

# THE MAXIMUM EDGE-DISJOINT PATHS PROBLEM IN BOUNDED TREEWIDTH GRAPHS

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# Maximum Edge-Disjoint Paths problem

(MEDP for short)

- Input:**
- a graph  $G$ ,
  - capacities  $c : E(G) \rightarrow \mathbb{N}$ ,
  - pairs  $(s_i, t_i)$  of *commodities*, with weights  $w_i$ .

- Output:**
- $\mathcal{P}$ , family of  $(s_i, t_i)$ -paths in  $G$ ,
  - at most  $c(e)$  paths of  $\mathcal{P}$  contain  $e$  ( $e \in E(G)$ ).

**Goal:** Maximize  $\sum_{i \in I_{\mathcal{P}}} w_i$ ,  
where  $I_{\mathcal{P}} = \{i : \text{there is an } (s_i, t_i)\text{-path in } \mathcal{P}\}$ .

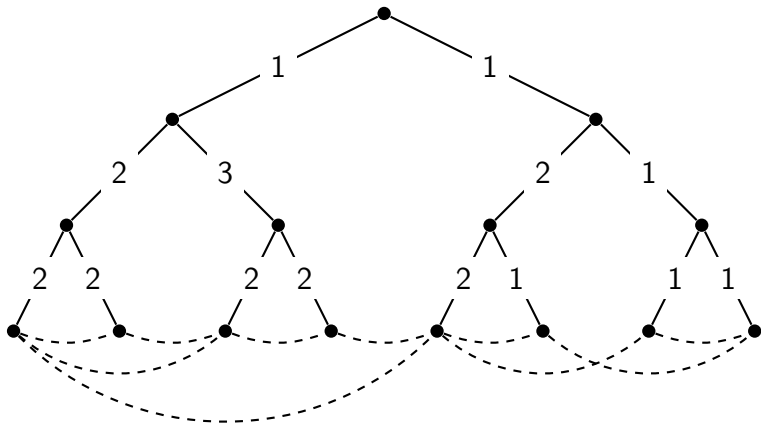
# General results

MEDP...

- is APX-hard, even in trees (Garg, Vazirani, Yannakakis, 1997),
- is hard to approximate within  $\Omega(m^{\frac{1}{2}-\epsilon})$  in directed graphs (Guruswami, Khanna, Rajaraman, Shepherd, Yannakakis, 1999),
- is hard to approximate within  $\Omega(\log^{1/2-\epsilon} n)$  in undirected graphs (Andrews, Chuzhoy, Khanna, Zhang, 2005),
- has  $\Omega(\sqrt{n})$  integrality gap, for the natural LP (Guruswami, . . .),  $O(\sqrt{n})$  in undirected graphs (Chekuri, Khanna, Shepherd, 2005)
- has approximation ratio  $O(\sqrt{m})$  (Kleinberg, 1996).

# 2-approximation in trees

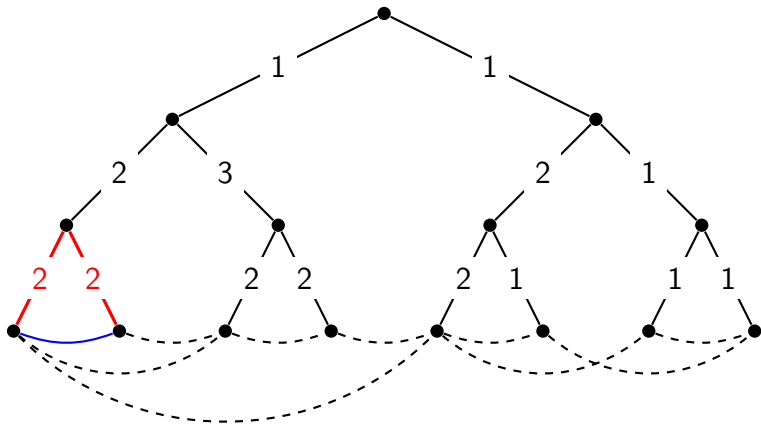
(Garg, Vazirani, Yannakakis, 1997)



Idea: route the deepest possible demand.

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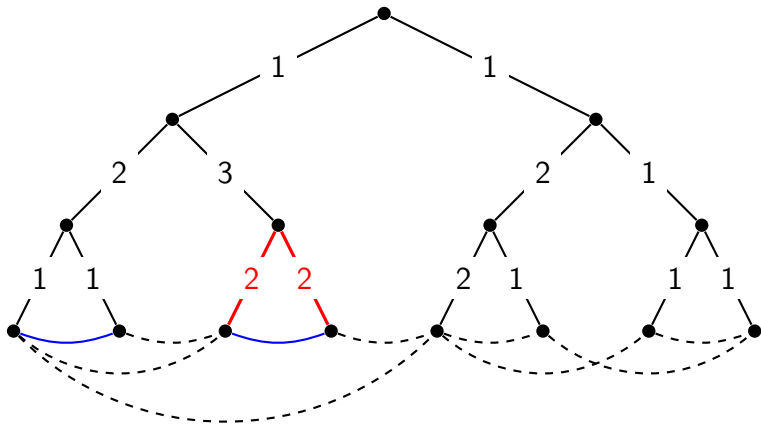
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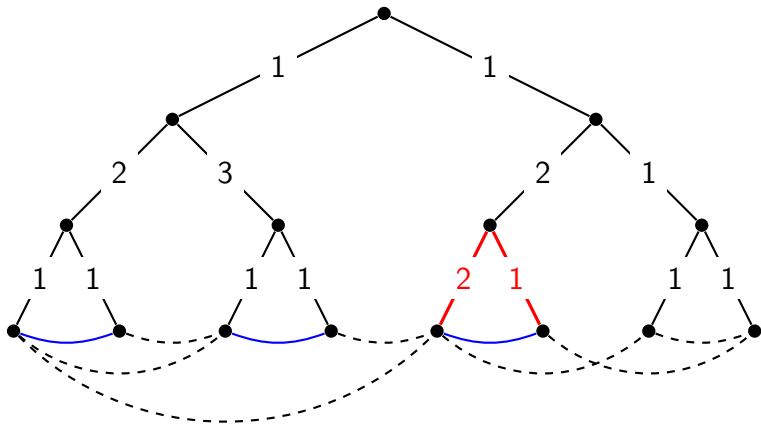
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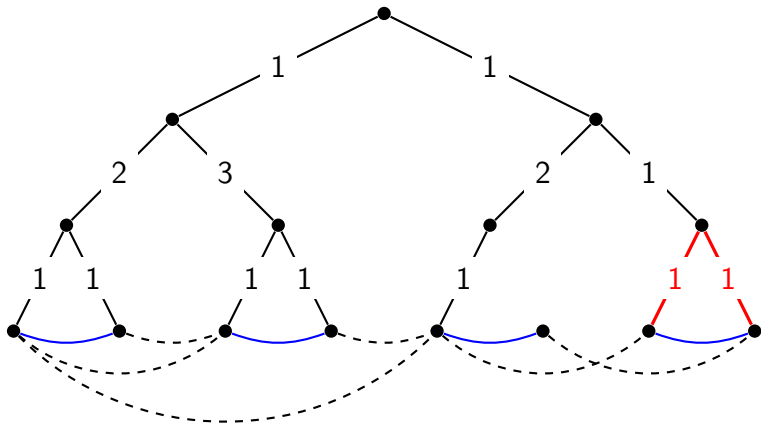
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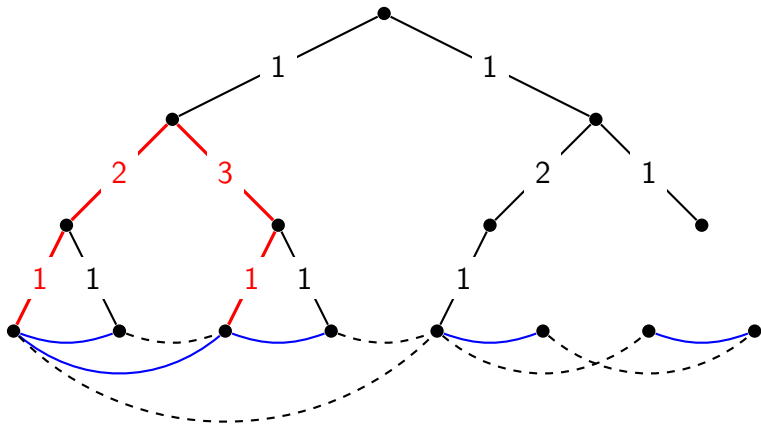


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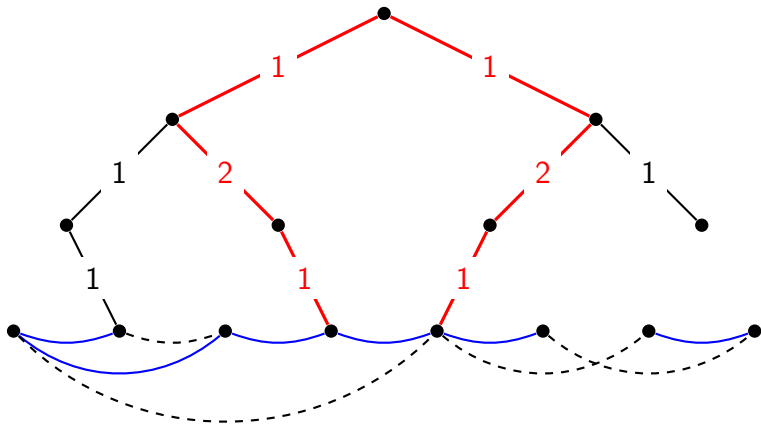
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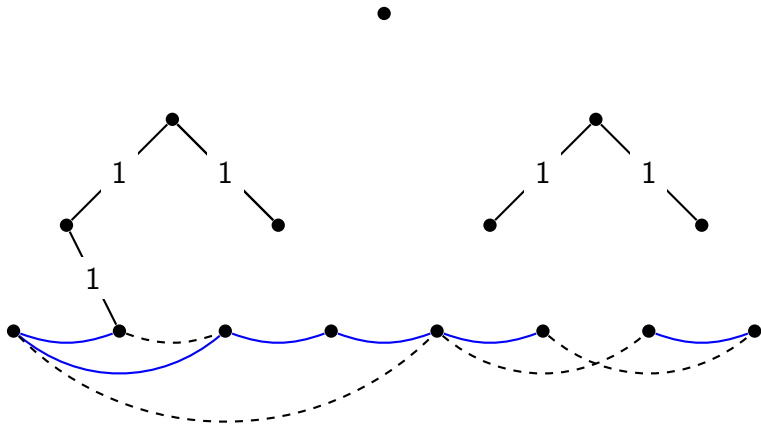
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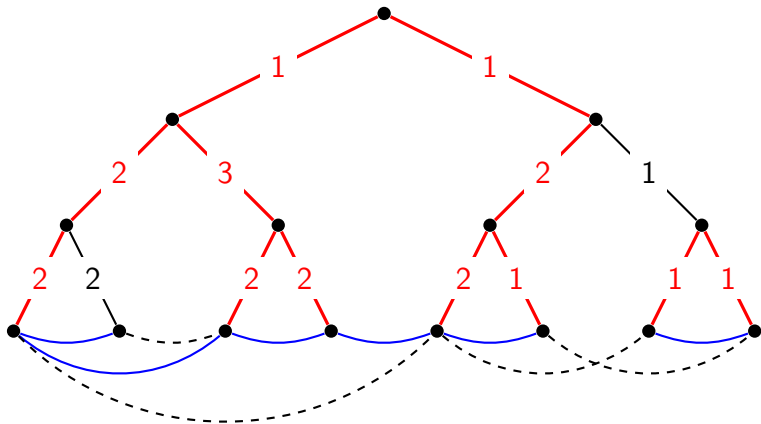
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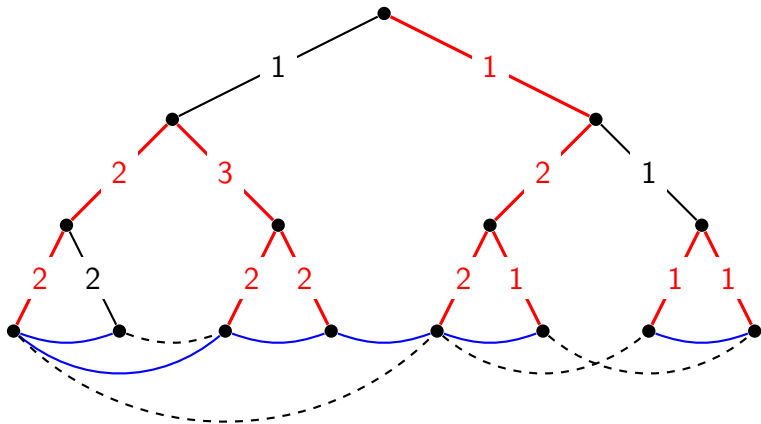
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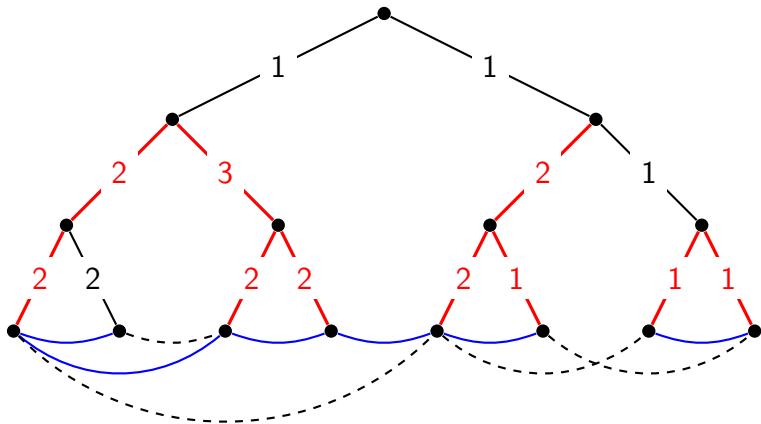
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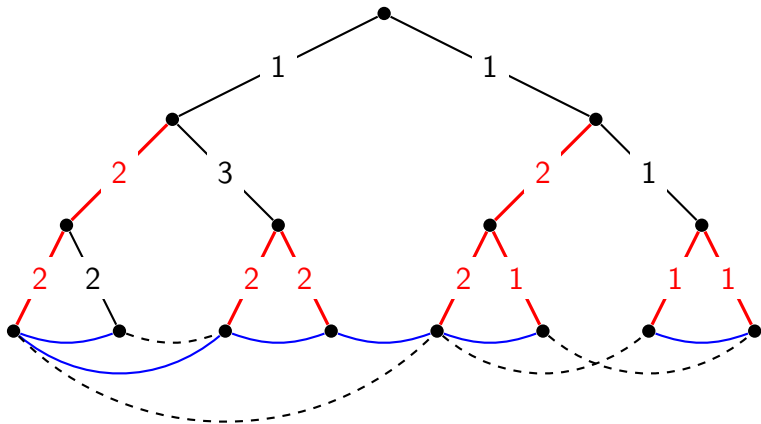
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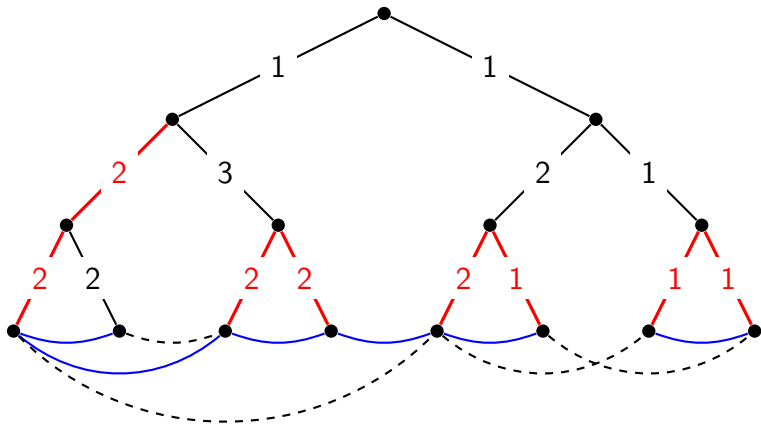
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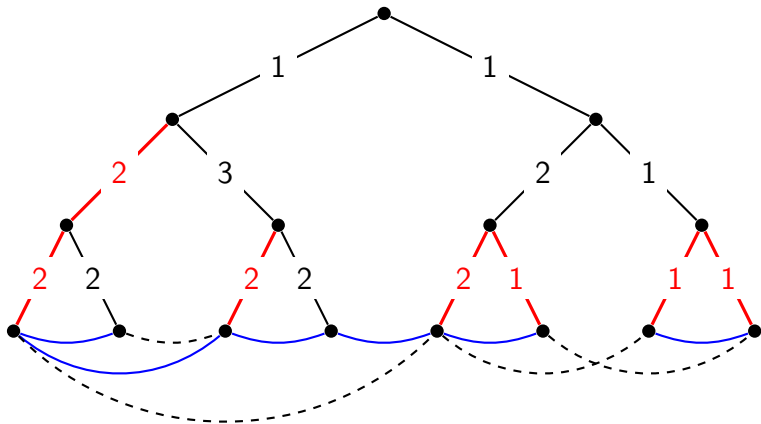


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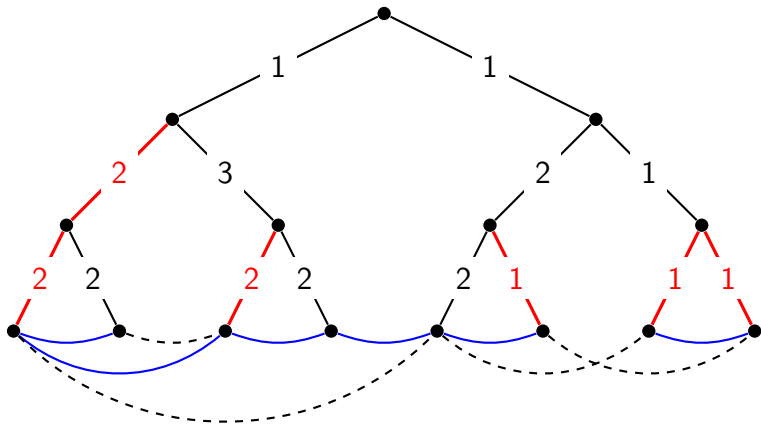
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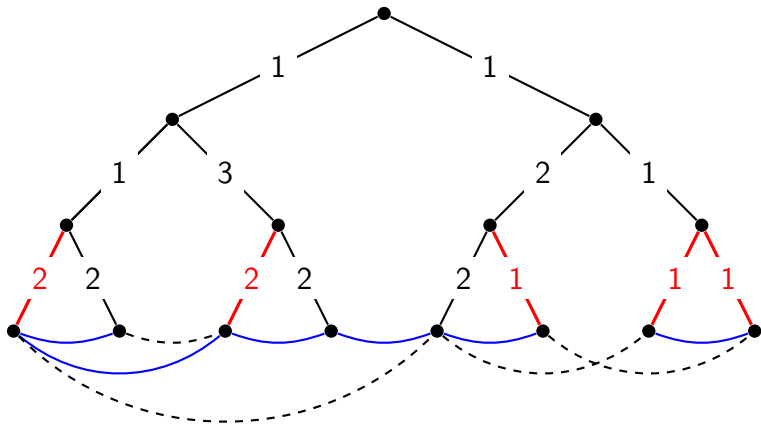
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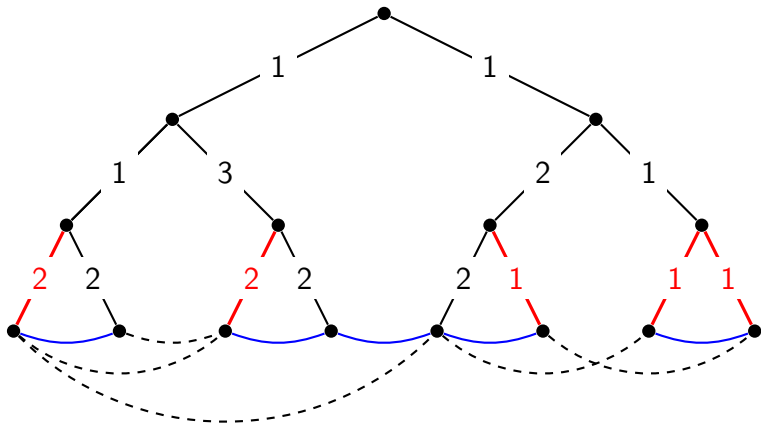
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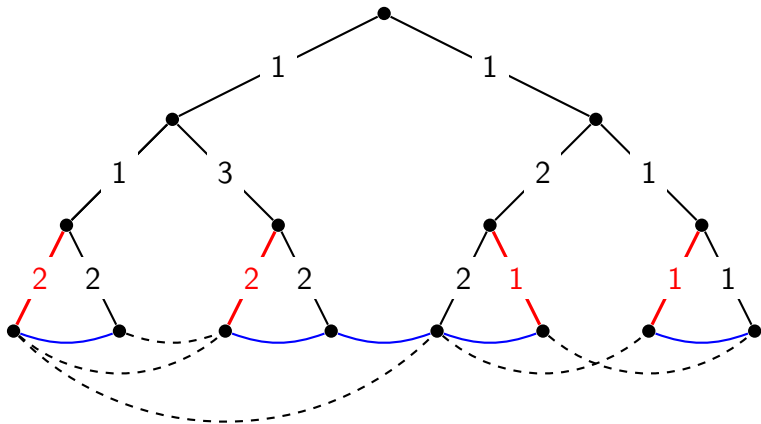
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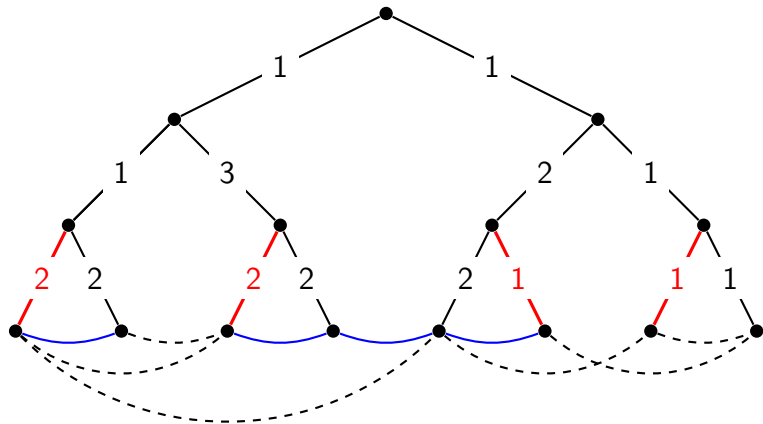
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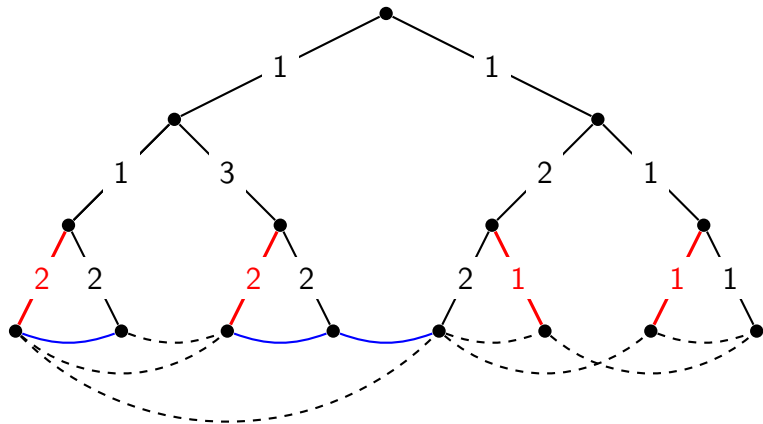
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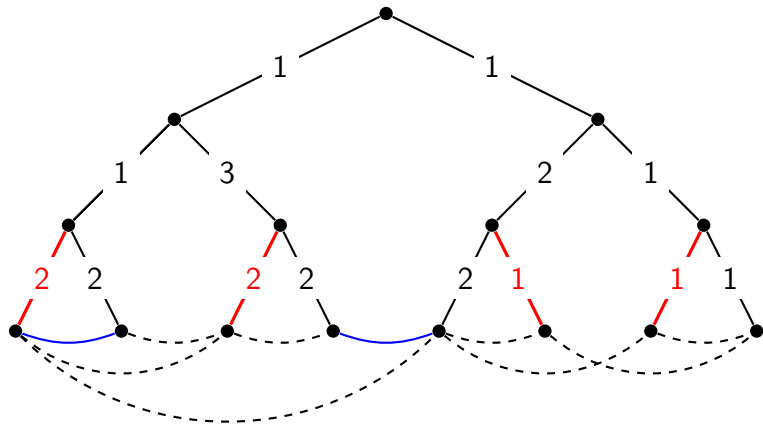
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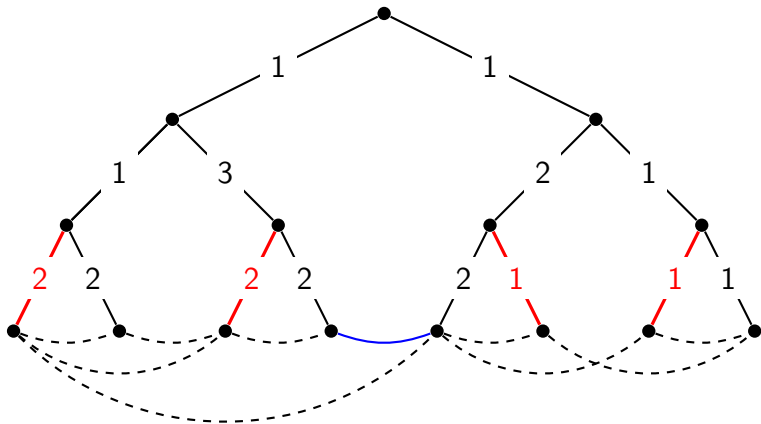


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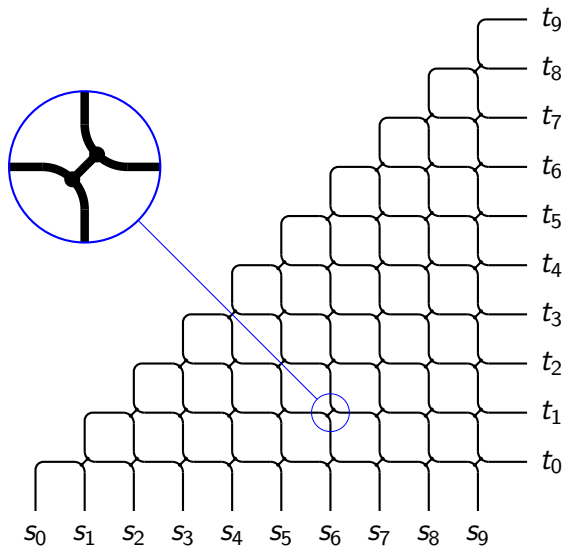
# MEDP on trees: results

- APX-hard and
- 2-approximation, no weight, (Garg, Vazirani, Yannakakis, 1997)
- 4-approximation with weight (Chekuri, Mydlarz, Shepherd, 2003).

Both algorithms have a bottom-up approach.

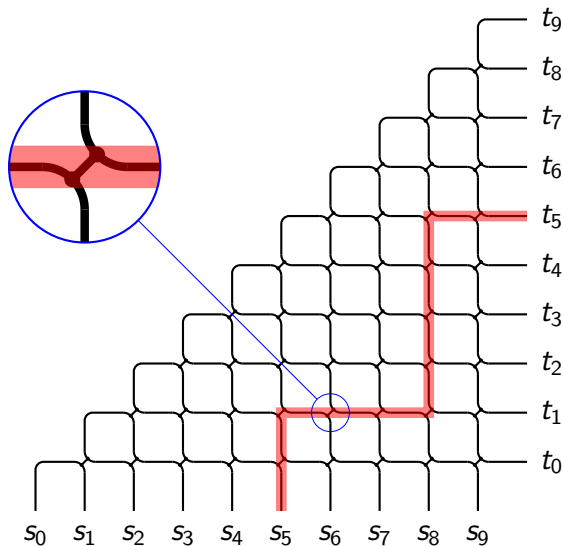
# Planar graphs

A bad example ( $\sqrt{n}$  integrality gap):



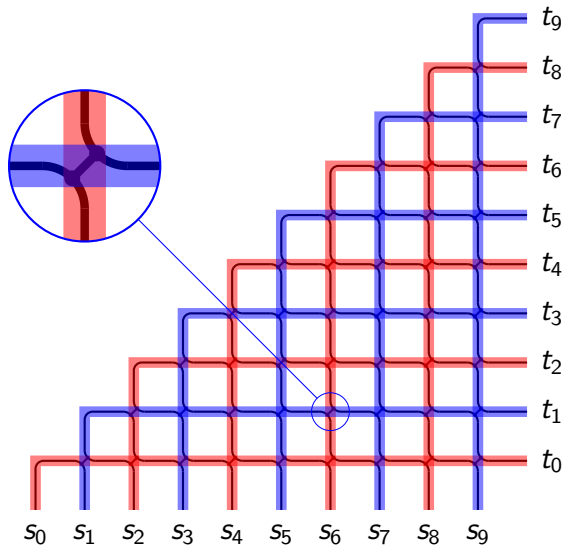
# Planar graphs

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# Planar graphs

A bad example ( $\sqrt{n}$  integrality gap):



# Congestion

In the previous example, multiplying the capacities by 2 leads to an integral solution matching the fractional optimum.

## Definition

Congestion: maximum ratio allowed between the number of paths taking an edge and its capacity.

# MEDP on planar graphs

Theorem (Chekuri, Khanna, Shepherd, 2006)

*$O(1)$ -approximation with congestion 4 in planar graphs.*

- Find a disc  $\mathcal{D}$  with properties:
  - capacity of  $\delta(\mathcal{D}) \ll$  flow routed inside  $\mathcal{D}$ ,
  - $\frac{1}{10}$  of the flows routed inside  $\mathcal{D}$  can be routed to the boundary of  $\mathcal{D}$ .
- Charge the flow crossing  $\delta(\mathcal{D})$  to  $\mathcal{D}$ .
- Remove  $\mathcal{D}$  and recurse.
- On  $\mathcal{D}$ , use the routing to the boundary, plus Okamura-Seymour theorem.

# Bounded treewidth graphs

- Trees = graphs of treewidth 1,
- Graphs of treewidth 2  $\subset$  planar graphs,
- $O(k \log k \log n)$ -approximation for graphs of treewidth  $k$  (Chekuri, Khanna, Shepherd 2006).
- Getting rid of the  $\log n$  factor?
- Extending planar result to minor-closed classes of graphs?



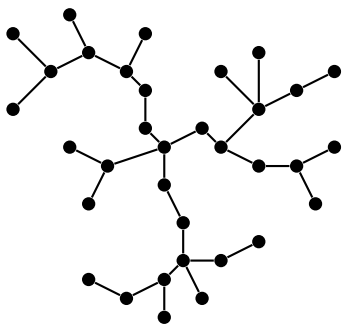
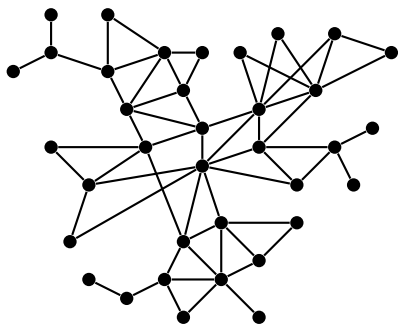
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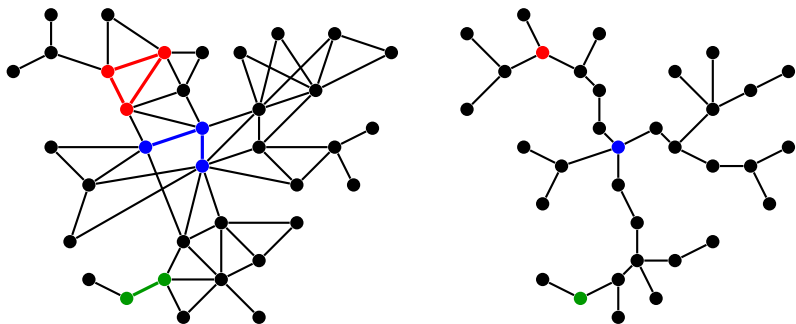
## Theorem

*For graphs of treewidth  $k$ ,  $\alpha_k$ -approximation with congestion  $\beta_k$ .*

# A graph with treewidth 2

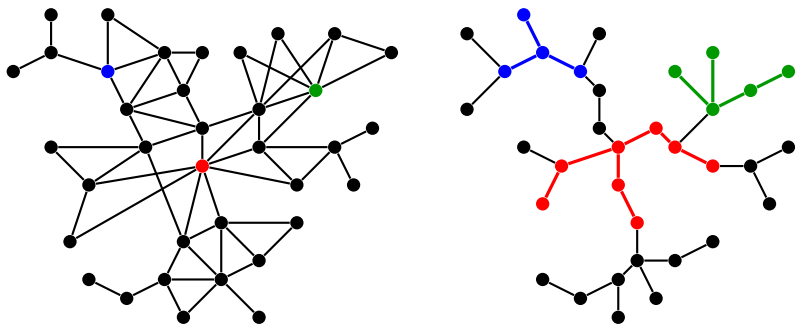


# Bags...



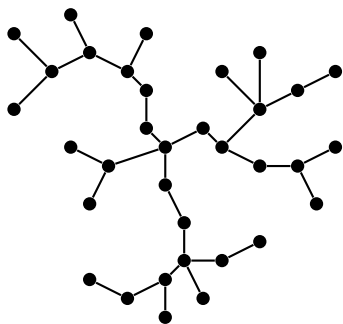
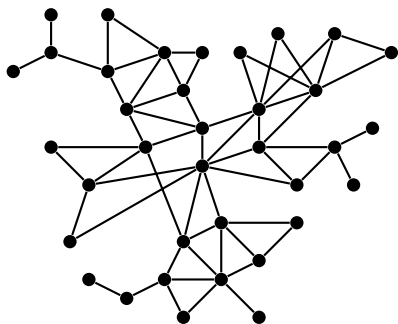
Every bag contains at most  $k + 1$  vertices.

## ... and vertices

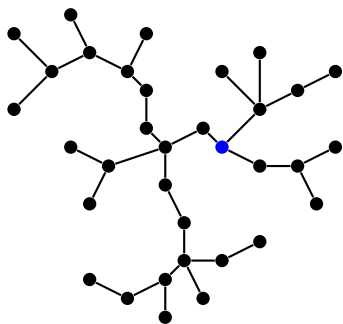
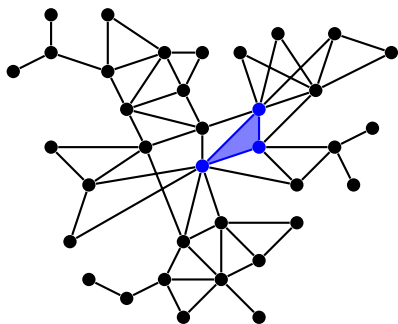


The bags containing a given vertex form a subtree.  
Two adjacent vertices have non-disjoint subtrees.

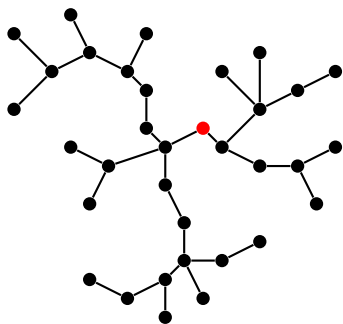
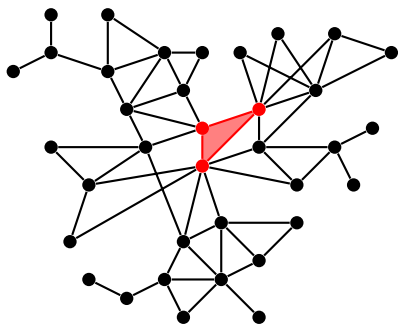
# Intersection of adjacent bags



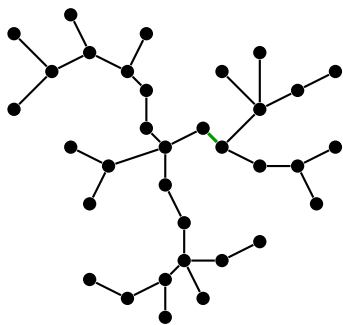
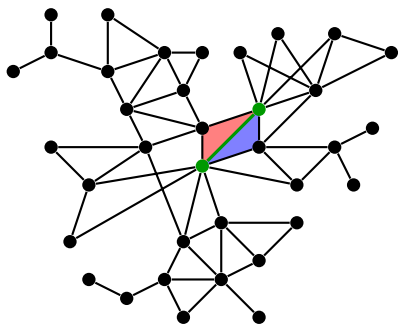
# Intersection of adjacent bags



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# Intersection of adjacent bags



Intersection of adjacent bags  $\implies$  cutset of size  $k$



# Proof of $O(1)$ -approx, $O(1)$ -congestion

Let  $x$  be a fractional optimum solution.

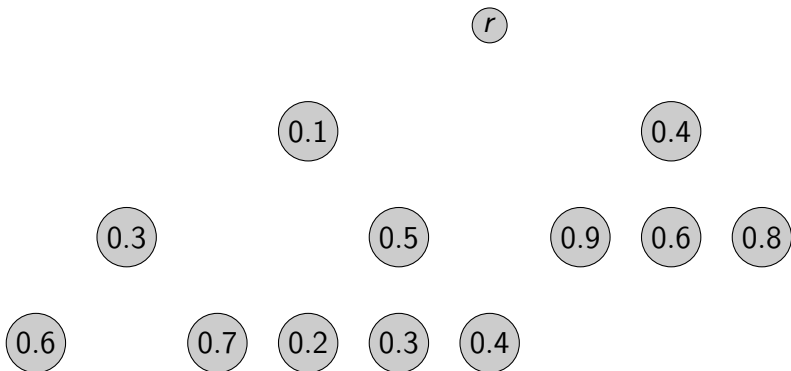
## Definition

*Marginal flow* at  $v$ : value of the flow paths in  $x$  having extremity  $v$ .

Main ideas:

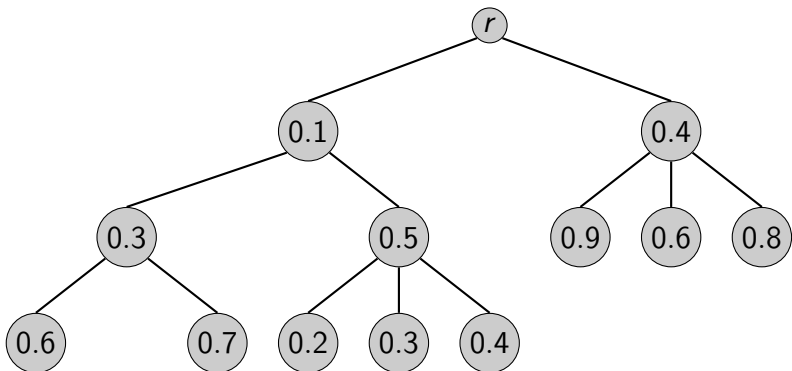
- Bottom-up approach,
- Cutting along a sparse cut and charging to the inside,
- Clustering.

# The clustering tool



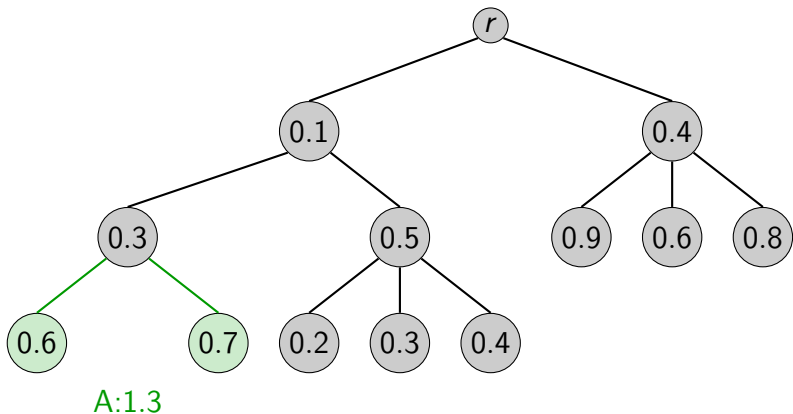
Suppose there is a flow to  $r$  with these marginal values.

# The clustering tool



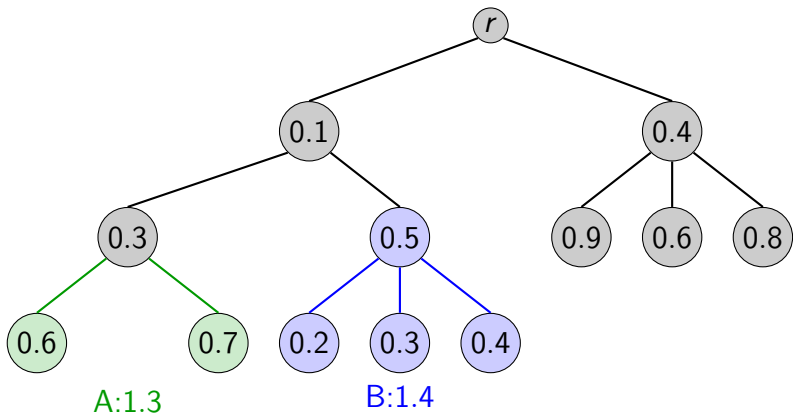
Take an arbitrary spanning tree.

# The clustering tool



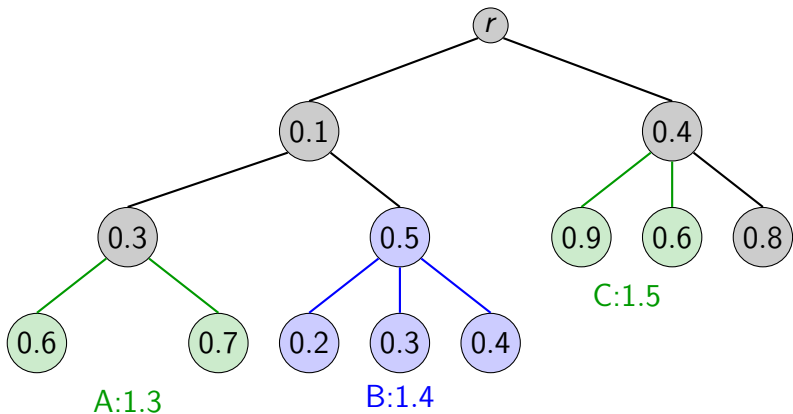
Find a lowest level node with marginal value  $\geq 1$ .  
Take just enough sons to get a value  $\geq 1$

# The clustering tool



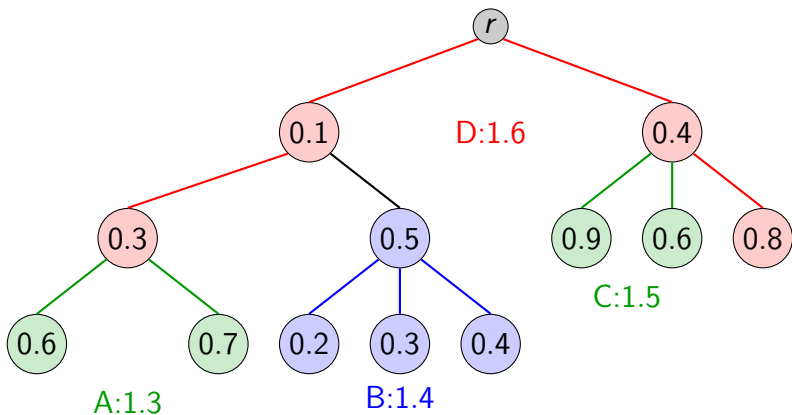
Find a lowest level node with marginal value  $\geq 1$ .  
Take just enough sons to get a value  $\geq 1$ , repeat.

# The clustering tool



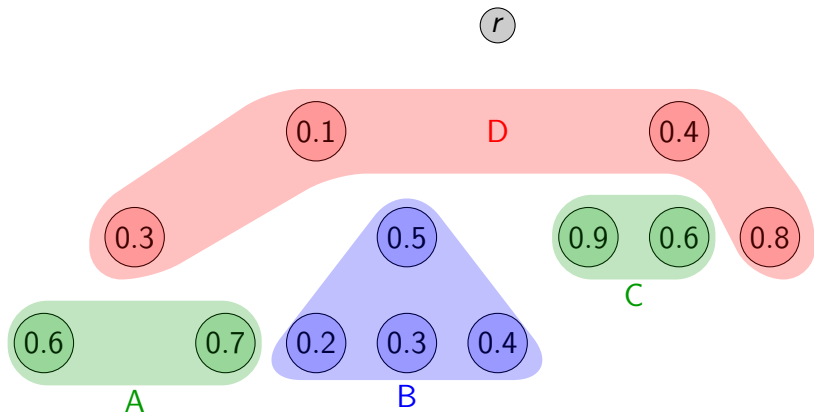
Again...

# The clustering tool



Again... until the remaining marginal value is  $< 3$ .

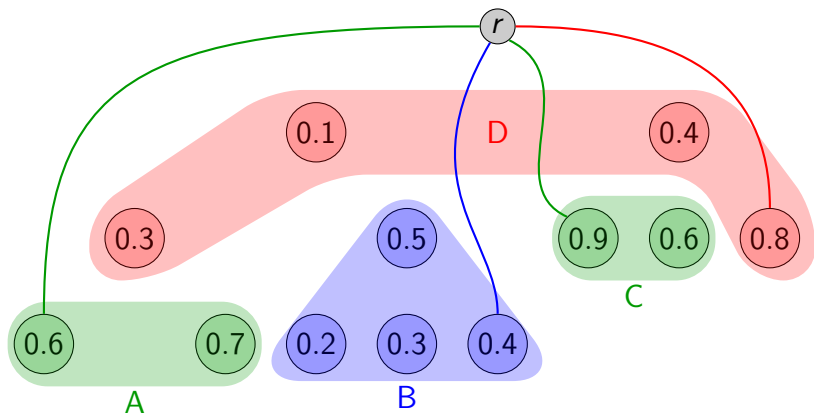
# The clustering tool



Clusters send a flow  $\geq 1$  to the root...

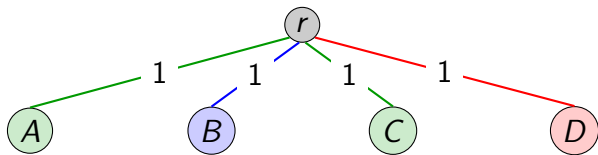


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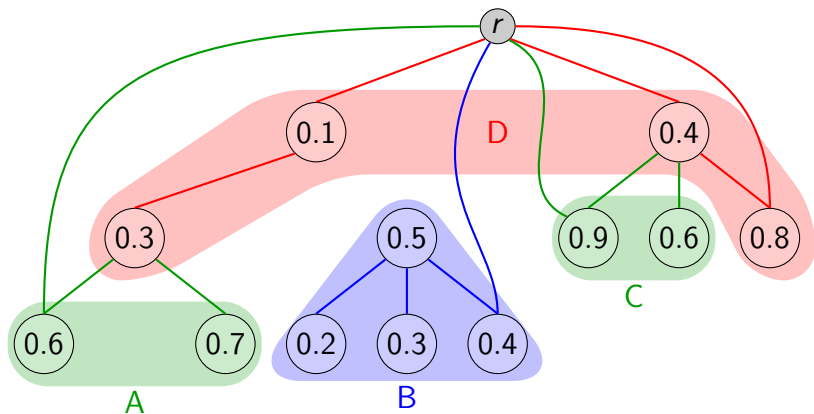
Clusters send a flow  $\geq 1$  to the root...  
... so we can find edge-disjoint paths.

# Contracting the clusters



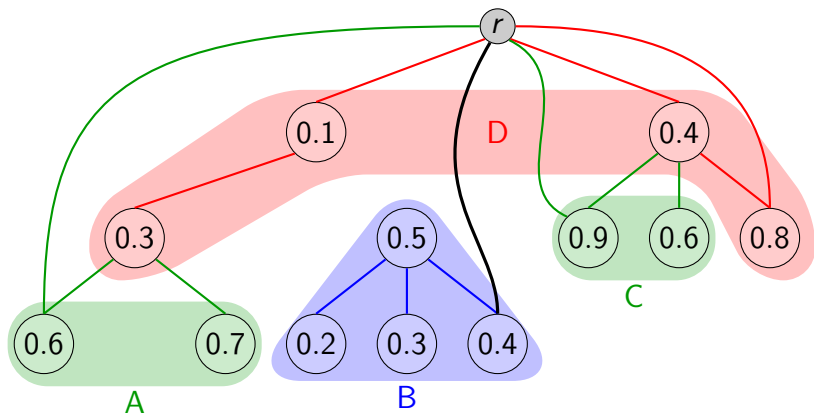
- Replace each cluster by a leaf.
- Also contract the demands.
- Then find an integral routing. . .
- . . . and uncontract the edge-disjoint paths.
- We get a 3-approximation with congestion 2.

# Uncontracting a path



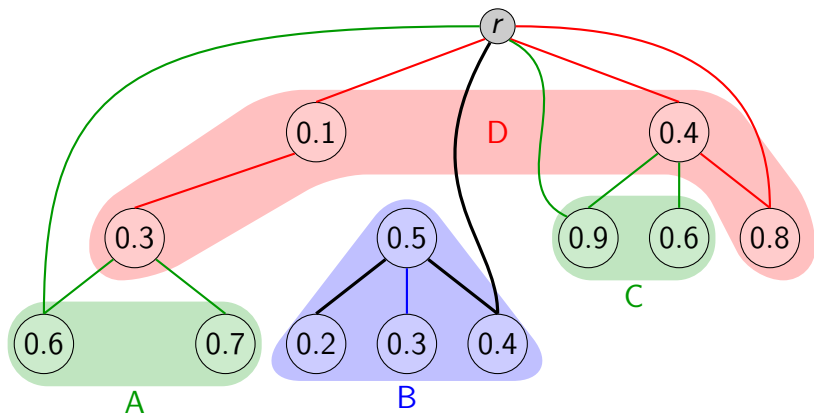
For a path satisfying a demand to the 0.2 blue node.

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# Clustering: what we get

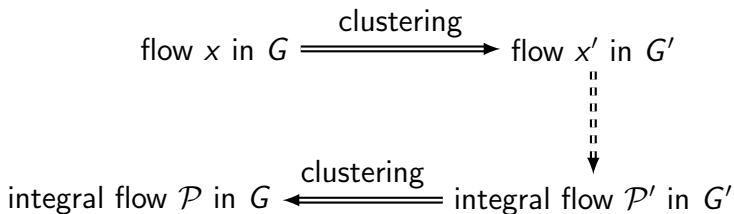
- If we can route a fraction of the marginal flow to  $U \subset V$ ,
- Then, move the demands to  $U$ ,
- Up to constant approximation, constant congestion:

flow  $x$  in  $G \xrightleftharpoons{\text{clustering}} \text{flow } x'$  in  $G'$

integral flow  $\mathcal{P}$  in  $G \xleftarrow{\text{clustering}} \text{integral flow } \mathcal{P}'$  in  $G'$

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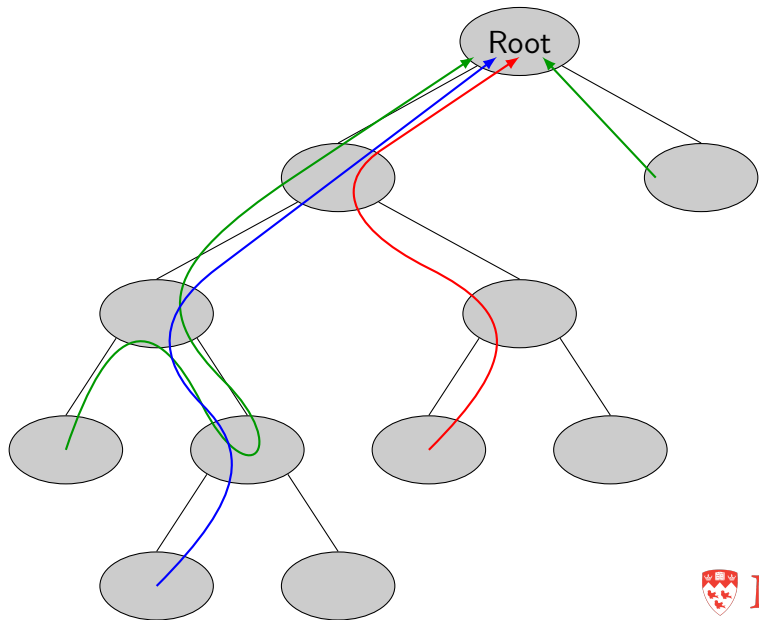
# The algorithm

Route the marginal values to the root of the decomposition tree.

- if success, then use clustering to conclude.
- if fail, cut along a sparse cut.



# Easy case: a flow to the root



## Easy case: solution

There is a flow  $f$  routing  $\frac{1}{10}$  of the marginal flow to the root.

- Make clusters using this flow  $f \implies$  fractional flow  $x'$ .
- The root has at most  $k + 1$  vertices, that are the terminals for  $x'$ .
- Select the pair  $(u, v)$  with maximum fractional flow  $x'$  between them.
- Find a packing of  $\lceil x'(u, v) \rceil$  disjoint  $(u, v)$ -paths, uncontract them.

## Easy case: solution

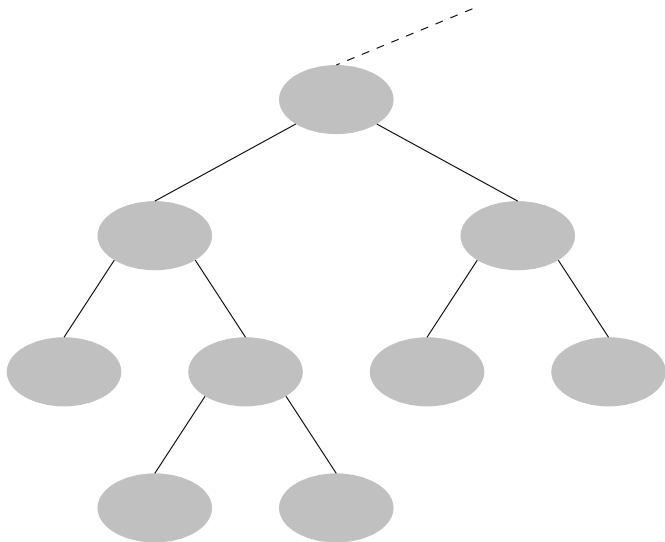
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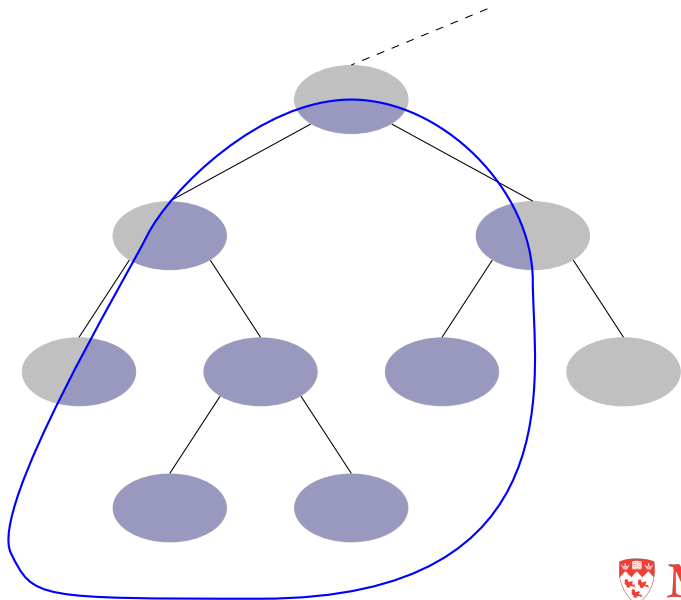
$\alpha k^2$ -approximation with  $\beta$  congestion.



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There is a sparse cut  $X$  separating terminals from the root.

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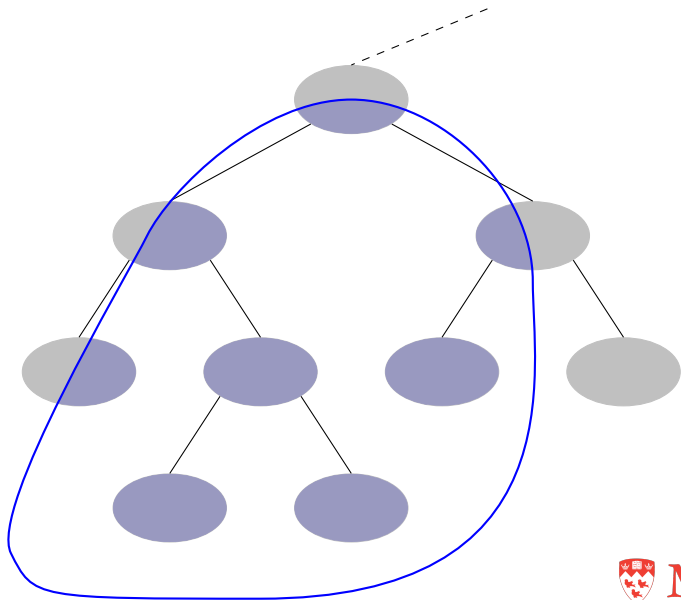
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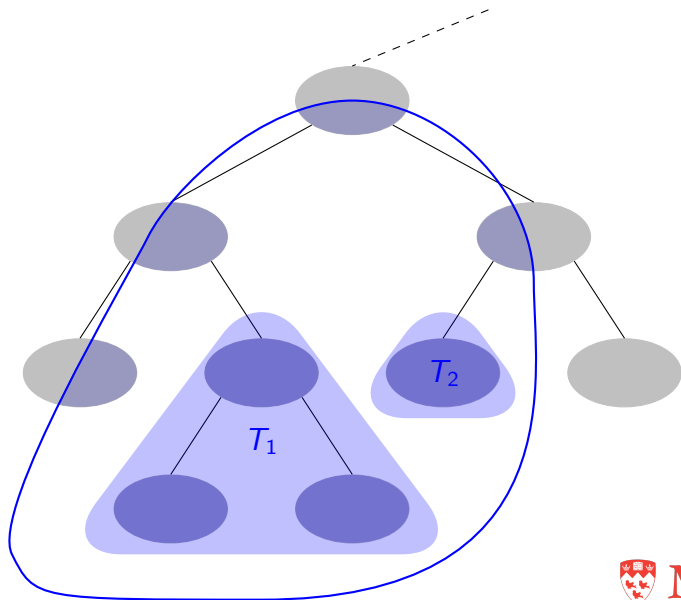
- Remove the flow through this cut.
- Charge the lost flow to the demands inside  $X$ .
- Recurse on  $G - X$  (smaller graph of treewidth  $k$ ).



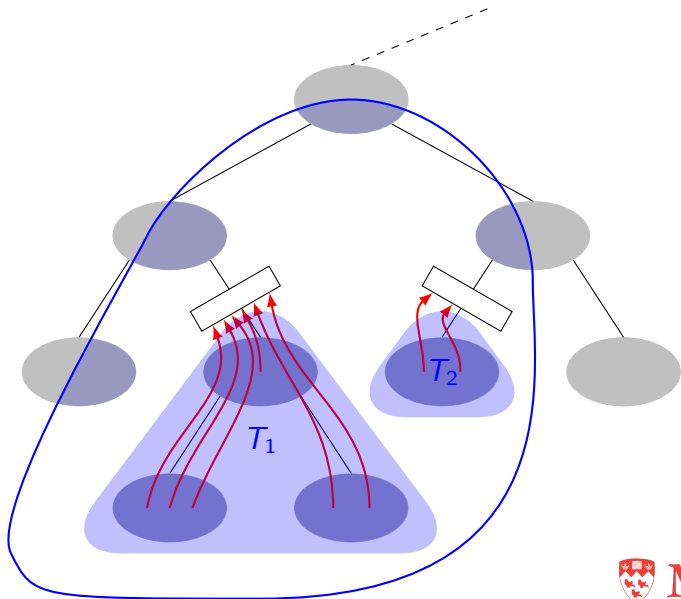
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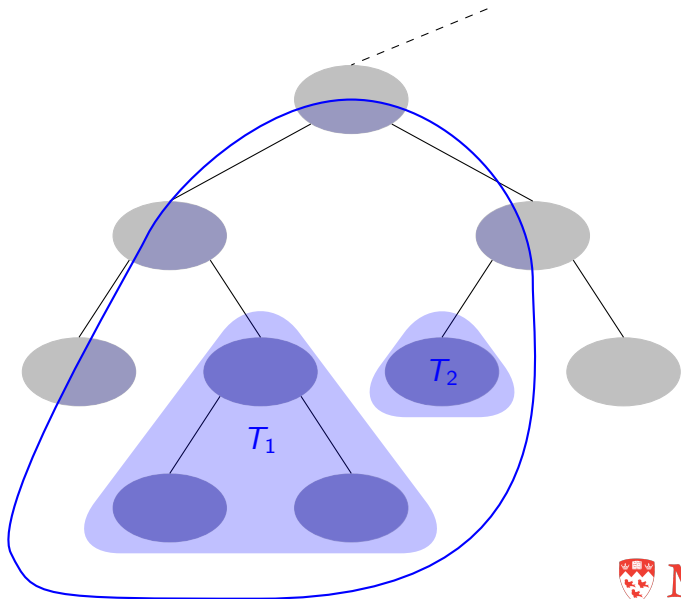


## Hard case: there is a sparse cut

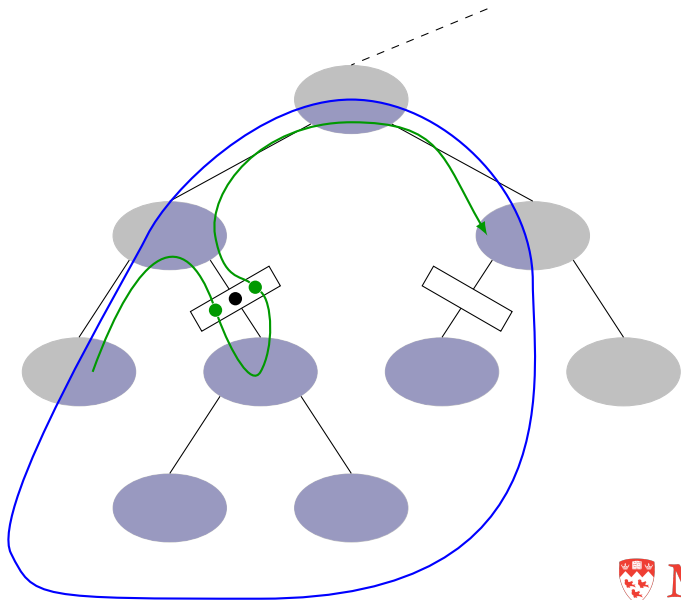
There is a sparse cut  $X$  separating terminals from the root.

- Remove the flow through this cut.
- Charge the lost flow to the demands inside  $X$ .
- Recurse on  $G - X$  (smaller graph of treewidth  $k$ ).
- Apply clustering on the complete subtrees of  $X$ .

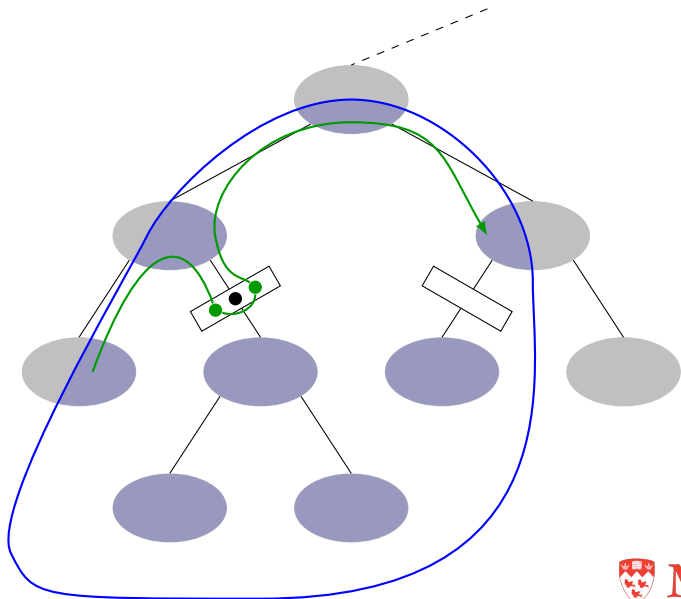
# Hard case: there is a sparse cut



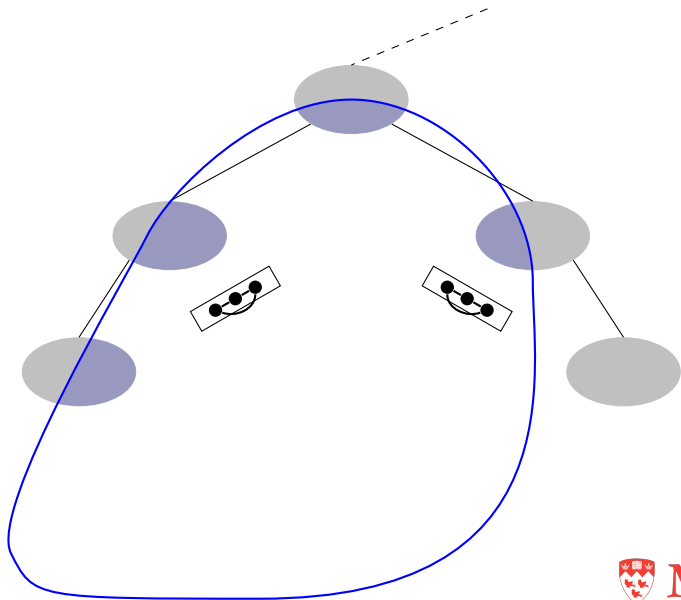
# Hard case: there is a sparse cut



# Hard case: there is a sparse cut

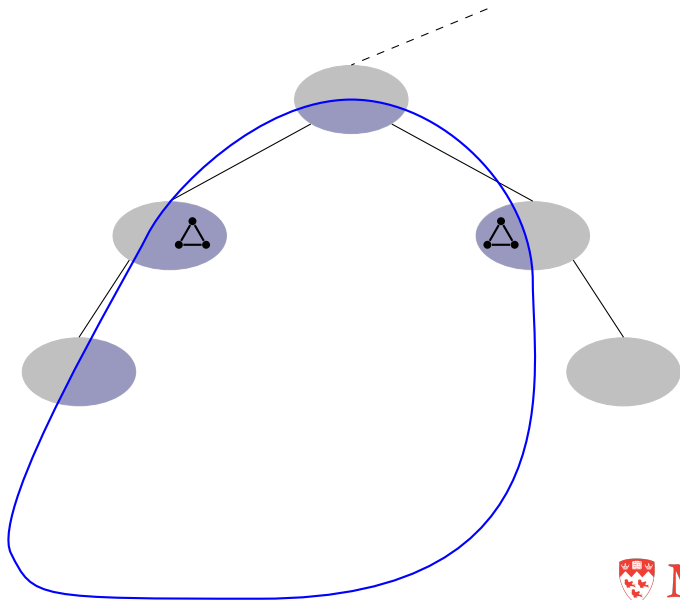


# Hard case: there is a sparse cut





# Hard case: there is a sparse cut

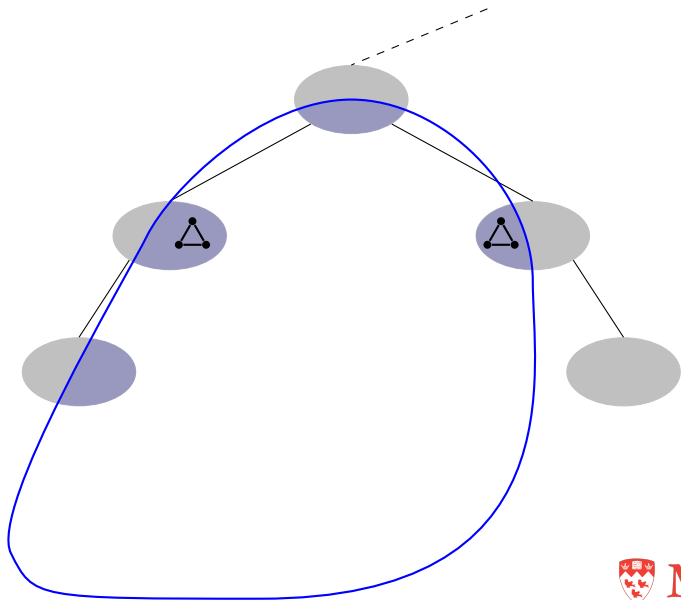


## Hard case: there is a sparse cut

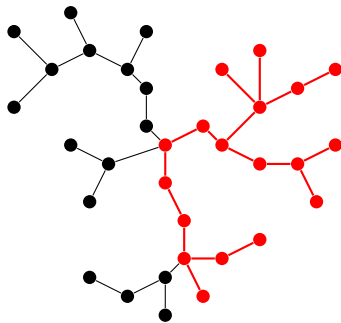
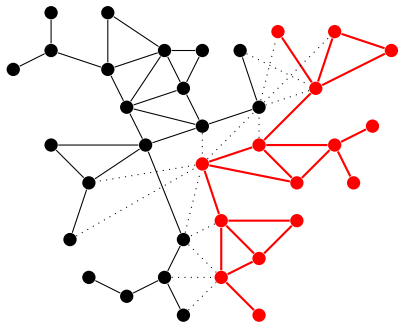
There is a sparse cut  $X$  separating terminals from the root.

- Remove the flow through this cut.
- Charge the lost flow to the demands inside  $X$ .
- Recurse on  $G - X$  (smaller graph of treewidth  $k$ ).
- Apply clustering on the complete subtrees of  $X$ .
- Contract the complete subtrees into cliques (congestion  $k^2$ ).

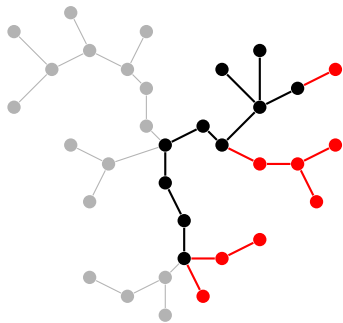
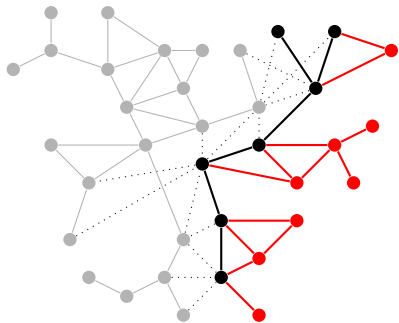
# Hard case: there is a sparse cut



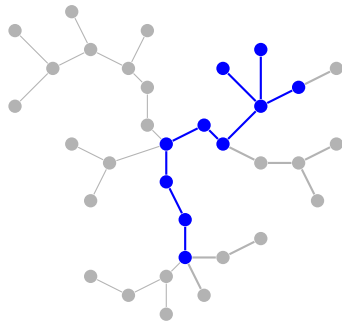
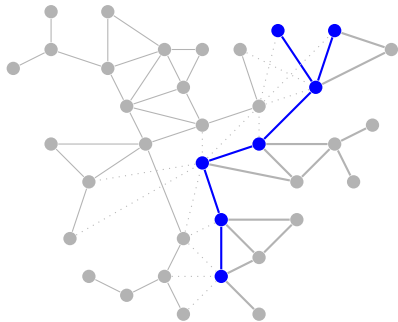
# Hard case in action



# Hard case in action



# Hard case in action



## Hard case: there is a sparse cut

There is a sparse cut  $X$  separating terminals from the root.

- Remove the flow through this cut.
- Charge the lost flow to the demands inside  $X$ .
- Recurse on  $G - X$  (smaller graph of treewidth  $k$ ).
- Apply clustering on the complete subtrees of  $X$ .
- Contract the complete subtrees into cliques (congestion  $k^2$ ).
- Apply induction on the contracted graph (treewidth  $k - 1$ ).

# What's next?

- weighted version,
- better bounds for congestion and approximation (exponential in the treewidth now),
- extend it to minor-closed classes of graphs.



# The end

Thank you!