

Recap

- Before break
 - Dynamic games with incomplete information
 - Signaling
 - Pooling and Separating equilibria
 - Principal-Agent problems intro
 - Principal has desired outcome but cannot necessarily control the agent's actions directly
- Today
 - PA: P does not know effort level

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Moral Hazard PA Problem

- In the final stage of the game, the agent decides his action (effort)
 - $\max_a \{ \sum_{j=1}^m P_{ij} U(w_j) - e(a_i) \}$
- In the next to last stage, the agent decides whether to accept the contract, and will if
 - $\sum_{j=1}^m P_{ij} U(w_j) - e(a_i) \geq \underline{U}$
- In the first stage, the principal designs the contract, anticipating the agent's behavior:

$$\max \sum_{j=1}^m P_{ij} (x_j - w_j)$$

$$\text{s.t. } \sum_{j=1}^m P_{ij} U(w_j) - e(a_i) \geq \underline{U}$$

$$\sum_{j=1}^m P_{ij} U(w_j) - e(a_i) \geq \sum_{j=1}^m P_{kj} U(w_j) - e(a_k) \quad \forall k \neq i$$

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Two actions and two outcomes

- Suppose the agent has two possible actions, a and b , and there are two possible outcomes, x_1 and x_2 .
- Suppose that action b is preferred by the principal

For action b :

$$\max \sum_{j=1}^2 P_{bj}(x_j - w_j)$$

$$P_{b1}U(w_1) + P_{b2}U(w_2) - e(b) \geq \underline{U} \dots\dots\dots \mathbf{m}$$

$$P_{b1}U(w_1) + P_{b2}U(w_2) - e(b) \geq$$

$$P_{a1}U(w_1) + P_{a2}U(w_2) - e(a) \dots \mathbf{l}$$

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Two actions and two outcomes

Incentive compatibility constraint :

$$P_{b1}U(w_1) + P_{b2}U(w_2) - e(b) \geq P_{a1}U(w_1) + P_{a2}U(w_2) - e(a)$$

When is the agent indifferent between a and b ?

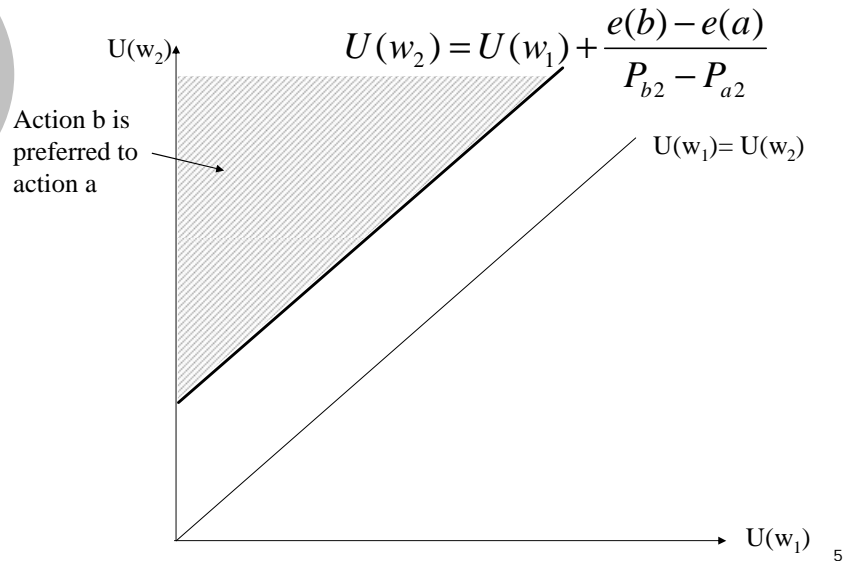
$$P_{b1}U(w_1) + P_{b2}U(w_2) - e(b) = P_{a1}U(w_1) + P_{a2}U(w_2) - e(a)$$

$$U(w_2) = \frac{P_{a1} - P_{b1}}{P_{b2} - P_{a2}} U(w_1) + \frac{e(b) - e(a)}{P_{b2} - P_{a2}} = U(w_1) + \frac{e(b) - e(a)}{P_{b2} - P_{a2}}$$

since $P_{a1} + P_{a2} = P_{b1} + P_{b2} = 1$

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Two actions and two outcomes



Two actions and two outcomes

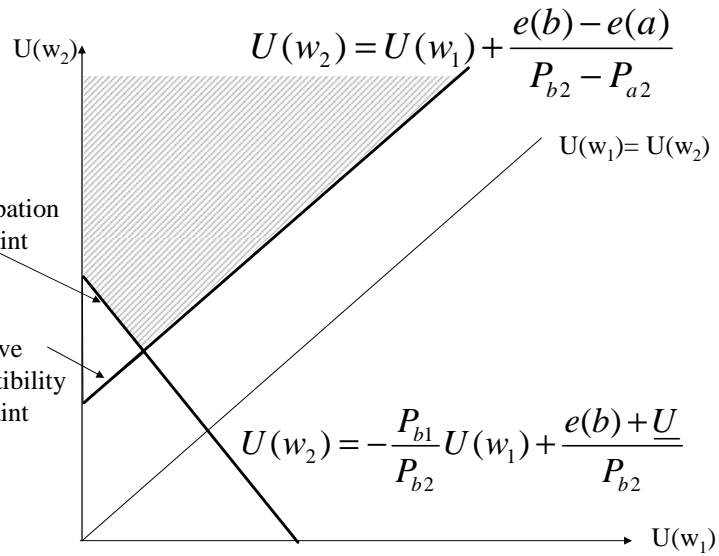
Participation constraints :

$$\text{Action } b: P_{b1}U(w_1) + P_{b2}U(w_2) - e(b) \geq \underline{U}$$

$$\rightarrow \rightarrow U(w_2) \geq -\frac{P_{b1}}{P_{b2}}U(w_1) + \frac{e(b) + \underline{U}}{P_{b2}}$$

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Two actions and two outcomes



Two actions and two outcomes

○ Principal's objective function

For action b :

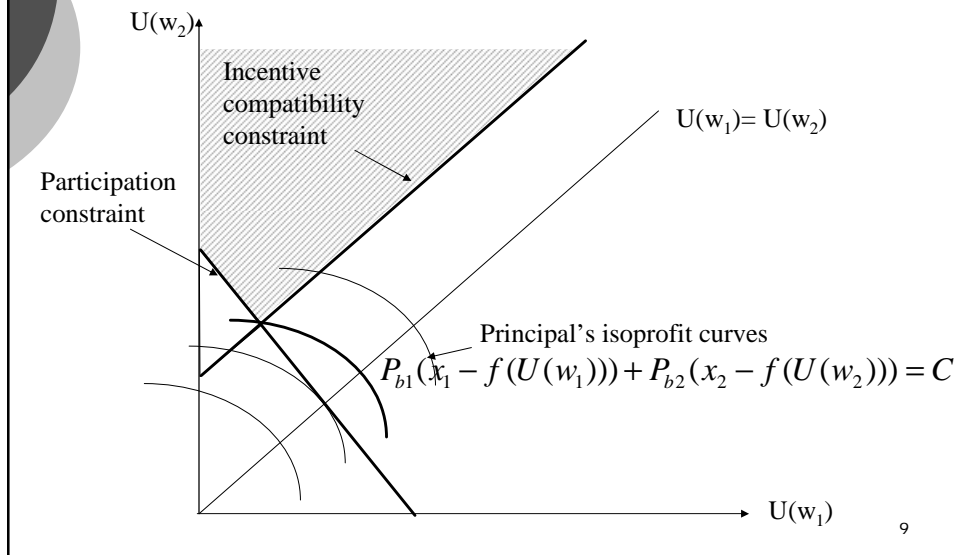
$$\max P_{b1}(x_1 - w_1) + P_{b2}(x_2 - w_2)$$

Let f be the inverse of U : $f(U(w_j)) = w_j$

$$\max P_{b1}(x_1 - f(U(w_1))) + P_{b2}(x_2 - f(U(w_2)))$$

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Two actions and two outcomes



Two actions and two outcomes

$$\max P_{b1}(x_1 - f(U(w_1))) + P_{b2}(x_2 - f(U(w_2)))$$

Slope of the objective function :

$$MRS = - \frac{P_{b1} f'(U(w_1))}{P_{b2} f'(U(w_2))}$$

Two actions and two outcomes

If $U(w_1) = U(w_2)$ (45° line)

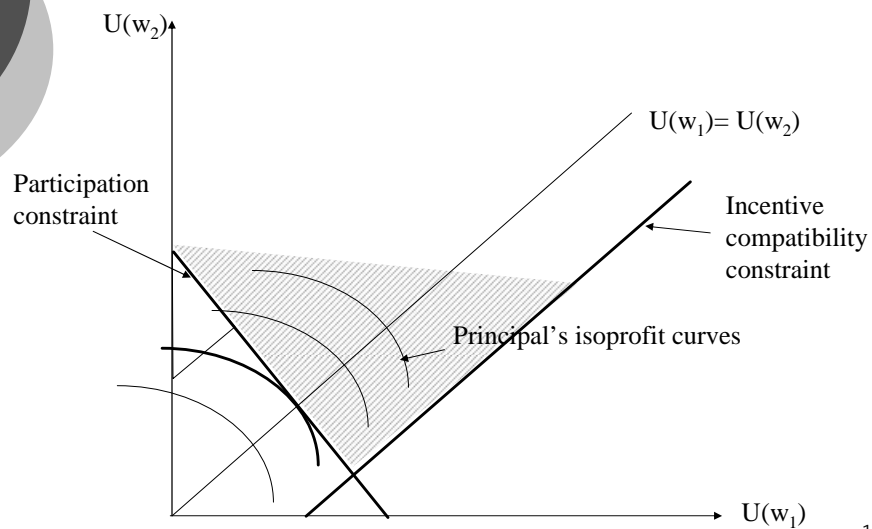
$$MRS = -\frac{P_{b1}f'(U(w_1))}{P_{b2}f'(U(w_2))} = -\frac{P_{b1}}{P_{b2}}$$

Same as the slope of the participation constraint!

The principal's isoprofit curve is tangent to the agent's participation constraint along the 45° line.

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Two actions and two outcomes



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Two actions and two outcomes

$$\frac{1}{U'(w_j)} = \mathbf{m} + \mathbf{I} \left(1 - \frac{P_{aj}}{P_{bj}} \right) \quad \frac{P_{aj}}{P_{bj}} : \text{likelihood ratio}$$

If the incentive constraint is not binding :

$$\mathbf{I} = 0, \quad U'(w_j) = 1/\mathbf{m} \text{ and } w_j = w.$$

Substituting into the incentive constraint

(the agent prefers action b over action a):

$$\sum_{j=1}^n P_{bj} U(w) - e(b) \geq \sum_{j=1}^n P_{aj} U(w) - e(a) \rightarrow e(a) \geq e(b)$$

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Two actions and two outcomes

$$\frac{1}{U'(w_j)} = \mathbf{m} + \mathbf{I} \left(1 - \frac{P_{aj}}{P_{bj}} \right) \quad \frac{P_{aj}}{P_{bj}} : \text{likelihood ratio}$$

If the incentive constraint is binding :

$$\mathbf{I} > 0, \text{ and } U'(w_j) \text{ depends on the likelihood ratio (LR).}$$

The optimal incentive scheme is a linear function of LR.

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Sensitivity analysis: Changes in the agent's costs

- What is the impact of the agent's costs on the outcome?

$$\begin{aligned} \max L(w, \mathbf{I}, \mathbf{m}) = & P_{b_1}(x_1 - w_1) + P_{b_2}(x_2 - w_2) + \\ & \mathbf{m}(P_{b_1}U(w_1) + P_{b_2}U(w_2) - e(b) - \underline{U}) + \\ & \mathbf{I}(P_{b_1}U(w_1) + P_{b_2}U(w_2) - e(b) - P_{a_1}U(w_1) - P_{a_2}U(w_2) + e(a)) \end{aligned}$$

$$\frac{\partial L(w, \mathbf{I}, \mathbf{m})}{\partial e(b)} = -(\mathbf{m} + \mathbf{I}) \quad \frac{\partial L(w, \mathbf{I}, \mathbf{m})}{\partial e(a)} = \mathbf{I}$$

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Sensitivity analysis: Changes in the agent's costs

- What is the impact of the agent's costs on the outcome?

$$\frac{\partial L(w, \mathbf{I}, \mathbf{m})}{\partial e(b)} = -(\mathbf{m} + \mathbf{I}) \quad \frac{\partial L(w, \mathbf{I}, \mathbf{m})}{\partial e(a)} = \mathbf{I}$$

- "Carrot": Decrease the cost of the desired action, b
- "Stick": Increase the cost of the undesired action, a
- Carrot vs. stick, which one is better?

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Sensitivity analysis: Changes in probability distribution

- What is the impact on the principal's utility of a change in probability distribution dP_{aj} ?

$$\frac{\partial L(w, \mathbf{l}, \mathbf{m})}{\partial P_{aj}} = -\mathbf{l} \sum_{j=1}^2 U(w_j) dP_{aj}$$

- When the IC constraint is binding the interests of the principal and agent are opposed