1. The Little Grothendieck Inequality. We prove the little Grothendieck inequality: For every positive semidefinite matrix A the following inequality holds:

$$
\max_{x_i \in \{\pm 1\}} \sum_{i,j} a_{ij} x_i x_j \ge \frac{2}{\pi} \max_{\|v_i\|_2 = 1} \sum_{i,j} a_{ij} \langle v_i, v_j \rangle.
$$

Consider the set of unit vectors v_i that maximizes the right hand side. Pick a random Gaussian vector g, and let $x_i = \text{sgn}(\langle v_i, g \rangle)$. We want to show that

$$
\mathbf{E}\left[\sum_{i,j} a_{ij} x_i x_j\right] \ge \frac{2}{\pi} \sum_{i,j} a_{ij} \langle v_i, v_j \rangle. \tag{1}
$$

(a) Prove that

$$
\mathbf{E}\big[\sum_{i,j}a_{ij}\langle g,v_i\rangle\cdot\langle g,v_j\rangle\big]=\sum_{i,j}a_{ij}\langle v_i,v_j\rangle.
$$

- (b) Compute $\mathbf{E}[[g_1]]$, where g_1 is a (one dimensional) Gaussian random variable with mean 0 and standard deviation 1 i.e. $g_1 \sim \mathcal{N}(0, 1)$.
- (c) Show that for all unit vectors u and v :

$$
\mathbf{E}\big[\text{sgn}(\langle u, g \rangle) \cdot \langle v, g \rangle\big]\big] = \sqrt{\frac{2}{\pi}} \, \langle u, v \rangle.
$$

(Note that the left hand side is not symmetric with respect to u and v .)

(d) Prove that for every λ ,

$$
\mathbf{E}\big[\sum_{i,j}a_{ij}(\langle v_i,g\rangle-\lambda\operatorname{sgn}(\langle v_i,g\rangle))\cdot(\langle v_j,g\rangle-\lambda\operatorname{sgn}(\langle v_j,g\rangle))\big]\geq 0.
$$

- (e) Using parts (a) , (c) , and (d) prove (1) .
- 2. **Isometric Embeddings of** ℓ_2 . We show that every *n*-point subset of ℓ_2 isometrically embeds into ℓ_1 . To this end, we define an L_1 norm on functions from \mathbb{R}^n to \mathbb{R} . We let

$$
||f||_{L_1} = \mathbf{E}[|f(g)|],
$$

where g is an *n*-dimensional Gaussian vector. Note that the expectation on the right hand side may be undefined. The distance between two functions f_1 and f_2 equals

$$
||f_1 - f_2||_{L_1} = \mathbf{E}[|f_1(g) - f_2(g)|].
$$

(a) Show that the L_1 norm on functions satisfies the triangle inequality. That is,

$$
||f_1 - f_3||_{L_1} \le ||f_1 - f_2||_{L_1} + ||f_2 - f_3||_{L_1}
$$

for all functions f_1 , f_2 and f_3 assuming that the norms above are defined.

(b) Let $V \subset \mathbb{R}^n$ be an *n*-point subset of *n*-dimensional Euclidean space. Construct a map $v \mapsto f_v$ from V to the space of functions such that for all $u, v \in V$:

$$
||f_u - f_v||_{L_1} = ||u - v||_2.
$$

Hint: Compute $||f_u - f_v||_{L_1}$ for $f_v(x) = \langle x, v \rangle$ (here $x \in \mathbb{R}^n$).

(c) Now we embed functions f_v , constructed in the previous part, into ℓ_1 . For every ordering of vertices π (i.e., a one-to-one map from $\{1, \ldots, n\}$ to V) define a set \mathcal{E}_{π} as follows:

$$
\mathcal{E}_{\pi} = \{ x : f_{\pi(i)}(x) \le f_{\pi(i+1)}(x) \text{ for all } i \}.
$$

Define a map φ from the set of functions f_v to an n! dimensional space as follows:

$$
\varphi_{\pi}(f_v) = \mathbf{E}[f_v(g) \cdot \mathbf{1}(g \in \mathcal{E}_{\pi})],
$$

here $\varphi_{\pi}(f_v)$ is the π coordinate of $\varphi(f_v)$; $\mathbf{1}(g \in \mathcal{E}_{\pi})$ is the indicator of the event $\{g \in \mathcal{E}_{\pi}\}.$ Prove that

$$
\|\varphi(f_u) - \varphi(f_v)\|_1 = \|f_u - f_v\|_{L_1}.
$$

- (d) Use all parts above to show than every n-point subset of Euclidean space embeds isometrically into ℓ_1 .
- 3. (From the book of Williamson and Shmoys.) In the maximum k-cut problem, we are given an undirected graph $G = (V, E)$, and non-negative weights $w_{ij} > 0$ for all $(i, j) \in E$. The goal is to partition the vertex set V into k parts V_1, \ldots, V_k so as to maximize the weight of all edges whose endpoints are in different parts. Give a $(k-1)/k$ -approximation algorithm for the MAX k-CUT problem.
- 4. Initialization of Interior Point Methods. Given an original linear program as follows. Here A is an integral $m \times n$ matrix which has full row rank and b and c are integral vectors

$$
\min_{c} c^{T} x
$$

s.t.

$$
Ax = b
$$

$$
x \ge 0
$$

Figure 1: Original Linear Program

of length m and n . Let

 $L = \log$ (largest absolute value of the determinant of a square submatrix of $A + 1$) + $+\log(1+\max_j|c_j|)+\log(1+\max_i|b_i|)+3.$

Let $\alpha = 2^{4L}$ and $\lambda = 2^{2L}$. Let $K_b = \alpha \lambda (n+1) - \lambda c^T e$ where e is all ones vector and $K_c = \alpha \lambda$. Now consider the augmented linear program.

```
\min c^T x + K_c x_{n+2}s.t.
Ax + (b - \lambda Ae)x_{n+2} = b(\alpha e - c)^T x + \alpha x_{n+1} = K_bx > 0
```


(a) Construct the dual for the the modified linear program where we have the dual variables y_i for $i = 1, \ldots, m$ for the original m constraints and y_{m+1} for the new constraint added in the following form where $\bar{\hat{b}}$, \hat{A} , \hat{c} need to be defined. Moreover, let $s \in \mathbb{R}^{n+2}$ denote the slack variables.

$$
\max \hat{b}^T y
$$

s.t.

$$
\hat{A}y + s = \hat{c}
$$

$$
s \ge 0
$$

Figure 3: Modified Linear Program

- (b) Let $x^* = (\lambda, \ldots, \lambda, 1)^T \in \mathbb{R}^{n+2}$, $y^* = (0, \ldots, 0, -1)^T \in \mathbb{R}^{m+1}$ and let slack variables $s^* = (\alpha, \ldots, \alpha, \alpha \lambda) \in \mathbb{R}^{n+2}$. Show x^* is feasible for modified primal LP and y^* is feasible for its dual and s^* are the corresponding slack variables for the dual constraints, i.e., $\hat{A}y^* + s^* = \hat{c}$. Also verify that $x_i^* s_i^* = \alpha \lambda$ for each i and therefore they are on the central path with $\mu = \alpha \lambda$.
- (c) Since modified primal and modified dual have feasible solutions, they will have optimal solutions. Let $\bar{x}, \bar{y}, \bar{s}$ denote the optimal primal and dual solutions. Show the following.
	- i. If $\bar{x}_{n+2} = 0$ and $\bar{s}_{n+1} = 0$, then $x' = (\bar{x}_1, \ldots, \bar{x}_n)$ is optimal for original primal and $y' = (\bar{y}_1, \ldots, \bar{y}_m)$ is dual optimal with slack variables $s' = (\bar{s}_1, \ldots, \bar{s}_n)$.
	- ii. If $\bar{x}_{n+2} \neq 0$ and $\bar{s}_{n+1} = 0$, then original primal is infeasible.
	- iii. If $\bar{s}_{n+1} \neq 0$ and $\bar{x}_{n+2} = 0$, then original primal is unbounded.