2} \mid \begin{array}{l} \langle A^k, W \rangle \leq b_k, \quad k = 1, 2, \\ \text{rank}(W) \leq 1 \end{array} \right\}.$$

Then, $\text{conv}(\mathcal{U}^2)$ is SOCr.

Arbitrary number of constraints - I

Theorem (D., Kocuk, Santana)

$$\mathcal{U} := \left\{ W \in \mathbb{R}_+^{n_1 \times n_2} \mid \langle A^k, W \rangle \leq b_k, \forall k \in [m], \text{rank}(W) \leq 1 \right\}.$$

Suppose the constraint matrices are of the form

$$A^k := \alpha^k \beta^\top \quad k \in [m],$$

where $\alpha^k \in \mathbb{R}^{n_1}$ for $k \in [m]$ and $\beta \in \mathbb{R}_{++}^{n_2}$. Moreover, let the α^k 's be such that $\{u \in \mathbb{R}_+^{n_1} \mid (\alpha^k)^\top u \leq 0, \forall k \in [m]\} = \{0\}$. Then:

1. The $\text{conv}(\mathcal{U})$ is a polyhedron.
2. A compact extended formulation of $\text{conv}(\mathcal{U})$ is given by:

$$\sum_{j=1}^{n_2} t_j = 1, \quad t_j \geq 0 \quad \forall j \in [n_2]$$

$$\sum_{i=1}^{n_1} \alpha_i^k \beta_j W_{ij} \leq b_k t_j \quad \forall k \in [m], j \in [n_2].$$

Arbitrary number of constraints - I

Theorem (D., Kocuk, Santana)

$$\mathcal{U} := \left\{ W \in \mathbb{R}_+^{n_1 \times n_2} \mid \langle A^k, W \rangle \leq b_k, \forall k \in [m], \text{rank}(W) \leq 1 \right\}.$$

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$$\sum_{j=1}^{n_2} t_j = 1, \quad t_j \geq 0 \quad \forall j \in [n_2]$$

$$\sum_{i=1}^{n_1} \alpha_i^k \beta_j W_{ij} \leq b_k t_j \quad \forall k \in [m], j \in [n_2].$$

Equivalent to result in (Sherali, Alameddine [1992])

Arbitrary number of constraints - II

Theorem (D., Kocuk, Santana)

Consider the set

$$\mathcal{U} := \left\{ W \in \mathbb{R}_+^{n_1 \times n_2} \mid \langle A^k, W \rangle \leq b_k, \forall k \in [m], \text{rank}(W) \leq 1 \right\},$$

with $n_1 = n_2 \geq 3$. Suppose that \mathcal{U} is bounded and the constraint matrices are of the form

$$A^k := \alpha^k \beta \beta^\top + \gamma^k \delta \delta^\top \quad k \in [m],$$

where $\alpha^k, \gamma^k \in \mathbb{R}_+$ for $k \in [m]$ and $\beta, \delta \in \mathbb{R}_{++}^{n_1}$.

Then, $\text{conv}(\mathcal{U})$ is SOCr. Moreover, for a fixed m , a linear function can be optimized in polytime over \mathcal{U} .

Some corollaries

► Row sum bounds:

$$\mathcal{U}^{\text{row}} := \left\{ W \in \mathbb{R}_+^{n_1 \times n_2} \mid l_i \leq \sum_{j=1}^{n_2} W_{ij} \leq u_i, \forall i \in [n_1], \right. \\ \left. \text{rank}(W) \leq 1 \right\}.$$

Then, $\text{conv}(\mathcal{U}^{\text{row}})$ is a polyhedron.

Some corollaries

- Row sum bounds:

$$\mathcal{U}^{\text{row}} := \left\{ W \in \mathbb{R}_+^{n_1 \times n_2} \mid l_i \leq \sum_{j=1}^{n_2} W_{ij} \leq u_i, \forall i \in [n_1], \right. \\ \left. \text{rank}(W) \leq 1 \right\}.$$

Then, $\text{conv}(\mathcal{U}^{\text{row}})$ is a polyhedron.

- Row sum and overall sum bounds:

$$\mathcal{U}^{\text{row}+} := \left\{ W \in \mathbb{R}_+^{n_1 \times n_2} \mid l_i \leq \sum_{j=1}^{n_2} W_{ij} \leq u_i, \forall i \in [n_1], \right. \\ \left. L \leq \sum_{i=1}^{n_1} \sum_{j=1}^{n_2} W_{ij} \leq U, \text{rank}(W) \leq 1 \right\}.$$

Then, $\text{conv}(\mathcal{U}^{\text{row}+})$ is a polyhedron.

3.2

Application: To the Generalized Pooling Problem

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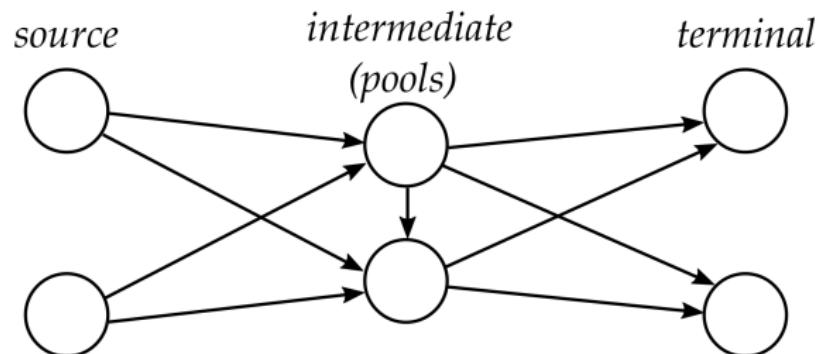
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Pooling problem

Haverly [1978].

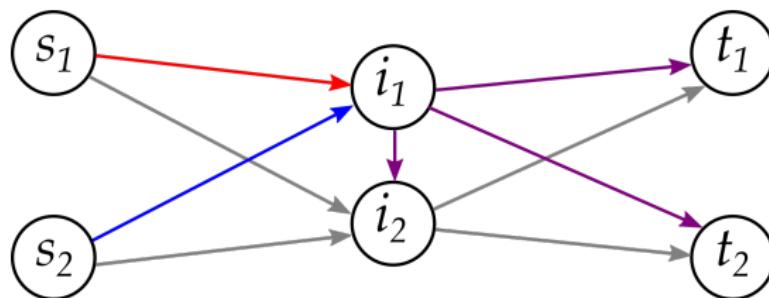


Called *generalized pooling problem* (GPP) if there are pool-pool arcs, otherwise, *standard pooling problem* (SPP).

Pooling problem

Haverly [1978].

Flow consistency requirement must be met at each pool.



pq-Formulation

SPP: Tawarmalani and Sahinidis [2002]
GPP: Alfaki and Haugland [2012]

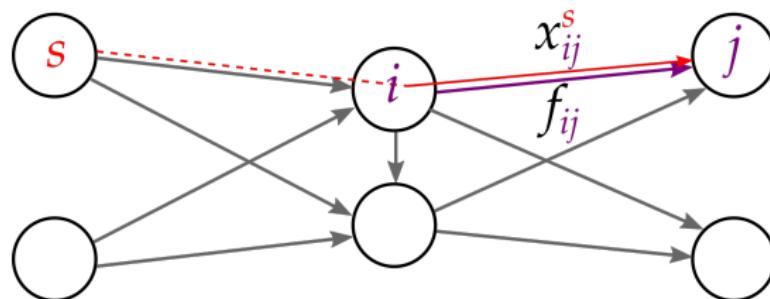
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pq-Formulation

SPP: Tawarmalani and Sahinidis [2002]
GPP: Alfaki and Haugland [2012]

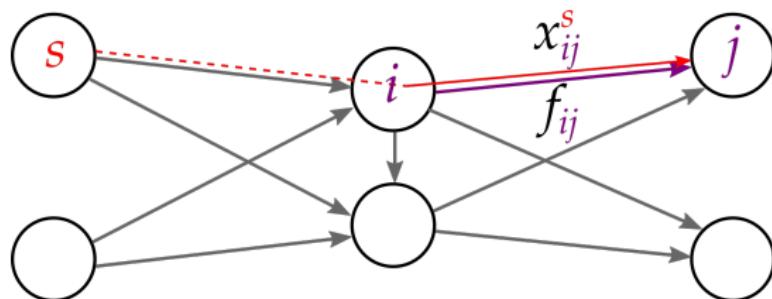
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For a fixed pool i and any source s :

$$q_i^s = \frac{x_{ij}^s}{f_{ij}} \quad \forall j \quad \Rightarrow \quad x_{ij}^s = q_i^s f_{ij} \quad \forall j.$$

tp-Formulation

SPP: Alfaki and Haugland [2013]
GPP: Boland et al. [2016]

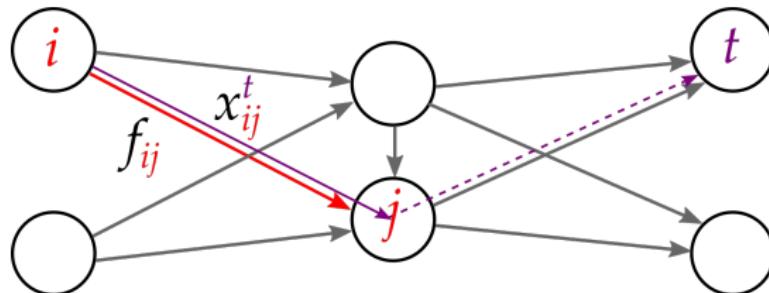
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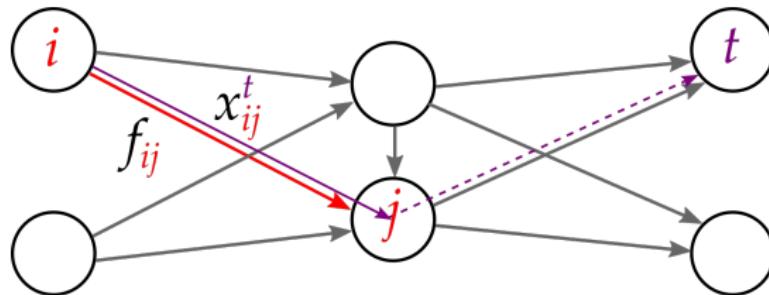
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tp-Formulation

SPP: Alfaki and Haugland [2013]

GPP: Boland et al. [2016]



For a fixed pool j and any terminal t :

$$q_j^t = \frac{x_{ij}^t}{f_{ij}} \quad \forall i \quad \Rightarrow \quad x_{ij}^t = q_j^t f_{ij} \quad \forall i.$$

From pq-formulation to rank-1 (Part I)

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For a fixed pool i , consider the matrix

$$[x_{ij}^s]_{(s,j)} = \begin{bmatrix} x_{i1}^1 & \cdots & x_{ij}^1 & \cdots & x_{in}^1 \\ & & \vdots & & \\ x_{i1}^s & \cdots & x_{ij}^s & \cdots & x_{in}^s \\ & & \vdots & & \\ x_{i1}^m & \cdots & x_{ij}^m & \cdots & x_{in}^m \end{bmatrix}_{(s,j)}$$

Then,

$$\begin{aligned} x_{ij}^s = q_i^s f_{ij}, \quad \forall s, j &\Leftrightarrow [x_{ij}^s]_{(s,j)} = [q_i^s]_s [f_{ij}]_j^\top \\ &\Leftrightarrow \text{rank}([x_{ij}^s]_{(s,j)}) = 1. \end{aligned}$$

From pq-formulation to rank-1 (Part II)

Consider again the matrix $[x_{ij}^s]_{sj}$, $\forall s, j$, for a fixed pool i . Then,

$$q_i^s = \frac{x_{ij}^s}{f_{ij}}, \quad \forall s, j \Leftrightarrow q_i^s = \frac{x_{ij}^s}{\sum_{s'} x_{ij}^{s'}}, \quad \forall s, j \Leftrightarrow \text{rank}([x_{ij}^s]_{(s,j)}) = 1.$$

$$\begin{bmatrix} x_{i1}^1 & \cdots & \cancel{x_{ij}^1} & \cdots & x_{in}^1 \\ \vdots & & \vdots & & \vdots \\ x_{i1}^s & \cdots & \cancel{x_{ij}^s} & \cdots & x_{in}^s \\ \vdots & & \vdots & & \vdots \\ x_{i1}^m & \cdots & \cancel{x_{ij}^m} & \cdots & x_{in}^m \end{bmatrix}_{(s,j)}$$

From pq-formulation to rank-1 (Part II)

Consider again the matrix $[x_{ij}^s]_{sj}$, $\forall s, j$, for a fixed pool i . Then,

$$q_i^s = \frac{x_{ij}^s}{f_{ij}}, \quad \forall s, j \Leftrightarrow q_i^s = \frac{x_{ij}^s}{\sum_{s'} x_{ij}^{s'}}, \quad \forall s, j \Leftrightarrow \text{rank}([x_{ij}^s]_{(s,j)}) = 1.$$

$$\begin{bmatrix} x_{i1}^1 & \cdots & \cancel{x_{ij}^1} & \cdots & x_{in}^1 \\ \vdots & & \vdots & & \vdots \\ x_{i1}^s & \cdots & \cancel{x_{ij}^s} & \cdots & x_{in}^s \\ \vdots & & \vdots & & \vdots \\ x_{i1}^m & \cdots & \cancel{x_{ij}^m} & \cdots & x_{in}^m \end{bmatrix}_{(s,j)}$$

By applying our convex hull result to $\mathcal{U}^{\text{col+}}$ to each matrix $[x_{ij}^s]_{sj}$, $\forall s, j$, we recover the **pq-relaxation!**

From pq-formulation to rank-1 (Part II)

Consider again the matrix $[x_{ij}^s]_{sj}$, $\forall s, j$, for a fixed pool i . Then,

$$q_i^s = \frac{x_{ij}^s}{f_{ij}}, \quad \forall s, j \Leftrightarrow q_i^s = \frac{x_{ij}^s}{\sum_{s'} x_{ij}^{s'}}, \quad \forall s, j \Leftrightarrow \text{rank}([x_{ij}^s]_{(s,j)}) = 1.$$

$$\begin{bmatrix} x_{i1}^1 & \cdots & \cancel{x_{ij}^1} & \cdots & x_{in}^1 \\ \vdots & & \vdots & & \vdots \\ x_{i1}^s & \cdots & \cancel{x_{ij}^s} & \cdots & x_{in}^s \\ \vdots & & \vdots & & \vdots \\ x_{i1}^m & \cdots & \cancel{x_{ij}^m} & \cdots & x_{in}^m \end{bmatrix}_{(s,j)}$$

By applying our convex hull result to $\mathcal{U}^{\text{col}+}$ to each matrix $[x_{ij}^s]_{sj}$, $\forall s, j$, we recover the **pq-relaxation!**

How about $\mathcal{U}^{\text{row}+}$?

From pq-formulation to rank-1 (Part II)

Consider again the matrix $[x_{ij}^s]_{sj}$, $\forall s, j$, for a fixed pool i . Then,

$$q_i^s = \frac{x_{ij}^s}{f_{ij}}, \quad \forall s, j \Leftrightarrow q_i^s = \frac{x_{ij}^s}{\sum_{s'} x_{ij}^{s'}}, \quad \forall s, j \Leftrightarrow \text{rank}([x_{ij}^s]_{(s,j)}) = 1.$$

$$\begin{bmatrix} x_{i1}^1 & \cdots & x_{ij}^1 & \cdots & x_{in}^1 \\ \vdots & & \vdots & & \vdots \\ x_{i1}^s & \cdots & x_{ij}^s & \cdots & x_{in}^s \\ \vdots & & \vdots & & \vdots \\ x_{i1}^m & \cdots & x_{ij}^m & \cdots & x_{in}^m \end{bmatrix}_{(s,j)} \quad \begin{bmatrix} x_{i1}^1 & \cdots & x_{ij}^1 & \cdots & x_{in}^1 \\ \vdots & & \vdots & & \vdots \\ x_{i1}^s & \cdots & x_{ij}^s & \cdots & x_{in}^s \\ \vdots & & \vdots & & \vdots \\ x_{i1}^m & \cdots & x_{ij}^m & \cdots & x_{in}^m \end{bmatrix}_{(s,j)}$$

$$q'_{ij} = \frac{x_{ij}^s}{\sum_{j'} x_{ij'}^s}, \quad \forall s, j \Leftrightarrow \text{rank}([x_{ij}^s]_{(s,j)}) = 1.$$

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From pq-formulation to rank-1 (Part II)

Consider again the matrix $[x_{ij}^s]_{sj}$, $\forall s, j$, for a fixed pool i . Then,

$$q_i^s = \frac{x_{ij}^s}{f_{ij}}, \quad \forall s, j \Leftrightarrow q_i^s = \frac{x_{ij}^s}{\sum_{s'} x_{ij}^{s'}}, \quad \forall s, j \Leftrightarrow \text{rank}([x_{ij}^s]_{(s,j)}) = 1.$$

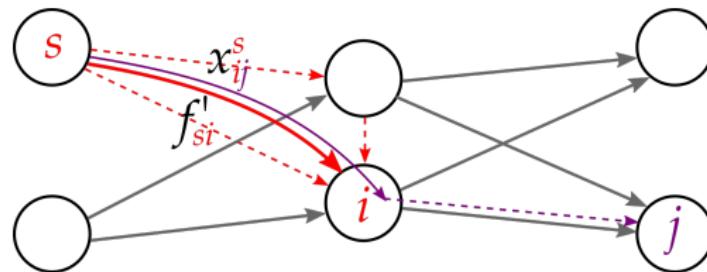
$$\begin{bmatrix} x_{i1}^1 & \cdots & x_{ij}^1 & \cdots & x_{in}^1 \\ \vdots & & \vdots & & \vdots \\ x_{i1}^s & \cdots & x_{ij}^s & \cdots & x_{in}^s \\ \vdots & & \vdots & & \vdots \\ x_{i1}^m & \cdots & x_{ij}^m & \cdots & x_{in}^m \end{bmatrix}_{(s,j)} \quad \begin{bmatrix} x_{i1}^1 & \cdots & x_{ij}^1 & \cdots & x_{in}^1 \\ \vdots & & \vdots & & \vdots \\ x_{i1}^s & \cdots & x_{ij}^s & \cdots & x_{in}^s \\ \vdots & & \vdots & & \vdots \\ x_{i1}^m & \cdots & x_{ij}^m & \cdots & x_{in}^m \end{bmatrix}_{(s,j)}$$

$$q'_{ij} = \frac{x_{ij}^s}{f'_{si}}, \quad \forall s, j \Leftrightarrow q'_{ij} = \frac{x_{ij}^s}{\sum_{j'} x_{ij'}^s}, \quad \forall s, j \Leftrightarrow \text{rank}([x_{ij}^s]_{(s,j)}) = 1.$$

Rank-1 on pq-formulation

These new non-linear equations enforce **flow consistency** requirements on the **source side**:

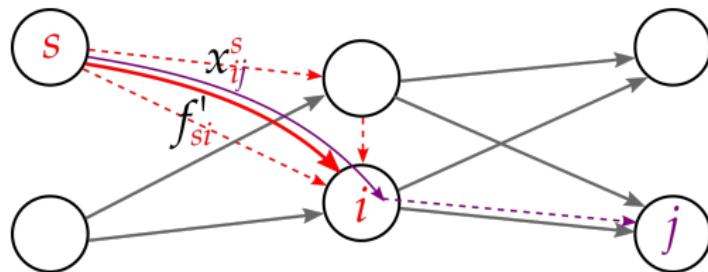
$$q'_{ij} = \frac{x_{ij}^s}{f'_{si}}, \quad \forall s, j \quad \Leftrightarrow \quad x_{ij}^s = q'_{ij} f'_{si}, \quad \forall s, j$$



Rank-1 on pq-formulation

These new non-linear equations enforce **flow consistency** requirements on the **source side**:

$$q'_{ij} = \frac{x_{ij}^s}{f'_{si}}, \quad \forall s, j \Leftrightarrow x_{ij}^s = q'_{ij} f'_{si}, \quad \forall s, j$$



By applying our convex hull result for $\mathcal{U}^{\text{row+}}$ to each $[x_{ij}^s]_{sj}, \forall s, j$:

- ▶ For SPP, we recover all the strength of tp-relaxation.
- ▶ For GPP, we partially recover the strength of tp-relaxation.

Most importantly, without having to define the x_{ij}^t variables of the tp-formulation.

New vs. known relaxations

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Formulation	Standard Pooling (SPP)	Generalized Pooling (GPP)
pq	Known [1]	Known [2]
tp	Known [2]	Known [3]
pq × tp	Known [3]	Known [3]
rank-1-pq	= pq ∩ tp	New
rank-1-tp	= pq ∩ tp	New

- [1]: Tawarmalani and Sahinidis [2002]
- [2]: Alfaki and Haugland [2013]
- [3]: Boland et al. [2016]

Computational results

Reporting the **best average duality gap** for each instance set:

Light-LP methods: pq, tp, rank-1-pq, rank-1-tp

Instance Set	Gap	Time	Method
Mining	4.14	1.76	rank-1-qp
Literature	18.11	0.02	rank-1-tp
Random	12.47	5.25	rank-1-qp

Medium-LP methods: $pq \cap tp$, $pq \times tp$, rank-1-pq \cap tp, pq \cap rank-1-tp, rank-1-pq \cap rank-1-tp

Instance Set	Gap	Time	Method
Mining	3.82	13.73	rank-1-qp \cap rank-1-tp
Literature	18.10	0.11	rank-1-qp \cap rank-1-tp
Random	12.28	27.34	rank-1-qp \cap rank-1-tp

Computational results

Reporting the **best average duality gap** for each instance set:

MILP methods: $\text{pq}(q^s)$, $\text{rank-1-pq}(q^s)$, $\text{rank-1-pq}(q')$, $\text{tp}(q^t)$,
 $\text{rank-1-tp}(q^t)$, $\text{rank-1-tp}(q')$

Instance Set	Gap	Time	Method
Mining	1.46	758.30	$\text{rank-1-qp}(q')$
Literature	0.49	150.29	$\text{rank-1-tp}(q')$
Random	7.37	927.50	$\text{rank-1-qp}(q')$

Set

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for QCQP

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Thank you!

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Duality gaps via LP for Mining instances

Inst	Paper [3]			pq		rank-1-pq		tp		rank-1-tp		pq ∩ tp		rank-1-pq ∩ tp		pq ∩ rank-1-tp		rank-1-pq ∩ rank-1-tp		pq × tp	
	Gap	Time	Gap	Time	Gap	Time	Gap	Time	Gap	Time	Gap	Time	Gap	Time	Gap	Time	Gap	Time	Gap	Time	Gap
2009H2	37.00	0.05	7.13	0.53	4.06	1.12	4.58	1.23	4.58	9.28	4.27	5.13	3.59	5.89	4.27	7.16	3.59	6.64	4.02	1697.27	
2009Q3	29.36	0.03	3.84	0.08	1.59	0.23	2.16	0.08	2.16	0.17	2.01	0.34	1.45	0.69	2.01	0.61	1.45	0.47	1.96	1.23	
2009Q4	41.86	0.02	24.93	0.13	14.49	0.57	17.11	0.30	17.11	0.78	16.94	1.20	13.77	1.75	16.94	1.36	13.77	1.98	10.84	22.59	
2010Y	26.01	0.25	10.37	5.16	8.58	10.99	8.91	33.62	8.91	61.63	8.87	101.08	8.14	86.91	8.87	141.66	8.14	92.30	(8.14)	86.91	
2010H1	32.42	0.08	14.64	1.02	13.42	1.95	13.38	8.97	13.38	6.23	13.32	10.09	12.77	17.47	13.32	18.48	12.77	15.73	12.78	285.80	
2010H2	14.83	0.09	3.94	0.81	1.84	2.09	2.45	3.27	2.45	5.34	2.45	10.60	1.80	16.55	2.45	15.61	1.80	14.89	2.26	480.52	
2010Q1	19.74	0.03	4.35	0.26	3.90	0.75	4.31	0.55	4.31	0.66	4.14	2.03	3.88	1.81	4.14	2.50	3.88	2.36	3.94	13.33	
2010Q2	35.38	0.03	21.41	0.11	18.59	0.61	18.58	0.27	18.58	0.61	18.55	1.28	17.90	1.39	18.55	1.38	17.90	0.98	18.26	5.66	
2010Q3	20.33	0.02	3.84	0.09	1.54	4.05	2.56	0.13	2.56	0.39	2.56	0.61	1.49	0.94	2.56	1.11	1.49	0.98	2.23	4.20	
2010Q4	28.62	0.05	11.43	0.12	9.95	0.36	9.43	0.58	9.43	0.94	9.14	1.00	8.83	1.37	9.14	1.48	8.83	1.56	8.75	47.97	
2011Y	19.30	0.14	2.45	2.83	1.50	7.64	1.43	7.95	1.43	16.39	1.41	57.67	1.25	322.28	1.41	60.89	1.25	88.55	1.28	1161.44	
2011H1	9.07	0.06	2.30	0.48	1.40	0.91	1.24	0.83	1.24	1.91	1.23	2.36	1.13	1.95	1.23	2.77	1.13	5.39	1.10	14.53	
2011H2	22.21	0.06	2.17	0.77	1.43	1.56	1.37	1.53	1.37	2.38	1.34	7.75	1.26	10.12	1.34	12.62	1.26	21.31	1.24	172.06	
2011Q1	10.51	0.02	1.78	0.04	1.03	0.15	0.83	0.11	0.83	0.34	0.82	0.52	0.72	0.53	0.82	0.47	0.72	0.77	0.72	1.16	
2011Q2	4.04	0.02	3.19	0.05	2.29	0.16	2.53	0.12	2.53	0.40	2.53	0.34	2.10	0.45	2.53	0.63	2.10	0.98	2.24	3.75	
2011Q3	10.04	0.00	0.39	0.02	0.07	0.03	0.15	0.03	0.15	0.06	0.15	0.14	0.07	0.08	0.15	0.11	0.07	0.14	0.15	0.25	
2011Q4	16.09	0.02	1.01	0.06	0.57	0.10	0.99	0.09	0.99	0.30	0.90	0.53	0.56	0.73	0.90	0.63	0.56	0.97	0.83	3.08	
2012Y	8.20	0.11	2.79	1.78	1.72	5.61	2.37	7.56	2.37	16.38	2.19	21.64	1.57	30.39	2.19	29.50	1.57	41.34	(1.57)	30.39	
2012H1	4.99	0.08	3.35	1.27	2.20	2.50	3.00	2.34	3.00	5.17	2.77	10.77	2.02	16.66	2.77	13.19	2.02	28.83	(2.02)	16.66	
2012H2	10.21	0.02	0.97	0.11	0.42	0.47	0.74	0.19	0.74	0.33	0.66	1.02	0.42	0.72	0.66	0.91	0.42	1.33	0.64	4.75	
2012Q1	13.93	0.01	9.31	0.03	4.43	0.08	8.66	0.09	8.66	0.22	8.25	0.41	4.16	0.33	8.25	0.31	4.16	0.75	8.13	2.37	
2012Q2	1.68	0.02	0.70	0.03	0.30	0.09	0.49	0.08	0.49	0.23	0.49	0.34	0.21	0.28	0.49	0.53	0.21	0.41	0.49	0.95	
2012Q3	5.92	0.02	1.13	0.05	0.56	0.13	0.99	0.06	0.99	0.20	0.92	0.38	0.56	0.33	0.92	0.42	0.56	0.86	0.89	1.52	
2012Q4	25.81	0.00	4.91	0.02	3.50	0.02	1.91	0.03	1.91	0.03	1.91	0.05	1.91	0.06	1.91	0.08	1.91	0.09	1.91	0.22	
Ave.	18.65	0.05	5.93	0.66	4.14	1.76	4.59	2.92	4.59	5.43	4.49	9.89	3.82	21.65	4.49	13.10	3.82	13.73	4.02	169.11	

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Inst	Paper [3]		rank-1-pq ∩ tp		pq ∩ rank-1-tp		rank-1-pq ∩ rank-1-tp		pq × tp	
	Gap	Time	Gap	Time	Gap	Time	Gap	Time	Gap	Time
2009H2	37.00	0.05	3.59	5.89	4.27	7.16	3.59	6.64	4.02	1697.27
2009Q3	29.36	0.03	1.45	0.69	2.01	0.61	1.45	0.47	1.96	1.23
2009Q4	41.86	0.02	13.77	1.75	16.94	1.36	13.77	1.98	10.84	22.59
2010Y	26.01	0.25	8.14	86.91	8.87	141.66	8.14	92.30	(8.14)	86.91
2010H1	32.42	0.08	12.77	17.47	13.32	18.48	12.77	15.73	12.78	285.80
2010H2	14.83	0.09	1.80	16.55	2.45	15.61	1.80	14.89	2.26	480.52
2010Q1	19.74	0.03	3.88	1.81	4.14	2.50	3.88	2.36	3.94	13.33
2010Q2	35.38	0.03	17.90	1.39	18.55	1.38	17.90	0.98	18.26	5.66
2010Q3	20.33	0.02	1.49	0.94	2.56	1.11	1.49	0.98	2.23	4.20
2010Q4	28.62	0.05	8.83	1.37	9.14	1.48	8.83	1.56	8.75	47.97
2011Y	19.30	0.14	1.25	322.28	1.41	60.89	1.25	88.55	1.28	1161.44
2011H1	9.07	0.06	1.13	1.95	1.23	2.77	1.13	5.39	1.10	14.53
2011H2	22.21	0.06	1.26	10.12	1.34	12.62	1.26	21.31	1.24	172.06
2011Q1	10.51	0.02	0.72	0.53	0.82	0.47	0.72	0.77	0.72	1.16
2011Q2	4.04	0.02	2.10	0.45	2.53	0.63	2.10	0.98	2.24	3.75
2011Q3	10.04	0.00	0.07	0.08	0.15	0.11	0.07	0.14	0.15	0.25
2011Q4	16.09	0.02	0.56	0.73	0.90	0.63	0.56	0.97	0.83	3.08
2012Y	8.20	0.11	1.57	30.39	2.19	29.50	1.57	41.34	(1.57)	30.39
2012H1	4.99	0.08	2.02	16.66	2.77	13.19	2.02	28.83	(2.02)	16.66
2012H2	10.21	0.02	0.42	0.72	0.66	0.91	0.42	1.33	0.64	4.75
2012Q1	13.93	0.01	4.16	0.33	8.25	0.31	4.16	0.75	8.13	2.37
2012Q2	1.68	0.02	0.21	0.28	0.49	0.53	0.21	0.41	0.49	0.95
2012Q3	5.92	0.02	0.56	0.33	0.92	0.42	0.56	0.86	0.89	1.52
2012Q4	25.81	0.00	1.91	0.06	1.91	0.08	1.91	0.09	1.91	0.22
Ave.	18.65	0.05	3.82	21.65	4.49	13.10	3.82	13.73	4.02	169.11

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Inst	pq			rank-1-pq			tp			rank-1-tp			pq ∩ tp			rank-1-pq ∩ tp			pq ∩ rank-1-tp			rank-1-pq ∩ rank-1-tp			pq × tp		
	Gap	Time		Gap	Time		Gap	Time		Gap	Time		Gap	Time		Gap	Time		Gap	Time		Gap	Time		Gap	Time	
L1	1.01	0.00	0.86	0.00	1.01	0.00	1.01	0.00	1.01	0.02	0.86	0.00	1.01	0.00	0.86	0.00	1.01	0.00	0.86	0.00	1.01	0.00	0.86	0.00	1.01	0.00	
L2	55.24	0.00	55.24	0.02	55.74	0.00	52.83	0.00	55.24	0.00	55.24	0.02	52.83	0.02	52.83	0.00	52.83	0.00	52.83	0.00	55.24	0.02	52.83	0.00	55.24	0.02	
L3	4.55	0.00	4.55	0.00	4.55	0.00	4.55	0.00	4.55	0.00	4.55	0.02	4.55	0.00	4.55	0.00	4.55	0.00	4.55	0.00	4.55	0.03	4.55	0.03	4.55	0.03	
L4	2.45	0.02	2.45	0.06	2.45	0.00	2.45	0.00	2.45	0.02	2.45	0.05	2.45	0.03	2.45	0.09	2.45	0.16	2.45	0.16	2.45	0.16	2.45	0.16	2.45	0.16	
L5	10.80	0.02	10.80	0.00	11.26	0.00	9.60	0.02	10.80	0.02	10.80	0.02	9.60	0.02	9.60	0.03	9.60	0.03	9.60	0.03	10.80	0.03	9.60	0.03	10.80	0.03	
L6	22.22	0.00	22.06	0.00	20.37	0.00	20.37	0.00	20.37	0.00	20.37	0.00	20.37	0.00	20.37	0.00	20.37	0.00	20.37	0.00	20.37	0.00	20.37	0.00	20.37	0.00	
L12	25.00	0.02	25.00	0.00	25.00	0.00	25.00	0.00	25.00	0.00	25.00	0.00	25.00	0.00	25.00	0.00	25.00	0.00	25.00	0.00	25.00	0.00	25.00	0.00	25.00	0.00	
L13	66.67	0.00	66.67	0.00	66.67	0.00	66.67	0.00	66.67	0.00	66.67	0.00	66.67	0.00	66.67	0.00	66.67	0.00	66.67	0.00	66.67	0.00	66.67	0.00	66.67	0.00	
L14	16.67	0.00	16.67	0.00	16.67	0.00	6.67	0.00	16.67	0.00	6.67	0.00	6.67	0.00	6.67	0.00	6.67	0.00	6.67	0.00	6.67	0.00	6.67	0.00	6.67	0.00	
L15	37.41	0.00	25.88	0.00	25.88	0.00	25.88	0.00	25.88	0.02	25.88	0.00	25.88	0.00	25.88	0.02	25.88	0.00	25.88	0.02	25.88	0.00	25.88	0.00	25.88	0.00	
C2	1.23	0.03	1.23	0.02	1.23	0.03	1.23	0.03	1.23	0.08	1.23	0.08	1.23	0.09	1.23	0.06	1.23	0.33	1.23	0.06	1.23	0.06	1.23	0.06	1.23	0.06	
D1	1.06	0.09	1.06	0.25	1.06	0.12	1.06	0.22	1.06	0.55	1.06	0.94	1.06	0.94	1.06	0.94	1.06	0.94	1.06	0.94	1.06	0.94	1.06	0.94	1.06	3.92	
Ave.	20.36	0.01	19.37	0.03	19.32	0.01	18.11	0.02	19.24	0.06	19.23	0.09	18.11	0.09	18.10	0.11	19.24	0.37									

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Duality gaps via LP for Random instances

Inst	pq		rank-1-pq		tp		rank-1-tp		pq \cap tp		rank-1-pq \cap tp		pq \cap rank-1-tp		rank-1-pq \cap rank-1-tp		pq \times tp	
	Gap	Time	Gap	Time	Gap	Time	Gap	Time	Gap	Time								
F1	3.79	0.02	3.79	0.02	5.02	0.03	4.09	0.06	3.79	0.05	3.79	0.12	3.79	0.09	3.79	0.09	3.79	0.22
F2	4.81	0.39	4.60	1.02	5.15	0.41	4.50	0.89	4.30	1.27	4.29	3.43	4.28	3.06	4.28	5.98	4.29	13.70
F3	13.52	0.27	13.19	1.27	14.57	0.70	14.57	1.41	13.19	1.55	13.19	2.82	13.19	2.00	13.19	6.44	13.19	22.39
F4	0.00	0.14	0.00	2.48	0.00	1.03	0.00	1.72	0.00	0.31	0.00	4.80	0.00	3.37	0.00	6.25	0.00	6.61
F5	14.58	0.42	11.02	1.81	13.06	0.34	11.96	1.06	11.71	1.19	10.97	3.59	11.66	3.03	10.97	6.19	11.65	22.69
F6	10.69	0.31	10.03	1.73	12.25	0.27	10.45	1.17	10.15	3.19	9.92	8.11	9.97	6.56	9.91	12.42	9.94	60.92
F7	33.72	1.05	33.09	3.25	34.91	1.20	34.04	5.08	33.09	5.31	33.09	12.50	33.05	12.45	33.05	22.45	33.09	86.13
F8	17.15	0.58	16.90	1.77	17.46	0.53	17.06	1.81	16.90	4.22	16.90	8.47	16.90	7.89	16.90	14.05	16.90	22.58
F9	18.13	0.50	17.17	1.03	20.75	0.38	17.78	1.15	17.24	3.48	17.15	8.91	17.16	5.77	17.15	16.30	17.16	19.64
F10	7.84	0.31	7.81	1.30	8.08	0.61	7.86	1.41	7.81	2.66	7.81	7.27	7.81	4.25	7.81	9.17	7.81	12.98
F11	5.43	0.02	5.32	0.05	5.71	0.03	5.20	0.08	5.28	0.06	5.28	0.16	5.19	0.16	5.19	0.23	5.28	0.39
F12	4.57	0.14	4.54	0.30	5.14	0.19	4.78	0.34	4.48	1.06	4.48	1.69	4.47	1.64	4.47	2.31	4.48	8.73
F13	7.20	0.67	7.15	2.11	8.12	0.69	7.92	1.81	7.17	1.86	7.14	4.45	7.16	3.84	7.13	7.48	7.16	32.11
F14	0.00	0.08	0.00	0.48	0.00	0.30	0.00	0.80	0.00	0.95	0.00	2.00	0.00	2.02	0.00	1.75	0.00	3.83
F15	17.95	0.23	17.88	0.78	18.82	0.39	18.33	1.61	16.36	1.84	16.33	2.77	16.36	3.03	16.33	6.06	16.36	14.53
F16	4.64	0.06	4.29	0.09	4.41	0.05	4.31	0.11	4.28	0.28	4.26	0.42	4.28	0.38	4.26	0.64	4.27	2.31
F17	10.24	0.02	10.24	0.05	9.63	0.06	9.62	0.11	9.62	0.12	9.62	0.16	9.62	0.17	9.62	0.27	9.62	0.64
F18	16.63	0.09	16.63	0.34	16.63	0.19	16.63	0.56	16.63	0.80	16.63	0.73	16.63	1.08	16.63	2.53	16.63	1.87
F19	1.06	0.02	1.06	0.02	2.73	0.03	1.06	0.03	1.06	0.03	1.06	0.03	1.06	0.05	1.06	0.09	1.06	0.08
F20	12.74	0.11	12.11	0.16	13.38	0.14	12.28	0.31	11.52	0.91	11.48	0.88	11.50	1.00	11.46	1.34	11.52	2.63
F21	26.02	12.38	25.57	55.88	26.49	8.72	25.71	50.89	25.42	70.72	25.40	165.03	25.37	133.67	25.36	310.98	(25.36)	310.98
F22	22.64	0.23	22.17	0.55	23.43	0.34	22.61	0.66	21.91	1.42	21.91	3.19	21.91	2.86	21.91	4.34	21.91	10.83
F23	43.92	10.64	43.58	49.09	47.04	12.15	45.05	49.55	43.39	53.61	43.35	493.14	43.16	224.12	43.13	207.30	(43.13)	207.30
F24	11.19	0.22	11.19	0.50	11.19	1.02	11.18	2.23	11.19	2.23	11.19	5.81	11.18	7.45	11.18	11.38	11.19	5.44
Ave.	12.85	1.20	12.47	5.25	13.50	1.24	12.79	5.20	12.35	6.67	12.30	30.85	12.32	17.91	12.28	27.34	12.32	36.23

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Inst	pq(q^s)		rank-1-pq(q^s)		rank-1-pq(q')		tp(q^t)		rank-1-tp(q^t)		rank-1-tp(q')	
	Gap	Time	Gap	Time	Gap	Time	Gap	Time	Gap	Time	Gap	Time
2009H2	3.64	1800.17	2.69	1800.18	1.61	1800.09	2.08	1800.37	2.08	1800.27	2.65	1800.14
2009Q3	0.80	23.67	0.54	16.45	0.20	10.64	0.21	12.56	0.22	18.12	0.53	8.56
2009Q4	8.82	1800.05	8.41	1800.05	3.45	1558.98	4.93	1800.06	4.74	1800.06	4.69	1800.02
2010Y	9.13	1800.27	8.27	1801.63	8.09	1800.63	8.06	1800.33	8.24	1800.25	8.44	1800.14
2010H1	13.31	1800.07	11.71	1800.15	6.92	1800.23	9.05	1800.09	8.55	1800.23	8.41	1800.09
2010H2	1.22	1800.11	0.84	1800.11	1.03	1800.33	1.00	1800.19	0.93	1800.11	2.19	1800.05
2010Q1	2.89	232.87	2.75	379.08	1.64	134.11	2.25	665.41	2.25	1279.26	2.32	199.84
2010Q2	12.37	1028.67	11.64	1594.03	2.95	232.52	4.89	1800.03	4.85	1800.05	4.23	422.70
2010Q3	0.94	39.75	0.70	40.09	0.38	14.31	0.70	33.23	0.70	37.08	0.80	48.44
2010Q4	6.38	132.55	5.28	160.81	1.97	772.50	3.84	231.61	3.84	239.50	4.95	701.95
2011Y	1.56	1800.09	1.28	1800.19	1.20	1800.11	1.17	1800.16	1.13	1800.20	1.28	1800.84
2011H1	0.64	1800.09	0.54	1800.08	0.18	871.16	0.41	1800.05	0.58	1800.14	0.31	287.62
2011H2	1.37	1800.06	1.26	1800.09	0.37	1800.09	1.07	1800.09	1.05	1800.12	0.66	1800.05
2011Q1	0.31	18.62	0.26	36.94	0.12	57.71	0.22	20.05	0.22	24.11	0.22	29.84
2011Q2	1.08	90.28	1.01	38.64	0.49	36.70	0.89	62.84	0.89	111.09	0.69	58.31
2011Q3	0.05	0.66	0.03	0.77	0.01	1.13	0.04	1.33	0.04	1.81	0.06	0.83
2011Q4	0.18	26.39	0.15	31.48	0.10	8.00	0.24	45.20	0.24	39.56	0.17	49.69
2012Y	1.85	1800.06	1.43	1800.09	1.20	1802.70	1.37	1800.08	1.37	1800.06	1.95	1800.13
2012H1	2.22	1800.03	1.72	1800.08	1.34	1800.04	1.14	1800.06	1.39	1800.08	2.48	1800.11
2012H2	0.19	39.77	0.15	52.55	0.07	52.66	0.18	55.59	0.18	60.58	0.19	72.69
2012Q1	3.35	22.00	2.15	10.64	0.91	11.08	1.32	9.00	1.32	23.47	1.78	23.52
2012Q2	0.16	12.02	0.12	10.39	0.12	3.97	0.16	18.55	0.16	19.77	0.11	22.23
2012Q3	0.29	19.80	0.23	28.28	0.07	28.56	0.18	20.72	0.18	48.72	0.21	33.38
2012Q4	1.77	4.73	1.65	4.16	0.70	1.03	0.44	2.31	0.44	2.22	0.33	8.56
Ave.	3.10	820.53	2.70	850.29	1.46	758.30	1.91	874.16	1.90	904.45	2.07	757.07

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Inst	pq(q^s)		rank-1-pq(q^s)		rank-1-pq(q')		tp(q^t)		rank-1-tp(q^t)		rank-1-tp(q')	
	Gap	Time	Gap	Time	Gap	Time	Gap	Time	Gap	Time	Gap	Time
L1	0.33	0.03	0.33	0.05	0.26	0.05	0.36	0.05	0.36	0.05	0.59	0.03
L2	2.96	1.12	2.96	1.70	15.66	1.38	2.70	0.20	2.70	0.09	1.55	0.28
L3	2.96	0.50	2.96	0.86	3.58	0.37	1.97	0.08	1.97	0.09	1.55	0.17
L4	1.96	16.64	1.96	19.78	2.45	1.36	0.47	0.49	0.47	0.28	0.26	2.14
L5	2.88	1.17	2.88	1.58	4.19	12.78	0.96	0.81	0.96	0.68	0.05	0.14
L6	0.00	0.14	0.00	0.17	0.00	0.11	0.00	0.04	0.00	0.02	0.00	0.06
L12	0.00	0.09	0.00	0.11	0.00	0.12	0.00	0.02	0.00	0.02	0.00	0.03
L13	0.00	0.08	0.00	0.13	0.00	0.20	0.00	0.02	0.00	0.03	0.00	0.03
L14	0.00	0.10	0.00	0.11	4.76	0.17	1.91	0.02	1.91	0.04	0.00	0.03
L15	0.77	0.14	0.68	0.12	1.20	0.08	1.20	0.03	1.20	0.06	0.68	0.09
C2	0.14	0.64	0.14	0.72	0.10	0.59	0.10	0.55	0.10	0.69	0.14	0.47
D1	1.06	1800.03	1.06	1800.00	1.04	1800.02	1.02	1800.02	1.03	1800.03	1.04	1800.02
Ave.	1.09	151.72	1.08	152.11	2.77	151.44	0.89	150.19	0.89	150.17	0.49	150.29

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Inst	pq(q^s)		rank-1-pq(q^s)		rank-1-pq(q')		tp(q^t)		rank-1-tp(q^t)		rank-1-tp(q')	
	Gap	Time	Gap	Time	Gap	Time	Gap	Time	Gap	Time	Gap	Time
F1	2.04	7.06	2.04	9.52	2.30	4.14	2.30	6.31	2.30	4.13	2.26	10.23
F2	3.01	1800.03	2.99	1800.02	2.39	1800.08	2.63	1800.08	2.59	1800.08	2.63	1800.03
F3	3.42	1800.05	4.36	1800.05	2.01	526.69	7.50	1800.05	8.88	1800.03	5.42	1800.09
F4	0.00	2.44	0.00	3.19	0.00	3.91	0.00	3.20	0.00	3.78	0.00	4.02
F5	7.26	1800.06	7.90	1800.03	6.52	1800.03	6.78	1800.06	7.55	1800.05	6.27	1800.06
F6	8.25	1800.02	8.38	1800.03	8.12	1800.05	9.11	1800.05	8.29	1800.05	8.19	1800.06
F7	24.44	1800.05	25.67	1800.06	25.96	1800.05	24.79	1800.06	26.83	1800.04	22.87	1800.08
F8	10.40	1800.06	10.81	1800.05	9.53	1800.05	7.66	1800.08	8.91	1800.06	10.55	1800.03
F9	8.09	1800.06	8.29	1800.06	6.78	1800.05	8.25	1800.06	7.88	1800.06	6.37	1800.12
F10	3.08	1800.14	3.65	1800.14	4.23	726.17	4.69	764.77	4.69	653.10	2.47	1110.62
F11	1.25	23.02	1.25	26.14	1.30	63.05	1.47	57.05	1.47	71.55	0.84	9.50
F12	1.75	1800.05	1.62	1800.07	1.11	431.17	1.57	1800.14	1.61	1800.12	1.49	1800.16
F13	4.54	1800.05	4.22	1800.05	1.67	1751.19	3.81	1800.10	3.79	1800.06	4.40	1800.05
F14	0.00	1.09	0.00	0.69	0.00	0.88	0.00	1.33	0.00	2.36	0.00	3.08
F15	13.15	1800.03	12.73	1800.03	12.22	1800.03	12.97	1800.03	13.52	1800.05	12.43	1800.05
F16	1.37	240.83	1.35	347.73	1.16	161.31	1.15	573.34	1.09	1460.55	1.48	39.92
F17	1.94	10.59	1.94	19.34	1.82	6.59	1.83	6.95	1.83	10.22	2.50	10.50
F18	1.79	61.87	1.79	42.75	1.16	36.03	1.17	21.73	1.17	27.42	2.64	16.83
F19	0.00	0.75	0.00	0.56	0.00	0.38	0.00	0.39	0.00	0.39	0.00	0.44
F20	3.47	1800.11	3.50	1800.05	2.49	535.50	2.29	631.09	2.29	1337.64	2.23	308.12
F21	26.01	1800.05	25.46	1800.08	25.55	1800.06	26.20	1800.05	25.69	1800.09	25.46	1800.11
F22	10.40	1800.03	11.68	1800.03	11.11	1800.05	12.60	1800.04	12.95	1800.08	7.26	1800.13
F23	43.65	1800.06	43.58	1800.11	43.58	1800.09	46.52	1800.05	45.03	1800.09	44.69	1800.09
F24	5.96	46.45	5.96	39.28	5.88	12.58	5.99	12.37	5.99	28.78	5.92	20.03
Ave.	7.72	1141.46	7.88	1145.42	7.37	927.50	7.97	1061.64	8.10	1125.03	7.43	1038.93

Proof of Thm 1 (sketch)

Proof of Case 5

For simplicity, $n_{q+} = 2$, $n_{q-} = 1$, $n_I = 0$: $w_1^2 + w_2^2 - x_1^2 = d$.

Let (a_1, a_2, b_1) be a point in the surface, i.e.,

$$a_1^2 + a_2^2 - b_1^2 = d.$$

We show that there exist u_1, u_2, v_1 such that the line

$$\{(a_1, a_2, b_1) + \lambda(u_1, u_2, v_1) \mid \lambda \in \mathbb{R}\}$$

is entirely contained in the surface:

$$(a_1 + \lambda u_1)^2 + (a_2 + \lambda u_2)^2 - (b_1 + \lambda v_1)^2 = d \quad \forall \lambda \in \mathbb{R}.$$

Proof of Thm 1 (sketch)

Proof of Case 5

Then, $\forall \lambda \in \mathbb{R}$,

$$d = (a_1 + \lambda u_1)^2 + (a_2 + \lambda u_2)^2 - (b_1 + \lambda v_1)^2$$

$$d = a_1^2 + a_2^2 - b_1^2 + \lambda^2(u_1^2 + u_2^2 - v_1^2) + 2\lambda(a_1 u_1 + a_2 u_2 - b_1 v_1)$$

$$0 = \lambda^2(u_1^2 + u_2^2 - v_1^2) + 2\lambda(a_1 u_1 + a_2 u_2 - b_1 v_1)$$

$$0 = \lambda(u_1^2 + u_2^2 - v_1^2) + 2(a_1 u_1 + a_2 u_2 - b_1 v_1).$$

Therefore,

$$\begin{cases} u_1^2 + u_2^2 - v_1^2 = 0 \\ a_1 u_1 + a_2 u_2 - b_1 v_1 = 0. \end{cases}$$

Setting $v_1 = 1$:

$$\begin{cases} u_1^2 + u_2^2 = 1 \\ a_1 u_1 + a_2 u_2 = b_1. \end{cases}$$

$$a_1^2 + a_2^2 - b_1^2 = d \Rightarrow a_1^2 + a_2^2 = d + b_1^2 \geq b_1^2 \Rightarrow \frac{|b_1|}{\|a\|_2} \leq 1.$$